

Remarks

(25)

$$(11) \quad f: X \longrightarrow \mathbb{R}^m$$

$$f(x) = (f_1(x), \dots, f_m(x))$$

f is differentiable at x_0



$f_i, 1 \leq i \leq m$, is differentiable at x_0

And then

$$df(x_0) = \begin{pmatrix} df_1(x_0) \\ \vdots \\ df_m(x_0) \end{pmatrix}$$

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(2) $\underbrace{m=1}$

$u: \mathbb{R}^n \longrightarrow \mathbb{R}$ "linear form"

is given by

$$u(x_1, \dots, x_n) = a_1 x_1 + \dots + a_n x_n$$

for some vector $(a_1, \dots, a_n) \in \mathbb{R}^n$.

One can also write

$$u(x) = a \cdot x$$

[where $x \cdot y = x_1 y_1 + \dots + x_n y_n$ is a scalar product].

Prop. (3.4.4)

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$f: \mathbb{R}^n \rightarrow \mathbb{R}$ differentiable
at x_0

(1) f is continuous at x_0

(2) f has partial derivatives at x_0 ,

and

$$\frac{\partial f}{\partial x_i}(x_0) = a_i$$

where

$$df(x_0) = a \cdot x$$

with $a = (a_1, \dots, a_n)$

Proof : (2) For $n = 2$ (28)

x, y as variables in \mathbb{R}^2

(x_0, y_0) $u =$ differential at (x_0, y_0)

Write $u(x, y) = ax + by$, a, b in \mathbb{R}

Compute $\frac{\partial f}{\partial x}$:

$$g(x) = f(x, y_0)$$

$$\frac{g(x) - g(x_0)}{x - x_0} = \frac{f(x, y_0) - f(x_0, y_0)}{x - x_0}$$

Write

$$f(x, y) = f(x_0, y_0) + a(x - x_0) + b(y - y_0) + E(x, y)$$

$a(x - x_0, y - y_0)$

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Then

$$\frac{f(x) - f(x_0)}{x - x_0} = \frac{a(x - x_0) + b(y_0 - y_0)}{x - x_0} + \frac{E(x, y_0)}{x - x_0}$$
$$= a + \frac{E(x, y_0)}{\|(x, y_0) - (x_0, y_0)\|}$$

f differentiable with $df(x_0, y_0) = \alpha$ (30)
means

$$\lim_{(x,y) \rightarrow (x_0, y_0)} \frac{E(x,y)}{\|(x,y) - (x_0, y_0)\|} = 0$$

So we find that

$$\lim_{x \rightarrow x_0} \frac{g(x) - g(x_0)}{x - x_0} = \alpha.$$

So $\frac{df}{dx}(x_0, y_0) = \alpha.$

Conclusion: to compute (31)

The differential, if is enough to compute partial derivatives.

Examples: (3, 4, 5)

(1) let $f(x) = y_0 + Ax$
 $(x \in \mathbb{R}^n)$
 \mathbb{R}^m

(affine-linear)
matrix with m rows, n columns

Then f is differentiable on \mathbb{R}^n

with $df(x_0) = u$ (32)

[where $u(x) = Ax$ for all x_0 [constant differential]]

Because:

$$y_0 + Ax = f(x) - f(x_0) - u(x - x_0) = 0$$

so $\lim_{x \rightarrow x_0} \frac{f(x) - f(x_0) - u(x - x_0)}{\|x - x_0\|} = 0$.

$$(2) \quad g(x, y) = \frac{xy}{\sqrt{x^2 + y^2}}, \quad g(0, 0) = 0 \quad (33)$$

$$\frac{\partial g}{\partial x} = 0, \quad \frac{\partial g}{\partial y} = 0$$

but is not differentiable

$$(3) \quad \underline{m=1}$$

if f is differentiable at x_0

$$\text{Then } dg(x_0)(x) = a \cdot x$$

where

$$a = \begin{pmatrix} \partial_{x_1} f(x_0) \\ \vdots \\ \partial_{x_n} f(x_0) \end{pmatrix} \stackrel{\text{def}}{=} \nabla f(x_0)$$

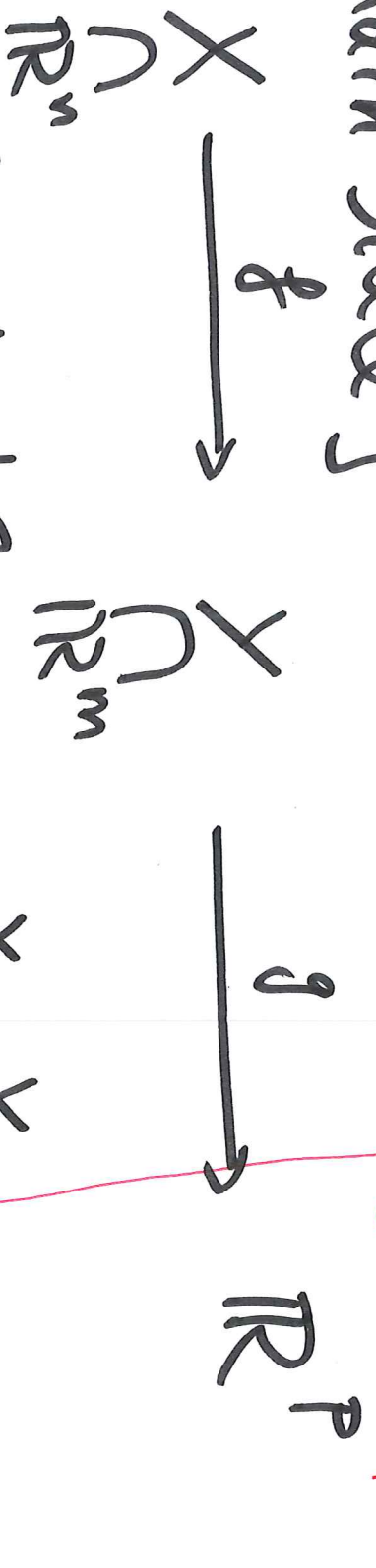
"gradient"
 $\in \mathbb{R}^n$

Nabla

Prop. [3.4.6, 3.4.7, 3.4.9] (34)

(1) If f, g are differentiable, so is $f+g$, and f/g (if $m=1$), f/g (if $m=1, g$ never zero)

(2) [Chain rule]



f, g differentiable on X, Y
 $\Rightarrow g \circ f$ is differentiable on X with $d(g \circ f)(x_0) = dg(f(x_0)) \circ df(x_0)$

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(3) If $f: X \rightarrow \mathbb{R}^m$ has partial derivatives on X and if all $\frac{\partial f_i}{\partial x_i}$ are continuous on X , then

f is differentiable on X and the matrix of $df(x_0)$ (w.r.t canonical bases of \mathbb{R}^n and \mathbb{R}^m) is the Jacobi matrix

$$J_f(x_0) = \left(\frac{\partial f_i}{\partial x_j} \right)_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$$

Examples -

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(1) Any polynomial in n variables is differentiable (any partial derivative is ~~not~~ a polynomial, so it is continuous).

$$(2) f(x) = f_1(x_1) \cdots f_n(x_n)$$

If f_i is C^1 (as function of one variable)

$$\text{Then } \frac{\partial f}{\partial x_i} = f_1(x_1) \cdots \underline{f_i'(x_i)} \cdots f_n(x_n)$$

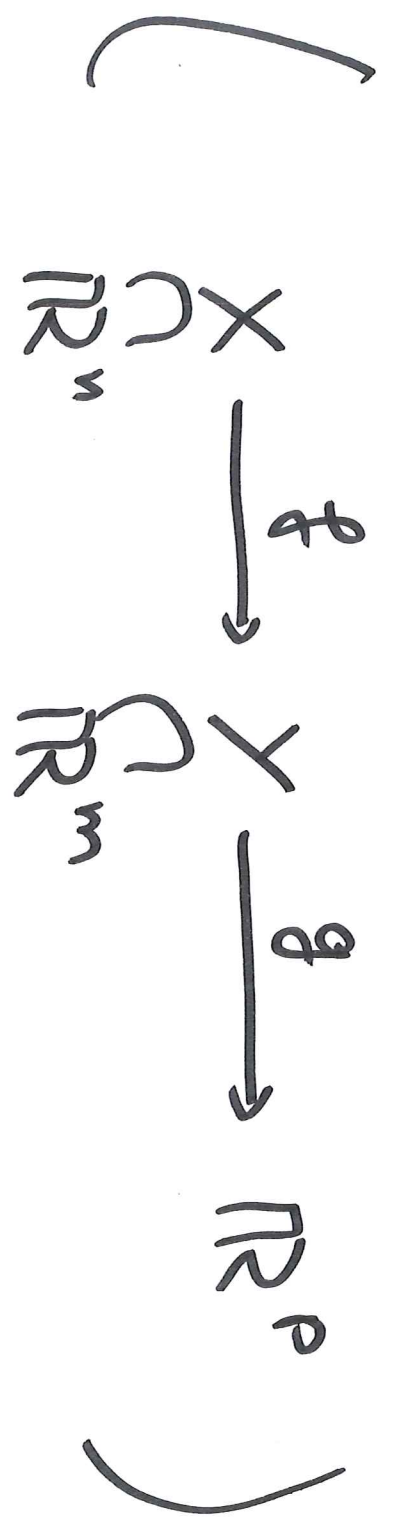
so f is differentiable.

(3) [Chain rule examples]

In terms of Jacobi matrices
The Chain Rule is

$$J_{g \circ f}(x_0) = J_g(f(x_0)) J_f(x_0)$$

matrix product



For instance :

$$n = m = p = 2$$

$$f(x, y) = (f_1(x, y), f_2(x, y)), \quad g(u, v) = (g_1(u, v), g_2(u, v))$$

$$J_f(x, y) = \begin{pmatrix} \partial_x f_1 & \partial_y f_1 \\ \partial_x f_2 & \partial_y f_2 \end{pmatrix}, \quad J_g = \begin{pmatrix} \partial_u g_1 & \partial_v g_1 \\ \partial_u g_2 & \partial_v g_2 \end{pmatrix}$$

at $(u, v) = (f_1(x, y), f_2(x, y))$
part evaluated

$$J_{g \circ f}(x, y) = \begin{pmatrix} \partial_u g_1 & \partial_v g_1 & \partial_x f_1 & \partial_y f_1 \\ \partial_u g_2 & \partial_v g_2 & \partial_x f_2 & \partial_y f_2 \end{pmatrix}$$

evaluate at (x, y)

P = 1

$f: X \rightarrow \mathbb{R}^m \xrightarrow{g} \mathbb{R}$

Chain rule gives $\frac{\partial (g \circ f)}{\partial x_i}$:

i = 1 $f(x) = (f_1(x), \dots, f_m(x))$

$$\frac{\partial (g \circ f)}{\partial x_1} = \frac{\partial g}{\partial y_1} \frac{\partial f_1}{\partial x_1} + \frac{\partial g}{\partial y_2} \frac{\partial f_2}{\partial x_1} + \dots$$

$$+ \frac{\partial g}{\partial y_m} \frac{\partial f_m}{\partial x_1}$$

$$(3) f, g: \mathbb{R}^n \longrightarrow \mathbb{R}$$

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$$\text{Let } h(x) = (f(x), g(x)), \quad h: \mathbb{R}^n \longrightarrow \mathbb{R}^2$$

$$m(u, v) = uv, \quad m: \mathbb{R}^2 \longrightarrow \mathbb{R}$$

$$\text{so } (m \circ h)(x) = f(x)g(x).$$

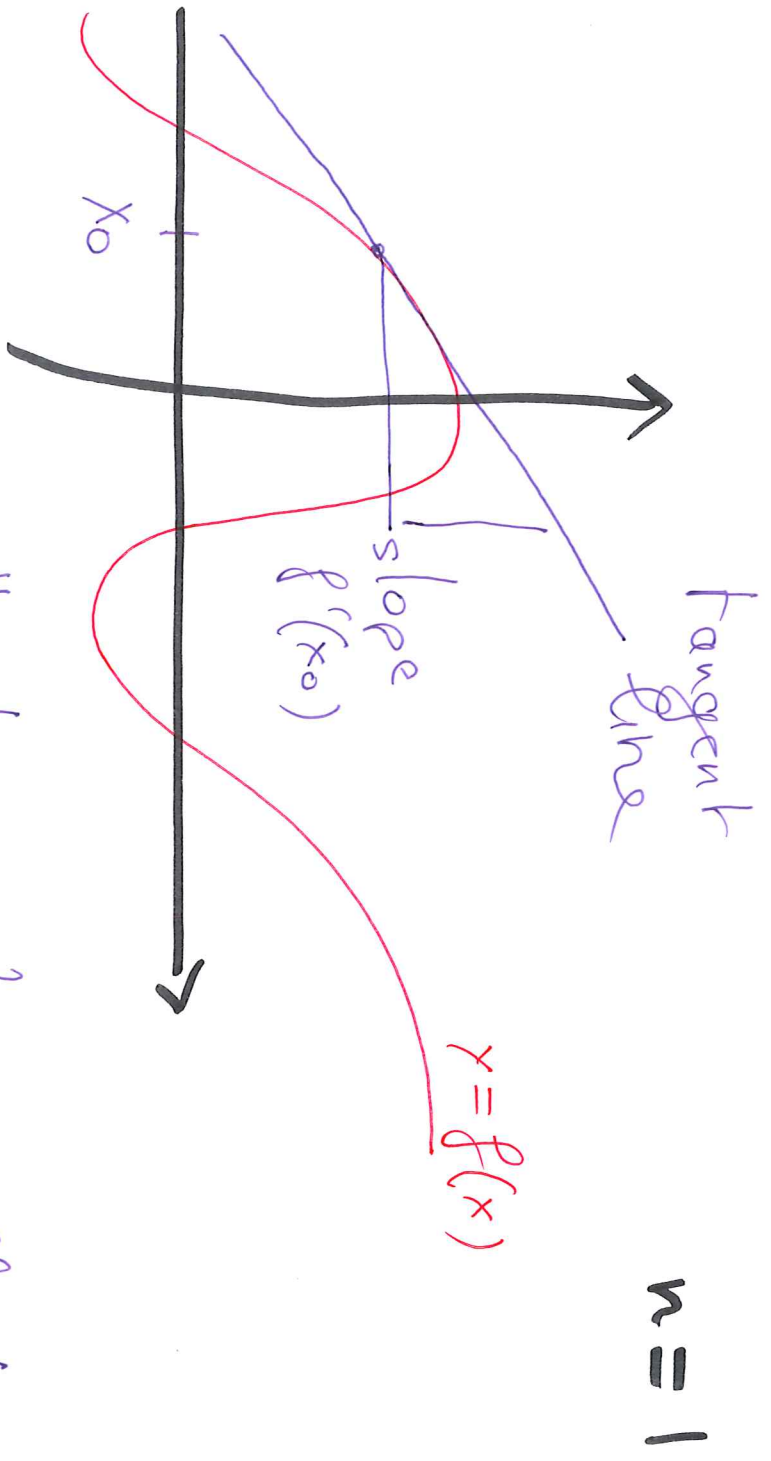
$$J_m(u, v) = \begin{pmatrix} v & u \end{pmatrix}$$

$$\begin{aligned} \text{so } \frac{\partial (m \circ h)}{\partial x_i} &= \frac{\partial (fg)}{\partial x_i} = v \frac{\partial f}{\partial x_i} + u \frac{\partial g}{\partial x_i} \\ &= g(x) \frac{\partial f}{\partial x_i} + f(x) \frac{\partial g}{\partial x_i} \end{aligned}$$

Geometric interpretation

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(1) Tangent space to a graph



$n = 1$

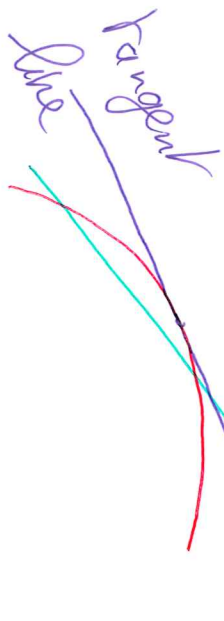
$T = \{ (x, y) \in \mathbb{R}^2 \mid$

$y = f(x) \}$

(graph of f)

"the graph is all to one side of the tangent line"

Close enough:



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General case: $n \geq 2$

If $f: X \rightarrow \mathbb{R}^m$ is differentiable -

- $b \in \mathbb{R}^n$, then we obtain an offline -
linear subspace $H \subset \mathbb{R}^n \times \mathbb{R}^m$
s.t. the graph of f is "best"
approximated by H

Def. (3.4.11)

(43)

$$f: X \rightarrow \mathbb{R}^m$$

differentiable

The tangent space at x_0 to the graph $\Gamma = \{(x, y) \in \mathbb{R}^{n+m} \mid y = f(x)\}$ is the graph of the affine-linear map

$$\begin{aligned} g(x) &= f(x_0) + u(x - x_0) \\ &= f(x_0) - u(x_0) + u(x) \end{aligned}$$

where $u = df(x_0)$.

The tangent space is all
 $\left. \begin{matrix} n \\ m \end{matrix} \right\} \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^{n+m}$ such that

$$y = f(x_0) - u(x_0) + u(x)$$

or

$$\begin{pmatrix} x \\ y \end{pmatrix} = \underbrace{\begin{pmatrix} x_0 \\ f(x_0) \end{pmatrix}}_{\text{fixed}} + \underbrace{\begin{pmatrix} x - x_0 \\ u(x - x_0) \end{pmatrix}}_{\text{gives an } n\text{-dim. linear subspace}}$$

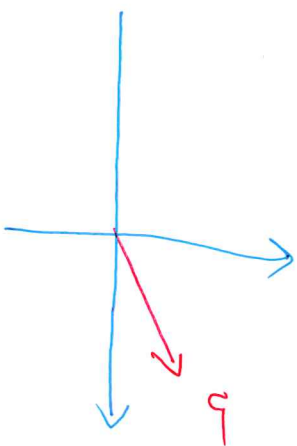
It is an affine subspace of dim. n .

(2) Directional derivatives

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Def. (3.4.13)

$$f: X \longrightarrow \mathbb{R}^m$$
$$0 \neq v \in \mathbb{R}^n$$



$$x_0 \in X$$

We say that f has directional derivative a vector $w \in \mathbb{R}^m$ at x_0 in direction v if the function

$$g(t) = f(x_0 + tv) + t \in \mathbb{R}$$

is differentiable at $t=0$ with $g'(0) = w$.

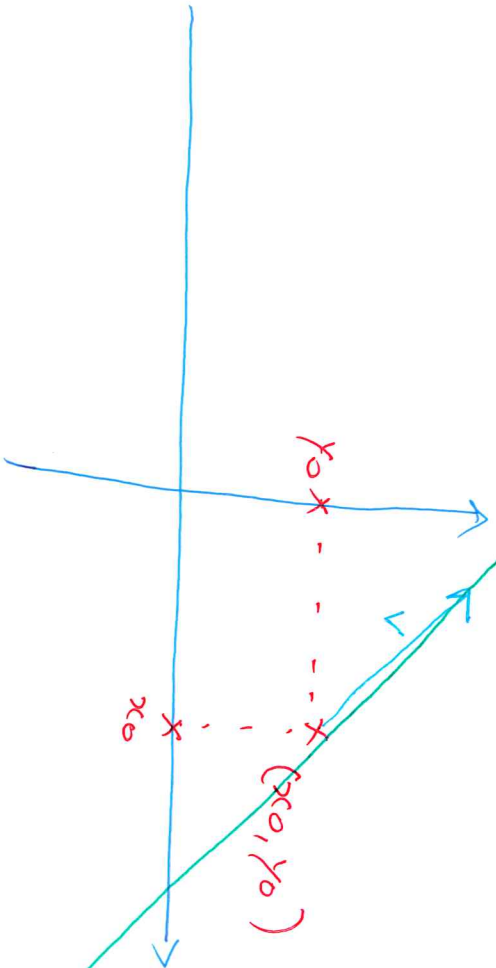
Ex.

(1) $v = e_i$, canonical basis vector

$$v = (0, \dots, 0, 1, 0, \dots, 0)$$

directional derivative = $\frac{\partial f}{\partial x_i}$

(2)



$$\begin{pmatrix} n = 2 \\ m = 1 \end{pmatrix}$$

restrict f to that line

and check if there is a tangent line

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Prop. (3.4.15)

$f: X \rightarrow \mathbb{R}^m$ is differentiable
at x_0 , with $df(x_0) = u$,

Then f has directional ~~derivatives~~
derivative in all directions $\vec{v} \neq 0$,
given by $u(\vec{v})$.

In particular, directional derivative
is linear with respect to v .

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$$(3) \quad \frac{m=1}{}$$

$$f: X \rightarrow \mathbb{R}$$

$$X \subset \mathbb{R}^n$$

differentiable at x_0

$$\text{so } df(x_0)(x) = \nabla f(x_0) \cdot x$$

$$\left(\begin{array}{c} \partial_{x_1} f \\ \vdots \\ \partial_{x_n} f \end{array} \right)$$

↪ tangent space in \mathbb{R}^{n+1}
is the ~~linear~~ affine subspace $f(x_0) +$

\perp perpendicular
no vectors to no

where

$$n_0 = \begin{pmatrix} -\nabla f(x_0) \\ 1 \end{pmatrix}$$

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$\hookrightarrow \nabla f(x_0) \in \mathbb{R}^n$ is the direction of greatest increase of f .