

Most important property of $\int f(s) \cdot d\vec{s}^n$:
independance of parameterization!

Def. (4.1.4)

$$\gamma : [a, b] \longrightarrow \mathbb{R}^n$$

An oriented reparameterization of

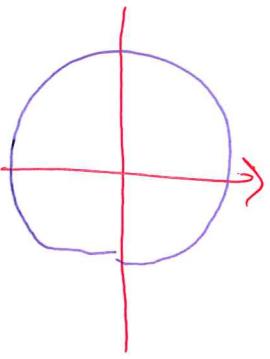
$$\sigma : [c, d] \longrightarrow \mathbb{R}^n$$

s.t. $\gamma(t) = \sigma(\varphi(u))$, $c \leq u \leq d$

where $\varphi : [c, d] \rightarrow [a, b]$ is strictly increasing, $\varphi(c) = a$, $\varphi(d) = b$

Ex.

$$f_n(t) = (\cos(2\pi t^n), \sin(2\pi t^n)) \quad (42)$$



$n \geq 1$

'n regen' the circle γ_2

oriented

reparameterization
of γ

Prop. 4.1.5 -

$$f: X \longrightarrow \mathbb{R}^n$$

$$\int_X f(s) \cdot d\vec{s} = \int_{\sigma} f(s) \cdot d\vec{s}$$

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Proof:-

$$\sigma = \gamma \circ \varphi$$

$$\varphi: [c, d] \rightarrow [\underline{a}, \underline{b}]$$

(143)

$$\int_{\sigma} f(s) \cdot d\vec{s} = \int_c^d f(\sigma(u)) \cdot \sigma'(u) du +$$

chain rule

$$= \int_c^d f(\varphi(\varphi(u))) \cdot \frac{\varphi'(u)}{\underline{R}} \frac{\varphi'(\varphi(u))}{\underline{R}^n} du$$

Substitute

$$\varphi(u) = t$$

$$\varphi'(u) du = dt$$

$$= \int_c^d f(\varphi(\varphi(u)) \cdot \varphi'(\varphi(u)) \frac{\varphi'(u)}{\underline{R}} du$$

$$\frac{\varphi'(u)}{\underline{R}}$$

$$= \int_a^b f(\varphi(t)) \cdot \varphi'(t) dt$$

$$= \int_a^b f(s) \cdot d\vec{s}$$

(144)

Remark: (1) oriented representations
on ℓ^* !

For instance a non-oriented representation -
realization of $\delta: [0, 1] \rightarrow \mathbb{R}^n$

is

$$\sigma(u) = \delta(1-u)$$

$$\sigma: [0, 1] \longrightarrow \mathbb{R}$$

Then

$$\int_{\sigma} f(s) \cdot d\vec{\sigma} = - \left(f(s) \cdot d\vec{s} \right)$$

$$f(0) = \sigma(1)$$

$$\left(\int_0^1 g = - \int_1^0 g \right)$$

(2) So

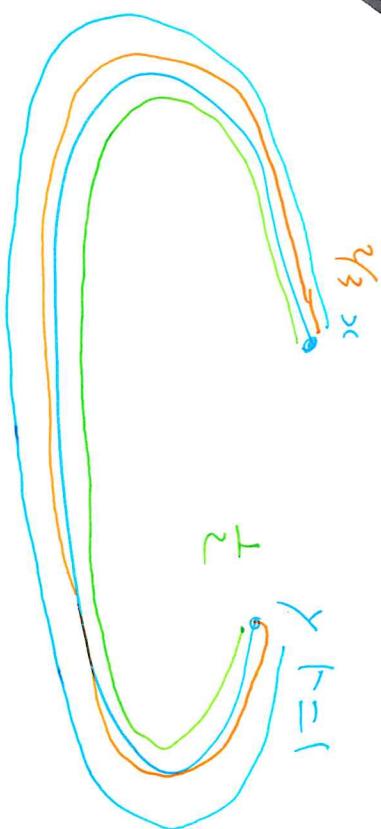
$$\int f(s) \cdot d\vec{s} \text{ on } \gamma$$

depends on the

image of γ in

" R^n "

R^n



one goes along the curve only once.

If σ goes from

x to y with $0 \leq t \leq \frac{1}{2}$, then γ with t to x with $\frac{1}{2} \leq t \leq 1$, then γ with $\frac{3}{2} \leq t \leq 1$.

This is

true, but

only if

145

Then

$$\int_{\sigma} f(s) \cdot d\vec{s} \neq \int_{f(\sigma)} f(s) \cdot d\vec{s}$$

(46)

even if the image of σ is the same as that of δ .

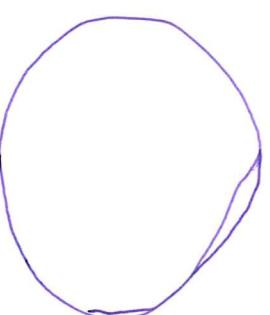
E.g. "Compute the line integral

$$f(x,y) = \begin{pmatrix} p_1(x,y) \\ p_2(x,y) \end{pmatrix},$$

circle $x^2 + y^2 = 1$ "

Then one has to find

a parameterization going around the circle only once.



Conservative vector fields

Let $X \subset \mathbb{R}^n$ be open

Let $g : X \rightarrow \mathbb{R}$ be

$$\text{Define } g = \underline{\underline{\nabla g}} =$$

$$g(x_1, \dots, x_n) =$$

This is a vector field
on X : it is continuous.

Let

$$\gamma: [a, b] \rightarrow X$$

a parameterized curve.

$$\int_a^b f(s) \cdot ds = \int_a^b f(\gamma(t)) \cdot \gamma'(t) dt$$

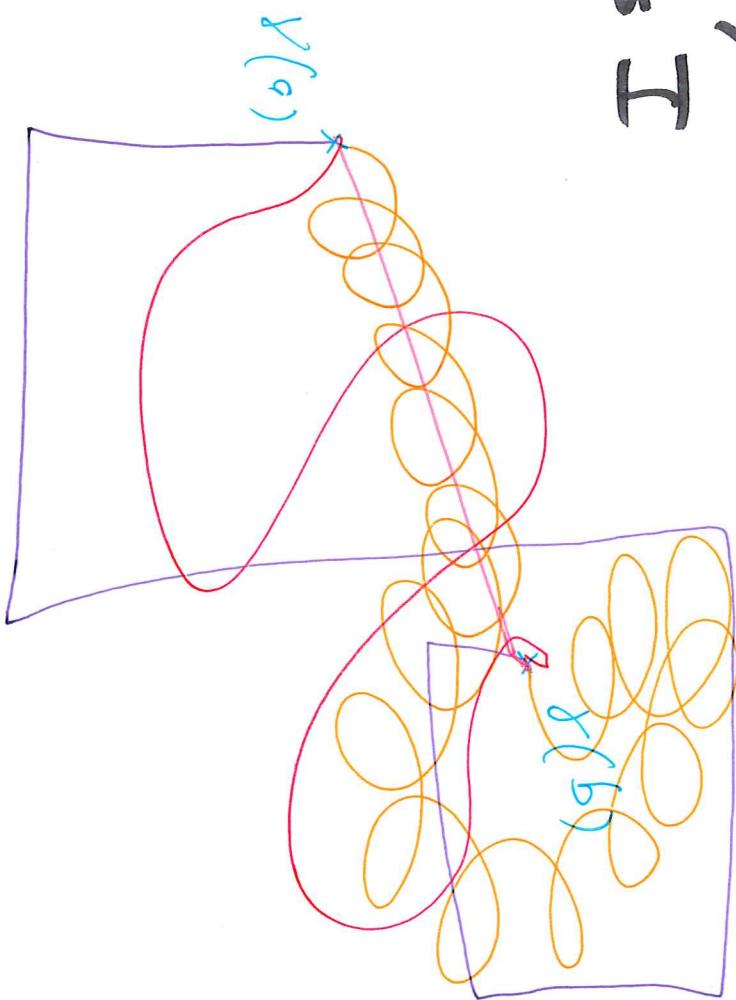
$$[\gamma(t) = (\gamma_1(t), \dots, \gamma_n(t)) \\ \gamma'(t) = (\gamma'_1(t), \dots, \gamma'_n(t))]$$

$$= \int_a^b \sum_{i=1}^n \underbrace{\frac{d}{dt} f_i(\gamma(t))}_{\frac{df}{dt}} \underbrace{\gamma'_i(t)}_{\frac{dx}{dt}} dt$$

$$\begin{aligned}
 (\text{Chain rule}) &= \int_a^b \frac{d}{dt} g(\gamma(t)) dt + \\
 &\quad g(\gamma(b)) - g(\gamma(a))
 \end{aligned}$$

Analysis I

This only depends on the endpoints of γ !



Def. (4.1g) A vector field

$$f: X \rightarrow \mathbb{R}^n$$

is conservative

if the line

$$\int f(s) \cdot ds$$

integral

~~of dependent on the direction of~~

is the same for all parameterized curves with the same starting point and endpoint.

Remark: (4.1.9)

$f: X \rightarrow \mathbb{R}^n$

conservative

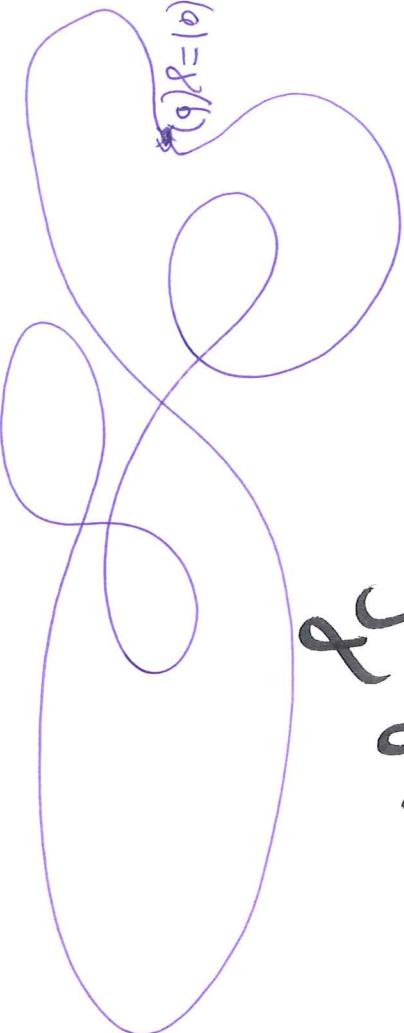


for any closed curve $\gamma: [a, b] \rightarrow X$
(that is, $\gamma(b) = \gamma(a)$), we have

$$\int_{\gamma} f(s) \cdot d\vec{s} = 0$$



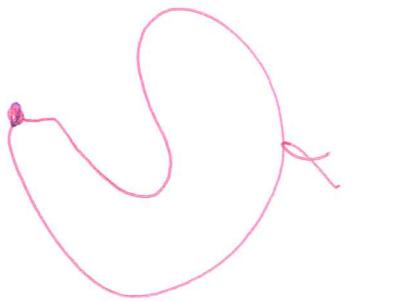
$$\gamma(a) = \gamma(b)$$



151

[conservative]

[closed]



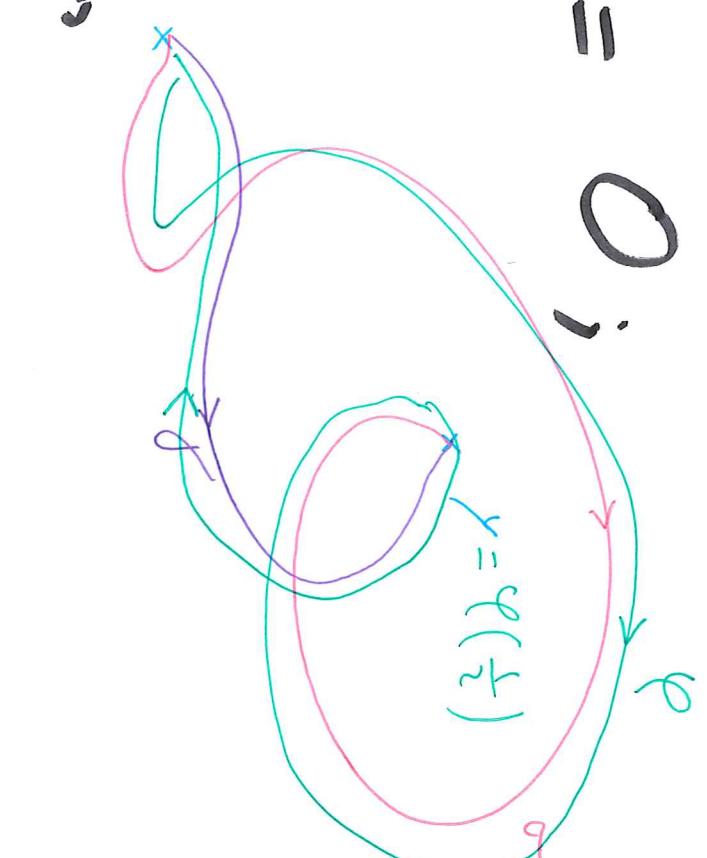
$$\int_{\gamma} f(s) \cdot d\vec{s} = \int_{\sigma} f(s) \cdot d\vec{s}$$

where $\sigma(t) = \gamma(a)$

$$= 0;$$

conversely:

$$\int_{\gamma} f(s) \cdot d\vec{s} = 0$$



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Th. (4.1.10)

Let $f: X \rightarrow \mathbb{R}^n$ be (continuous)

conservative. Then there is

$$g: X \rightarrow \mathbb{R}^*$$

$\in C^1$

such that $f = \nabla g$.

[Def.: g is called a potential of
the vector field f .]

(153)

154

Remark: (i) the potential is not unique:

one replace g by $g + a$, where $a \in \mathbb{R}$.

(ii) if X is path-connected then

two potentials g_1, g_2 of \mathcal{F} satisfy

$$g_2 - g_1 = \text{constant on } X.$$

Def.

X

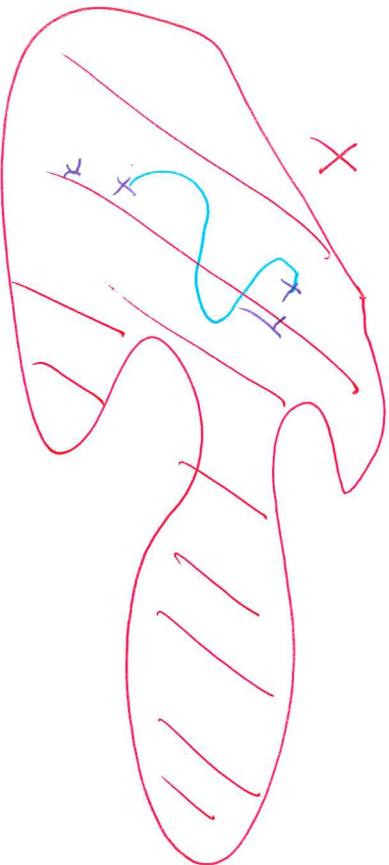
is path-connected

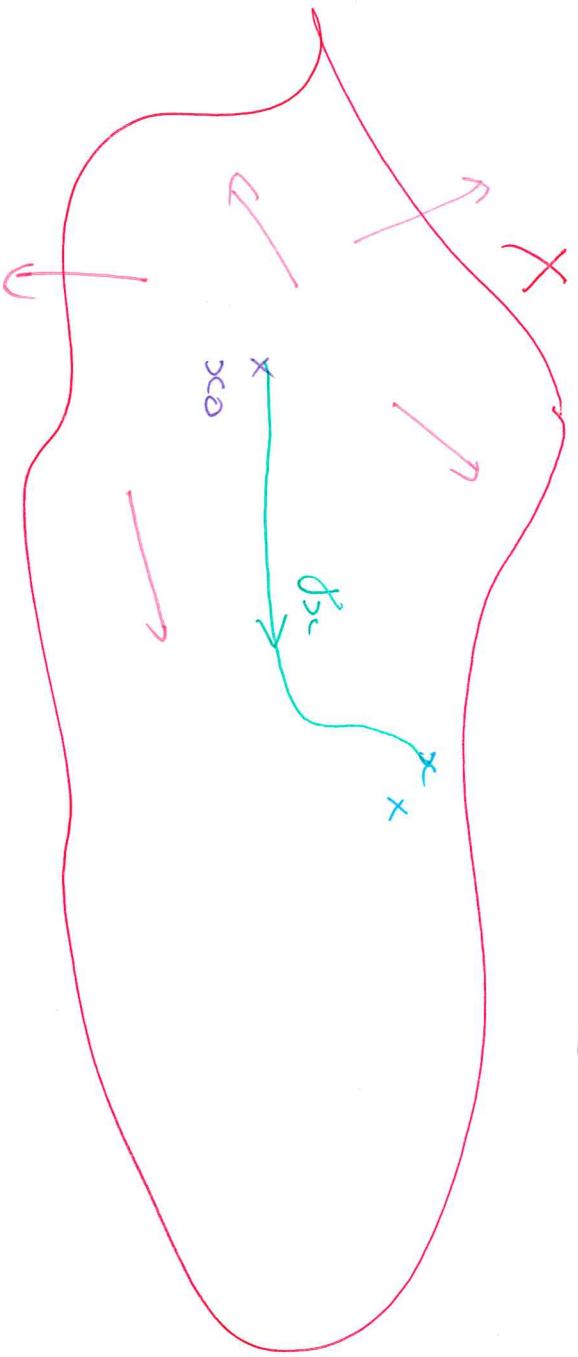
\Updownarrow

for all

x, y in X
there is
curve

$\gamma: [0, 1] \rightarrow X$ s.t.
 $\gamma(0) = x, \gamma(1) = y$





Idea of proof.

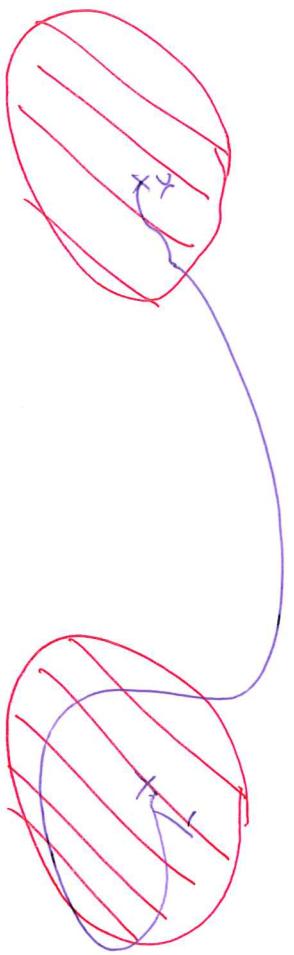
$X = \text{union of two disjoint discs}$
 is not path-connected

(X path connected)

$$g(x) = \int f(s) ds$$

f_x

where f_x
goes from
 x_0 to x



155

156

If conservative $\Rightarrow f(x)$ does not depend on the choice of f^{x_i} .

To compute

$$\frac{\partial}{\partial x_1}$$



$$(x_1 + \delta x_1, x_2, \dots, x_n) = x'$$

\Rightarrow computations like fundamental th. of calculus.

$f_{x_1}^* = f^*$ followed by a small horizontal segment

Questions:

- (1) How does one check that a "concrete" vector field is conservative or not?
- (2) How does one compute a potential ϕ of a conservative vector field \mathbf{f} ?

Example / answer for (2):

$$f = (f_1, \dots, f_n)$$

1528

Method:

$$\frac{C_f}{e^{x_1}} = f_2$$

b.)

primitive w.r.t. $x_1 \Rightarrow$

$$g = F_1 + g_1(x_2, \dots, x_n)$$

solve

$$f_2 = \frac{\partial F_1}{\partial x_2} + \frac{\partial g_1}{\partial x_2}$$

$$\Rightarrow g = F_1 + F_2 + g_2(x_3, \dots)$$

4.1.12 (2)

$$f(x, y, z) =$$

$$\begin{pmatrix} 6x^2 \cos(yz) + 3 \sin(y) \\ -3x^2 \sin(yz) + x^2 \cos(y) \\ z^2 + 2z + 1 \end{pmatrix}$$

$$f(x, y, z) =$$

$$\begin{aligned}
 & z^2 + k^2 + \\
 & (k) \sin 2x + (\cos k) \sin 2x \times \sum = (\sin k)^2 \quad \Leftarrow \\
 & \dots \dots \dots \\
 & (\sin k) \sin 2x + k \cos k = (\sin k)^2 \quad \Leftarrow \\
 & \dots \dots \dots \\
 & = \frac{k^2}{1 - k^2} + \\
 & (k) \sin 2x + (k) \sin 2x - \quad \Leftarrow \\
 & (\sin k)^2 + \sin k \cos k + \\
 & (\sin k)^2 \cos k + \sin k \sin k \cos k = \beta \\
 & \Leftarrow
 \end{aligned}$$

(65)

Q. How does one check that
a vector field is conservative?

Necessary condition:

Prop. 4.1.13

$X \subset \mathbb{R}^n$, open

$f: X \rightarrow \mathbb{R}^n$ C^1 vector field

is conservative then

$$\frac{\partial f_i}{\partial x_j} = \frac{\partial f_j}{\partial x_i} \quad \text{for } 1 \leq i, j \leq n$$

$$(*) \quad \frac{\partial f_i}{\partial x_j} = \frac{\partial f_j}{\partial x_i}$$

Ex:

$$f(x, y, z) = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \text{in } \mathbb{R}^3$$

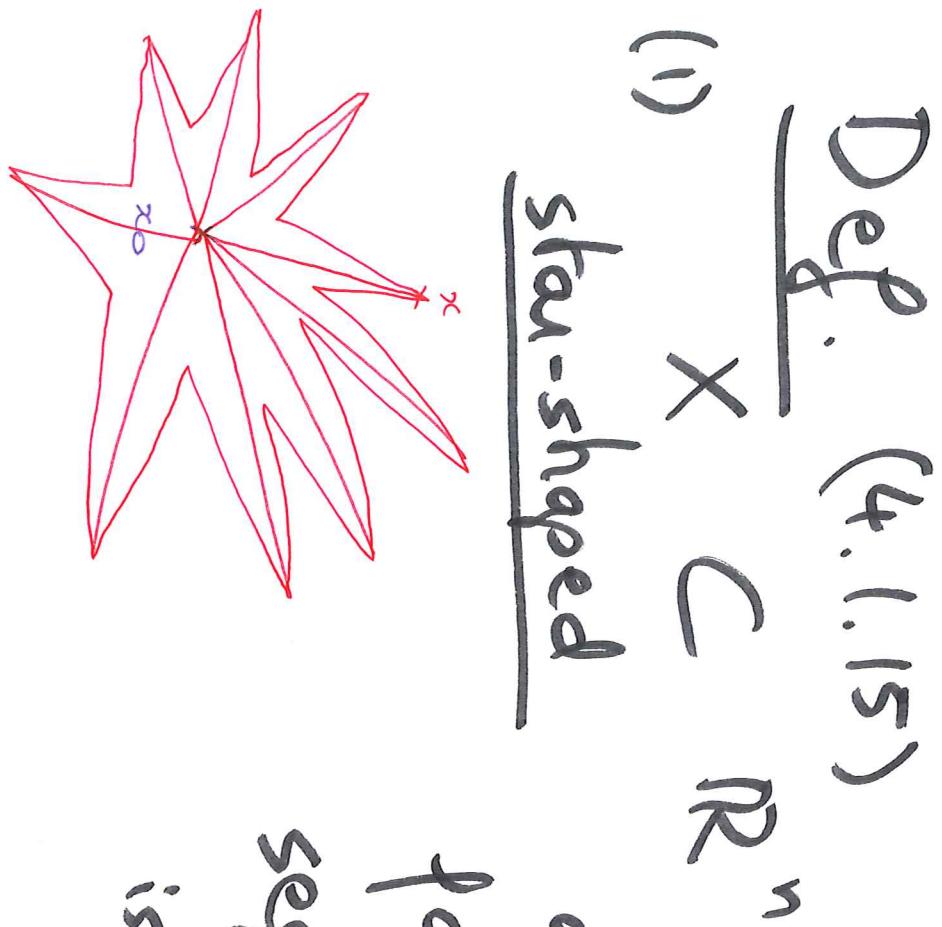
$$\frac{\partial f_1}{\partial y} = \cancel{2y} \neq \frac{\partial f_2}{\partial x} = z$$

so f is not conservative

Question: if all equalities (*) i.d. are true for $f(x, y, z)$, is it conservative?

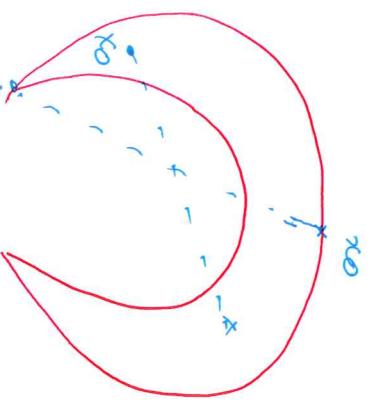
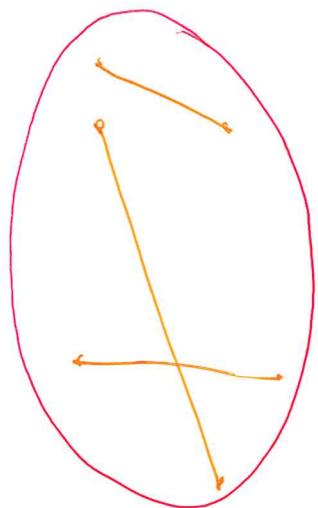
(61)

The answer depends on the shape of X .



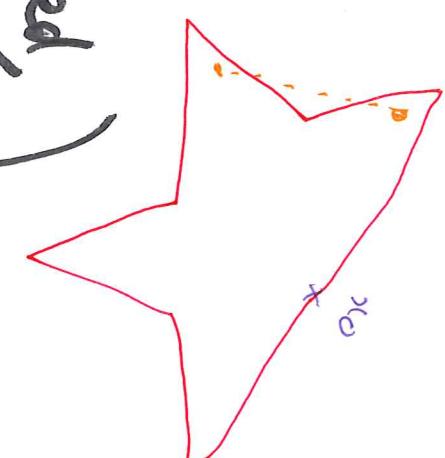
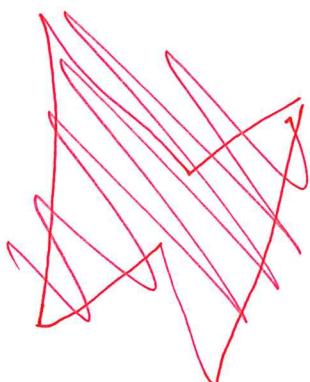
(i) Def. (4.1.15)
 $X \subset \mathbb{R}^n$ is called star-shaped around $x_0 \in X$ if for all $x \in X$, the segment from x_0 to x is contained in X .

(2) $X \subset \mathbb{R}^n$ is convex if
for all $x, y \in X$,
the segment
joining them is contained in X .



not star-shaped

(star-shaped,
not convex)



Ex.

• any ball is convex

$$\{x \in \mathbb{R}^n \mid \|x - x_0\| \leq r\}$$

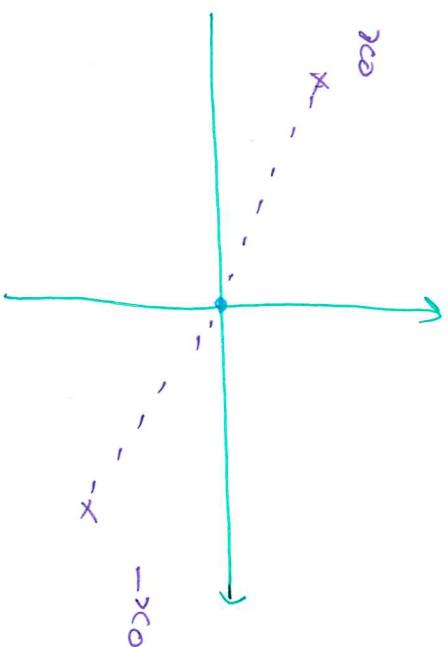
• a sphere is not convex

$$\{x \in \mathbb{R}^n \mid \|x - x_0\| = r\}$$



\mathbb{R}^n is convex

$$\mathbb{R}^n - \{0\}$$



is not

star-shaped

(Ball of radius 1 around 0) - {0}

(Ball of radius 1 around 0) - {0}



164

Th. (4.1.17) $\frac{\partial}{\partial t}$

$f: X \subset \mathbb{R}^n$, open, star-shaped

C^1 vector field

$\frac{\partial f_i}{\partial x_j} = - \frac{\partial f_j}{\partial x_i}, \quad 1 \leq i \neq j \leq n$

Then f is conservative.

Ex.

$$f(x, y) = \begin{pmatrix} ax^3 + bx^2y \\ bx^4 + cx^2y^2 \end{pmatrix}$$

For which (a, b, c) is f conservative?

$$X = \nabla f = \begin{pmatrix} ax^2 + 2bx^2y \\ 4bx^3 + 2cx^2y \end{pmatrix}$$

$$\text{so } c \Rightarrow$$

$$\frac{\partial f_2}{\partial x} = \frac{\partial f_1}{\partial y}$$

$$4bx^3 + 2cx^2y = ax^3 + 3bx^2y^2$$

$$4b = a \quad \text{and} \quad 2c = 3b$$

(166)

so

$$(a, b, c) = \left(4b, b - \frac{3b}{2}\right).$$

(167)

(Note:

if f_1, f_2 conservative, then

$f = af_1 + bf_2$ is conservative
for all a, b in \mathbb{R}

$$g = ag_1 + bg_2$$