

# Brownian Motion and Stochastic Calculus

## Exercise sheet 1

Please hand in your solutions during exercise class or in your assistant's box in HG E65 no later than March 3rd

**Exercise 1.1** Let  $W$  be a Brownian motion on  $[0, 1]$  and define the *Brownian bridge*  $X = (X_t)_{0 \leq t \leq 1}$  by  $X_t = W_t - tW_1$ .

- Show that  $X$  is a Gaussian process and calculate its mean and covariance functions. Sketch a typical path of  $X$ .
- Show that  $X$  does **not** have independent increments.

**Exercise 1.2** Let  $(\Omega, \mathcal{F}, P)$  be a probability space and assume that  $X = (X_t)_{t \geq 0}$ ,  $Y = (Y_t)_{t \geq 0}$  are two stochastic processes on  $(\Omega, \mathcal{F}, P)$ . Two processes  $Z$  and  $Z'$  on  $(\Omega, \mathcal{F}, P)$  are said to be *modifications* of each other if  $P(Z_t = Z'_t) = 1 \forall t \geq 0$ , while  $Z$  and  $Z'$  are *indistinguishable* if  $P(Z_t = Z'_t \forall t \geq 0) = 1$ .

- Assume that  $X$  and  $Y$  are both right-continuous or both left-continuous. Show that the processes are modifications of each other if and only if they are indistinguishable.

**Remark:** A stochastic process is said to *have the path property*  $\mathcal{P}$  ( $\mathcal{P}$  can be continuity, right-continuity, differentiability, ...) if the property  $\mathcal{P}$  holds for  $P$ -almost every path.

- Give an example showing that one of the implications of part **a)** does not hold for general  $X$ ,  $Y$ .

**Exercise 1.3** Let  $X = (X_t)_{t \geq 0}$  be a stochastic process defined on a filtered probability space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), P)$ . The aim of this exercise is to show the following chain of implications:

$X$  optional  $\Rightarrow X$  progressively measurable  $\Rightarrow X$  product-measurable and adapted.

- Show that every progressively measurable process is product-measurable and adapted.
- Assume that  $X$  is adapted and *every* path of  $X$  is right-continuous. Show that  $X$  is progressively measurable.

*Remark:* The same conclusion holds true if every path of  $X$  is left-continuous.

*Hint:* For fixed  $t \geq 0$ , consider an approximating sequence of processes  $Y^n$  on  $\Omega \times [0, t]$  given by  $Y_0^n = X_0$  and  $Y_u^n = \sum_{k=0}^{2^n-1} 1_{(tk2^{-n}, t(k+1)2^{-n}]}(u) X_{t(k+1)2^{-n}}$  for  $u \in (0, t]$ .

- Recall that the optional  $\sigma$ -field  $\mathcal{O}$  is generated by the class  $\overline{\mathcal{M}}$  of all adapted processes whose paths are all RCLL. Show that  $\mathcal{O}$  is also generated by the subclass  $\mathcal{M}$  of all *bounded* processes in  $\overline{\mathcal{M}}$ .
- Use the monotone class theorem to show that every optional process is progressively measurable.