

$$D_c \bar{u} : P \longrightarrow T_0 M.$$

In this case if $x_1, x_2 \in P$ are such that \bar{x}_1, \bar{x}_2 are orthonormal in $T_0 M$,

we have:

$$\sigma_0(\bar{x}_1, \bar{x}_2) = -\langle R_0(\bar{x}_1, \bar{x}_2), \bar{x}_1, \bar{x}_2 \rangle$$

$$= \overline{\langle [x_1, x_2], x_1 \rangle}, \bar{x}_2$$

$$= -B_{g_0}([x_1, x_2], x_1, x_2)$$

$$= -B_{g_0}([x_1, x_2], [x_1, x_2]) = \|\bar{x}_1, \bar{x}_2\|^2 \\ \geq 0.$$

In the case (G, K) of non-compact type we can take $B_{g_0}|_{P \times P}$ or

Riemannian metric at 0 and the

Computation above leads to

$$\sigma_0(\langle \bar{x}_1, \bar{x}_2 \rangle) = -\|\overline{[x_1, x_2]}\|^2 \leq 0.$$

The assertion about the euclidean type
is clear.

IV.2. Semisimple Lie groups : bases.

We have seen that the decomposition
theorem of symmetric spaces leads to
a class of Lie algebras, the semisimple
ones. The corresponding Lie groups are
then closely related to RSP and in this
short introduction we will establish an
important global property of those with
negative definite Killing form.

Def. IV. 4 A Lie group is semisimple
if its Lie algebra is.

Beside their importance for the study
of RSS, semisimple groups are together
with solvable ones the building blocks
of general Lie groups.

Next let us indicate where the terminology
semisimple comes from.

Def. IV. 5 A Lie algebra is simple
if it is non-abelian and contains
no proper non-zero ideals.

Then:

Thm IV. 6. (Cartan's criterion) A Lie
algebra \mathfrak{g} is semisimple if and only if
it is sum of simple ideals.

In fact this theorem is valid for Lie algebras over a field of characteristic zero. One direction is an elegant ~~the~~ argument of Diananda. Assume K_g is non-degenerate. First we show that g has no non-zero ~~ideal~~ abelian ideal. Indeed if $\alpha \triangleleft g$ is an abelian ideal then one verifies easily that

$$(\text{ad}(A)\text{ad}(x))^2 = 0 \quad \forall A \in \mathfrak{g}, \forall x \in \alpha$$

and hence

$$K_g(A, x) = \text{tr}(\text{ad}(A)\text{ad}(x)) = 0.$$

Next let $\pi \triangleleft g$ be a non-zero ideal of minimal dimension. Then $[\pi, \pi]$ being an ideal in g and π being not abelian

implies $m = [m, m]$. Let m^\perp be
the subspace of \mathfrak{g} orthogonal to m wrt
the Killing form. Then one verifies that
 m^\perp is an ideal. Thus either $m \cap m^\perp = \{0\}$
or $m \subset m^\perp$. The latter case cannot
occur: let $A = \sum_i [B_i, C_i] \in m$ and
with $B_i, C_i \in m$
 $x \in \mathfrak{g}$. Then:

$$\begin{aligned} K_g(A, x) &= - \sum_i K_g(B_i, [C_i, x]) \\ &\stackrel{\wedge}{\in} m \quad \stackrel{\top}{\in} m^\perp \\ &= 0 \quad \text{since } m \subset m^\perp. \end{aligned}$$

But this contradicts the assumption that
 K_g is not degenerate. Thus $m \cap m^\perp$
and \mathfrak{g} is the direct sum of the ideals
 m and m^\perp .

The other direction uses Cartan's criterion
for solvability of a Lie algebra \mathfrak{g} (in
characteristic zero) :

Thm. IV.7 (Cartan's Criterion)

\mathfrak{g} is solvable if $K_{\mathfrak{g}}(\mathfrak{g}, [\mathfrak{g}, \mathfrak{g}]) = 0$.

Now we turn to a property of the adjoint
representation of a semisimple Lie group.

~~namely~~

Let G be a real connected Lie group
with Lie algebra \mathfrak{g} , $\text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$
its adjoint representation. Then $\text{Ad}(G)$
is contained in $\text{Aut}(\mathfrak{g})$ the group of
automorphisms of \mathfrak{g} , which is a closed

subgroup of $GL(g)$. In fact since
 G is connected we have $\text{Ad}(G) \subset (\text{Aut } g)^\circ$.

When G is connected semisimple we
have:

Thm IV.8 If G is connected semisimple
we have $\text{Ad}(G) = (\text{Aut } g)^\circ$.

The proof uses the analogy in the level of
Lie algebras:

Prop. IV.9. If g is semisimple then

$$\text{Der}(g) = \text{ad}(g)$$

in other words every derivation of g
is inner.

Proof: We have the following inclusion of
spaces: $\text{ad}(g) \subset \text{Der } g \subset \text{End } g$.

On $\text{End}(g)$, $(A, B) \mapsto \text{tr}AB$ defines
a non-degenerate symmetric bilinear
form. Its restriction to $\text{ad}(g)$ is
non-degenerate since g is semisimple.

Thus it suffices to show that if
 $D \in \text{Der } g$ is orthogonal to $\text{ad}(g)$ then
, it vanishes.

Now we compute $\forall x, y \in g$:

$$K_g(Dx, y) = \text{tr}(\text{ad}(Dx)\text{ad}(y))$$

$$\begin{aligned} \text{But } \text{ad}(Dx)(z) &= [Dx, z] \\ &= D([x, z]) - [x, Dz] \end{aligned}$$

$$\text{that is, } \text{ad } Dx = [D, \text{ad}(x)].$$

Hence

$$K_g(Dx, y) = \text{tr}([D, \text{ad}(x)]\text{ad}(y))$$

$$\begin{aligned} &= \text{tr} \left(D \text{ad}(x) \text{ad}(y) - \text{ad}(x) D \text{ad}(y) \right) \\ &= \text{tr} \left(D \text{ad}(x) \text{ad}(y) - D \text{ad}(y) \text{ad}(x) \right) \\ &= \text{tr} \left(D [\text{ad}(x), \text{ad}(y)] \right) \\ &= \text{tr} (D \text{ad}([x, y])) = 0 \quad \forall x, y \in \mathfrak{g}. \end{aligned}$$

Hence $\text{B}_g(Dx, y) = 0 \quad \forall x, y \in \mathfrak{g}$

which implies $D = 0$. \blacksquare

Here is a lemma left as exercise:

Lemma IV.10 Let \mathfrak{g} be a real Lie algebra. Then $\text{Aut}(\mathfrak{g})$ is a Lie subgroup of $GL(\mathfrak{g})$ and its Lie algebra coincides with $\text{Der}(\mathfrak{g})$.

The proof of Thm IV.8 is then straightforward. Indeed, we have that

$$\text{Lie } \text{Ad}(G) = \text{ad}(g) = \text{Der}(g) = \text{Lie}(\text{Aut}g)$$

which shows that $\text{Ad}(G) \subset \text{Aut}g$ have the same Lie algebras; since G , hence

$\text{Ad}(G)$ is connected, this implies $\text{Ad}(G) = \text{Aut}g^\circ$.

Now we are in a position to prove

Thm IV.11 If G is a connected Lie group whose Lie algebra has a negative definite Killing form then G is compact.

Prf: Let $\mathfrak{g} = \text{Lie}(G)$. Then G is semi-simple and hence by Thm IV.8

$$\text{Ad}(G) = \text{Aut}(\mathfrak{g})^\circ.$$

Now $\text{Aut}(g) \subset \text{GL}(g)$ is a closed subgroup preserving B_g \Leftrightarrow hence it is compact and so is $\text{Ad}(G)$ ^{automorphism}.

Now we consider $G \times G$ with ~~involution~~

$\sigma(g, h) = (h, g)$ which is an involution whose fixed point subgroup

$$(G \times G)^\sigma = \{(g, g) : g \in G\} := \Delta(G)$$

is the diagonal subgroup of $G \times G$.

Consider the adjoint representation.

$$\text{Ad}_{G \times G} : G \times G \rightarrow \text{GL}(g \otimes g).$$

The image $\text{Ad}_{G \times G}(\Delta(G))$ coincides with

$$\{(A, t) \in \text{GL}(g \otimes g) : A \in \text{Aut}(g)^\circ\}$$

and is hence compact. Thus

$(G \times G, \Delta(G))$ is a riemannian

symmetric pair. We consider the

6×6 - equivariant decomposition

$$\therefore 6 \times 6 /_{\Delta(G)} \longrightarrow G$$

$$(g, h) \cdot \Delta(g) \mapsto g \cdot h^{-1}$$

where the 6×6 action on G is given by

$$(g, h)x = g x h^{-1}.$$

We fix a (6×6) - invariant riemannian

metric on $6 \times 6 /_{\Delta(G)}$; via Δ it gives

a (6×6) - invariant riemannian metric

on G , or simply put, a left or right
invariant riemannian metric in G .

Let $\mathcal{M} = \{(x, -x) : x \in \mathfrak{g}\}$. Then

the geodesics through $e \in \mathcal{M}$ in $6 \times 6 /_{\Delta}$

are the $(\exp tX, \exp(-tX))$ orbit of Δ and under D , we conclude that the geodesics on G through e for the biinvariant metric are given by

$$t \mapsto \exp(2tX), X \in \mathfrak{g}.$$

Now we proceed by contradiction. Assume G is not compact. We use the following general, easy to prove fact:

If (M, g) is a complete riemannian manifold and M is not compact, then given $q \in M$ there exists a geodesic ray:

$$r: [0, \infty) \rightarrow M,$$

$$r(\cdot) = q, d(r(t), r(s)) = t \quad \forall t \geq 0.$$

Thus if G is not compact, denoting
d the biinvariant riemannian distance
on G , there exists $x \in g$ such
that $d(\exp(tx), e) = t \quad \forall t \geq 0$.

Now consider $\begin{aligned} \mathbb{R} &\longrightarrow \text{Ad}(G) \\ t &\mapsto \text{Ad}(\exp tx) \end{aligned}$

whose closure $\bar{T} \subset \text{Ad}(G)$ is a abelian
connected compact subgroup, hence a
torus. By a theorem of Kronecker there
exists $t_n \rightarrow +\infty$ such that

$$\lim_{n \rightarrow \infty} \text{Ad}(\exp 2t_n x) = \text{Id}.$$

Since $\text{Ker Ad} = Z(G)$ there exists $z_n \in Z(G)$ with hence

$z_n \in Z(G)$ with

$$\lim_{n \rightarrow \infty} d(\exp 2t_n x, z_n) = 0.$$

-IV - 29 -

Now let $a \in G$ and consider

$$\gamma(t) = a(\exp 2tX) \bar{a}^{-1}$$

$$\gamma'(t) = \exp tX.$$

Then: since $z_n \in Z(G)$ and d is
biinvariant:

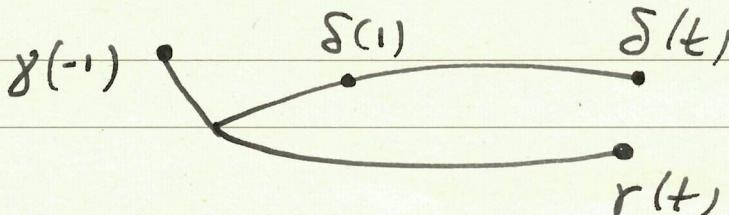
$$\begin{aligned} d(\gamma(t_n), z_n) &= d(a(\exp t_n X) \bar{a}^{-1}, z_n) \\ &= d(\exp t_n X, \bar{a} z_n a) \\ &= d(\gamma(t_n), z_n) \xrightarrow[n \rightarrow \infty]{} 0 \end{aligned}$$

hence

$$\lim_{n \rightarrow \infty} d(\gamma(t_n), \delta(t_n)) = 0$$

Remark γ, δ are two geodesics through e . Assume now $\gamma(t) \neq \delta(t)$ for some

$t > 0$.



- IV - 29 -

then $\delta(0) \neq \gamma(0)$. In particular:

$$d(\gamma(-1), \delta(1)) < 2.$$

Otherwise ~~$\delta(-1), \gamma(1)$~~ the concatenation

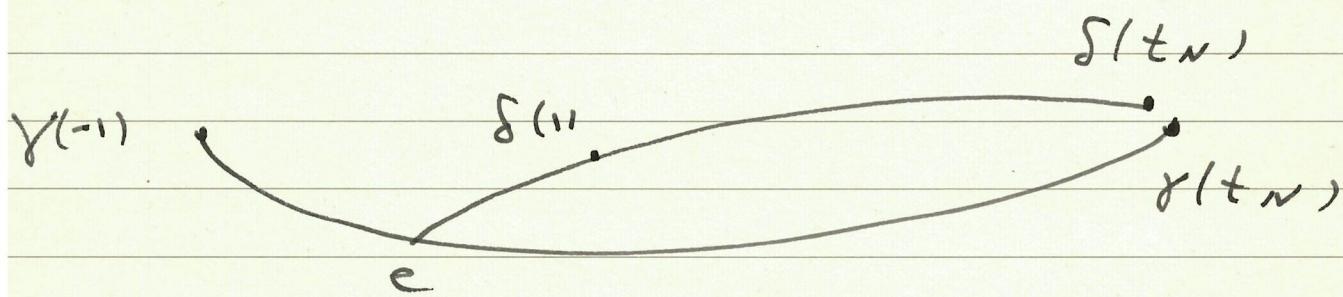
of $\gamma|_{[-1,0]} \cup \delta|_{[0,1]}$ would be a ~~distance~~

length minimizing path hence a geodesic.

Now pick N with

$$d(\gamma(t_N), \delta(t_N)) < 2 - d(\gamma(-1), \delta(1)).$$

And consider the path:



consisting of a length min. geodesic from

$\gamma(-1)$ to $\delta(1)$, the segment $\delta|_{[1, t_N]}$

and a length min. geodesic from $\delta(t_N)$ to
 $\gamma(t_N)$.

- \overrightarrow{IV} -25-

This path has length $< t_{n+1} = d(\gamma_{t-1}, \gamma_{t_n})$

which is a contradiction. Thus

$$f(t) = g(t) \quad \forall t$$

that is $\exp(zt \operatorname{Ad}(a)(x)) = \exp(zt x), \forall t$

hence $\operatorname{Ad}(a)(x) = x \quad \forall a \in A$.

But this implies $\dim Z(g) \geq 1$, contradicting
semisimplicity of g . \square