

Betrachten wir den GDF zur Endzeit $T = t_N$:

$$\begin{aligned}
 |e_N| &\stackrel{\text{Def.}}{=} |y(t_N) - y_N| \\
 &= \left| \underbrace{y(t_{N-1})}_{\text{Trick}} + h \cdot \underbrace{\frac{y(t_N) - y(t_{N-1})}{h}}_{\text{Trick}} \right. \\
 &\quad \left. - h \left(\underbrace{\phi(t_{N-1}, y(t_{N-1}), h)}_{\text{Trick}} - \underbrace{\phi(t_{N-1}, y(t_{N-1}), h)}_{\text{Trick}} \right) \right. \\
 &\quad \left. - \underbrace{\left(y_{N-1} + h \cdot \phi(t_{N-1}, y_{N-1}, h) \right)}_{y_N} \right|
 \end{aligned}$$

$$\begin{aligned}
 &\stackrel{\Delta\text{-UG}}{\leq} \underbrace{|y(t_{N-1}) - y_{N-1}|}_{= e_{N-1}} \\
 &+ h \cdot \underbrace{\left| \frac{y(t_N) - y(t_{N-1})}{h} - \phi(t_{N-1}, y(t_{N-1}), h) \right|}_{= \rho_N} \\
 &+ h \cdot \underbrace{\left| \phi(t_{N-1}, y(t_{N-1}), h) - \phi(t_{N-1}, y_{N-1}, h) \right|}_{= h \tilde{L} |y(t_{N-1}) - y_{N-1}| = h \tilde{L} |e_{N-1}|}
 \end{aligned}$$

$$= (\lambda + h \tilde{L}) |e_{N-1}| + |e_N|$$

$$\stackrel{\text{Rekursiv einsetzen}}{=} (\lambda + h \tilde{L}) \left((\lambda + h \tilde{L}) |e_{N-2}| + |e_{N-1}| \right) + |e_N|$$

$\vdots$

$$\begin{aligned}
 &= (\lambda + h \tilde{L})^N |e_0| + \sum_{j=1}^N \underbrace{(\lambda + h \tilde{L})^{N-j}}_{\leq (\lambda + h \tilde{L})^N} |e_j|
 \end{aligned}$$