

III.3. Decomposition into irreducible symmetric spaces.

Our aim is to push the decomposition theorem a little further until we reach "irreducible pieces". Some care has to be taken since for instance euclidean space E^n , $n \geq 2$, is a riemannian product in many ways. With the proper concepts we will however be able to obtain a canonical decomposition of so called reduced OSL's,

Def. III.20 An OSL $(\mathfrak{g}, \mathfrak{O})$ is reduced if it does not contain any non-zero ideal of \mathfrak{g} .

Clearly since any subalgebra of the center $Z(\mathfrak{g})$ of \mathfrak{g} is an ideal, if (\mathfrak{g}, θ) is reduced, we must have $Z(\mathfrak{g}) \cap \mathfrak{u} = (0)$ and hence (\mathfrak{g}, θ) is effective.

Def III.21 An OSL (\mathfrak{g}, θ) with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ is irreducible

if (1) \mathfrak{g} is semisimple and (\mathfrak{g}, θ) is reduced.

(2) the Lie algebra $\text{ad}_{\mathfrak{g}}(\mathfrak{k})$ acts irreducibly on \mathfrak{p} .

With these definitions we have:

Theorem III. 22

Let (g, θ) be a reduced OSL. Then

(g, θ) is the direct product of a reduced OSL (g_0, θ_0) of unidirectional

type and irreducible OSL's (g_i, θ_i)

$1 \leq i \leq a$. This decomposition is unique

up to orders of the factors $1 \leq i \leq a$.

The proof (left as an exercise) uses the

same overall strategy than the proof

of Thm III. 9 with an additional input:

Thm III. 23 Let $K < GL(V)$ be a

compact subgroup where V is a finite

dimensional real vector space. Then

there is a decomposition $V = \bigoplus_{i \in I} V_i$
into a direct sum of K -invariant
irreducible subspaces.

The idea of proof goes as follows:
First one uses a Haar measure on K
to produce a K -invariant scalar product
on V . Then one observes that if $W \subset V$
is K -invariant so is its orthogonal W^\perp .
Finally one chooses $W \subset V$ minimal invariant
and proceeds by induction on $\dim V$.

Now with the notations of the proof of
Thm III. 9 namely

$$B_g(x, y) = \langle Ax, y \rangle \quad \forall x, y \in E$$

let $E = \bigoplus_{i=0}^r E_i$ be the direct sum

decomposition into eigenspaces of A :

$$A|_{\mathfrak{g}_i} = c_i \text{Id}, \quad c_0 = 0, \quad c_1 \neq 0, \dots, c_r \neq 0$$

and all the c_i 's are distinct.

Then $\text{ad}_g(u)$ leaves each \mathfrak{g}_i invariant

and since $\text{ad}_g(u) \in \text{Lie } U$ with

U compact we can apply Thm III.23

and there exists therefore a direct

sum decomposition of $\bigoplus_{i=1}^r \mathfrak{g}_i$ into

subspaces $\mathfrak{M}_i, i=1, \dots, a$ each of

which is contained in some \mathfrak{g}_j , which

are mutually orthogonal wrt B_g and

$\text{ad } u$ -minimal invariant. Then one

defines
$$\mathfrak{g}_i = [\mathfrak{M}_i, \mathfrak{M}_i] + \mathfrak{M}_i$$

$$i = 1, \dots, a$$

Then one shows:

(1) \mathfrak{g}_i is a \mathbb{Q} -stable ideal in \mathfrak{g} .

(2) $B_{\mathfrak{g}_i} = B_{\mathfrak{g}}|_{\mathfrak{g}_i \times \mathfrak{g}_i}$ is non-degenerate.

Define then $\mathfrak{TR} := \bigoplus_{i=1}^a \mathfrak{g}_i$. Then \mathfrak{TR}

is a semisimple \mathbb{Q} -stable ideal in \mathfrak{g}

(3) $\mathfrak{g}_0 := \mathcal{Z}_{\mathfrak{g}}(\mathfrak{TR})$ the centralizer of

\mathfrak{TR} in \mathfrak{g} is a \mathbb{Q} -stable ideal in \mathfrak{g} .

Now we turn to the corresponding notions for

RSP's and Riemannian symmetric spaces.

Def. III.24 A Riemannian symmetric pair

(G, K) is

- reduced if the corresponding OSZ is

- irreducible if the corresponding OSZ is.

We observe that (G, K) is reduced iff

K doesn't contain any connected non-trivial normal subgroup of G or in other words:

(III.25) The kernel N of the G -action on G/K is discrete.

We conclude that if M is RSP and

$G = \text{Is}(M)^\circ$, $K = \text{Stab}_G(o)$ the associated

RSP, then (G, K) is reduced.

~~We define~~ It thus makes sense to define:

Def III.26 A RSP M is irreducible if

the corresponding RSP is.

From the above we deduce

(IV.27) A riemannian symmetric space M

is irreducible iff for $G = \text{Is}(M)^\circ$, $K = \text{Stab}_G(o)$

the Lie algebra \mathfrak{g} of G is semisimple

and the representation $\text{Ad}: K^0 \rightarrow \text{GL}(\mathfrak{p})$ is irreducible, where $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ is the Cartan decomposition.

As in Thm III. 19, one can globalize the decomposition given by Thm IV. 22 and obtain

Corollary III. 28.

A riemannian symmetric space M is isometric to a riemannian product

$$M_0 \times M_1 \times \dots \times M_c$$

where $M_0 = \mathbb{E}^n$, and M_1, \dots, M_c are irreducible. This product decomposition is unique up to permutation of the factors M_1, \dots, M_c .

Irreducible riemannian symmetric pairs

(hence spaces) satisfy an interesting dichotomy:

Prop. III.29 Let (G, κ) be an \mathbb{R} irradual

riemannian symmetric pair $g = \mathfrak{g} \oplus \mathfrak{p}$ the Cartan decomposition and B_g the Killing form of g . Then there is a (up to scaling) unique G -invariant riemannian metric

on G/κ and one of the following holds:

(1) $B_g|_{\mathfrak{p} \times \mathfrak{p}} \gg 0$ and G/κ is of non-compact type.

(2) $B_g|_{\mathfrak{p} \times \mathfrak{p}} \ll 0$ and G/κ is of compact type.

In the first case $B_g|_{\mathfrak{p} \times \mathfrak{p}}$ gives rise to

a G -invariant riemannian metric, and in

the second case it is $\rightarrow B_g|_{\mathfrak{p} \times \mathfrak{p}}$.

Proof: As usual, let $\langle \cdot, \cdot \rangle$ be any

AdK-invariant scalar product on \mathfrak{g}

and $A \in \text{End } \mathfrak{g}$ defined by

$$B_{\mathfrak{g}}(x, y) = \langle Ax, y \rangle \quad \forall x, y \in \mathfrak{g}.$$

~~Since A and $\text{Ad}(K)$ commute~~

Recall that A is symmetric hence diagonal

over \mathbb{R} . Since $\text{Ad}(K)$ and A commute

any eigenspace of A is $\text{Ad}(K)$ -invariant

which since $\text{Ad}(K)$ act irreducibly on \mathfrak{g}

implies $A = \lambda \text{Id}$ for some $\lambda \neq 0$.

Thus $B_{\mathfrak{g}}(x, y) = \lambda \langle x, y \rangle$ which shows

the uniqueness statement. The sign of λ

then determines whether we are in case (1)

or (2).



IV. On some global properties of

symmetric spaces. Duality.

In the first subsection we indicate how the distinction between compact type, non-compact type and euclidean type is reflected in the sign of the sectional curvature. With a theorem of Hadamard we conclude then that a symmetric space of non-compact type is diffeomorphic to \mathbb{R}^n and is a CAT(0)-space. In the second subsection we establish some basic properties of semisimple group and use them to show that if (G, K) is a riemannian symmetric pair of compact

type, then G is compact and the associated symmetric space $M = G/K$ is as well.

The last subsection is devoted to the duality between symmetric spaces of compact and non-compact type.

IV. 1. Curvature of symmetric spaces.

Recall that if (M, g) is a riemannian manifold and ∇ the Levi Civita connection, the multilinear mapping

$$R : \text{Vect}(M) \times \text{Vect}(M) \times \text{Vect}(M) \longrightarrow \text{Vect}(M)$$

defined by :

$$R(X, Y)Z := \nabla_X (\nabla_Y Z) - \nabla_Y (\nabla_X Z) - \nabla_{[X, Y]} Z$$

is a tensor, that is, the value

$(R(X, Y)Z)_p$ at a point p only depends

on the values X_p, Y_p, Z_p .

A related curvature notion which is

equivalent to the knowledge of the

Riemannian curvature tensor is the sect-

ional curvature σ_p defined for every

$p \in M$ on the Grassmannian of 2-planes

in $T_p M$:

$$\sigma_p: Gr_2(T_p M) \rightarrow \mathbb{R}$$

$$\sigma_p(P) = - \langle R(u, v)u, v \rangle$$

where $\{u, v\}$ is an orthonormal basis

of the 2-plane $P \subset T_p M$.

We refer to Berger's book "A panorama of Riemannian Geometry" section 4.4 for a discussion of various aspects of the Riemannian curvature tensor.

A fundamental theorem due to J.

Hadamard gives global metric information for Riemannian manifolds with sectional curvature ≤ 0 .

Thm IV.1. Let M be a complete Riemannian manifold with $\sigma_p(R) \leq 0$ $\forall p \in M$, $\forall R \in \mathcal{G}_2(T_p M)$.

Given $p \in M$ and $v \in T_p M$ and identifying $T_v(T_p M)$ with $T_p M$ we

have:
$$D_v \exp_p : T_p M \rightarrow T_p(M)$$

$$\exp_p(0)$$

is norm increasing, that is:

$$\|D_e(\exp_p)(\xi)\| \geq \|\xi\| \quad \forall \xi \in T_p M.$$

In particular

$$(1) \text{ length}(\sigma) \leq \text{length}(\exp_p \circ \sigma)$$

for any rectifiable path $\sigma: [0, 1] \rightarrow T_p M$.

$$(2) \exp_p: T_p M \rightarrow M \text{ is a covering}$$

map.

(3) If M is simply connected,

\exp_p is a diffeomorphism and

$$d(\exp_p(v), \exp_p(w)) \geq \|v - w\|$$

$$\forall v, w \in T_p M.$$

~~We will return~~

In this subsection we want to

discuss the following:

Thm IV. 2

Let (G, κ) be a RSP and M the associated symmetric space equipped with a G -invariant Riemannian metric.

(1) If (G, κ) is of compact type the sectional curvature is everywhere ≥ 0 .

(2) If (G, κ) is of non compact type the sectional curvature is everywhere ≤ 0 .

(3) If (G, κ) is of Euclidean type the sectional curvature $\equiv 0$.

~~The proof of~~

Thus Hadamard's theorem applies to symmetric spaces of non-compact type.

The proof of Thm IV.2 is based on a (non-trivial) computation which we will skip.

See Helgason Thm IV.4.2 p. 215.

Thm IV.3

Let (G, κ) be a RSP, M the associated symmetric space and R the ricmanian curvature tensor with any G -invariant metric. Let as usual

$$D_c \pi: \mathcal{P} \rightarrow T_0 M$$

be the canonical isomorphism. Then

$\forall x, \tau, z \in \mathcal{P}$:

$$R_0(\overline{x}, \overline{\tau} | \overline{z}) = - \overline{[x, \tau], z}$$

where we set $\overline{T} = D_c \pi(T)$, $T \in \mathcal{P}$.

Proof of Thm IV.2 :

We use IV.3 to compute the sectional curvature in each case.

Let (g, ω) be the o.s.l. associated to (G, κ) , $\mathfrak{g} = \mathfrak{g} \oplus \mathfrak{p}$ the Cartan decomposition and B_g the Killing form. Then

We have $\forall x_1, x_2 \in \mathfrak{p}$:

$$\begin{aligned} & B_g(-[[x_1, x_2], x_1], x_2) \\ &= B_g([x_1, [x_1, x_2]], x_2) \\ &= -B_g([x_1, x_2], [x_1, x_2]). \end{aligned}$$

If (G, κ) is of compact type we may

take $-B_g|_{\mathfrak{p} \times \mathfrak{p}}$ as Riemannian metric at 0, under the identifie.