

## Solutions 5

### 1. Constant sectional curvature

Let  $(M, g)$  be a Riemannian manifold with constant sectional curvature  $\text{sec}(E) = \kappa \in \mathbb{R}$  for all  $E \in G_2(TM)$ . Show that

$$R(X, Y)W = \kappa (g(Y, W)X - g(X, W)Y).$$

*Solution.* As the sectional curvature is constant, we have

$$R(X, Y, X, Y) = \kappa (g(X, X)g(Y, Y) - g(X, Y)g(X, Y))$$

for all  $X, Y \in \Gamma(TM)$ . Consider now the  $(0, 4)$ -tensor  $T$  given by

$$T(V, W, X, Y) := \kappa (g(V, X)g(Y, W) - g(V, Y)g(X, W)).$$

Then the  $(0, 4)$ -tensor  $S := R - T$  has the following symmetry properties:

1.  $S(V, W, X, Y) = -S(V, W, Y, X)$ ,
2.  $S(V, W, X, Y) + S(V, Y, W, X) + S(V, X, Y, W) = 0$ ,
3.  $S(V, W, X, Y) = S(X, Y, V, W)$ ,
4.  $S(X, Y, X, Y) = 0$ .

The first three properties hold for  $R$  and  $T$ , while the last one was already observed above. Our goal is now to show that  $S \equiv 0$ .

For all  $A, B, C, D \in \Gamma(TM)$ , we have by 3. and 4.

$$\begin{aligned} 0 &= S(A, B + D, A, B + D) \\ &= S(A, B, A, B) + S(A, B, A, D) + S(A, D, A, B) + S(A, D, A, D) \\ &= 2S(A, B, A, D) \end{aligned}$$

and

$$\begin{aligned} 0 &= S(A + C, B, A + C, D) \\ &= S(A, B, A, D) + S(A, B, C, D) + S(C, B, A, D) + S(C, B, C, D) \\ &= S(A, B, C, D) + S(A, D, C, B). \end{aligned}$$

Finally, we get

$$\begin{aligned} 3S(V, W, X, Y) &= S(V, W, X, Y) - S(V, Y, X, W) - S(V, W, Y, X) \\ &= S(V, W, X, Y) + S(V, Y, W, X) + S(V, X, Y, W) = 0, \end{aligned}$$

for all  $V, W, X, Y \in \Gamma(TM)$ .

## 2. Ricci curvature

Let  $(M, g)$  be a 3-dimensional Riemannian manifold. Show the following:

- a) The Ricci curvature  $\text{ric}$  uniquely determines the Riemannian curvature tensor  $R$ .
- b) If  $M$  is an Einstein manifold, that is, a Riemannian manifold  $(M, g)$  with  $\text{ric} = kg$  for some  $k \in \mathbb{R}$ , then the sectional curvature  $\text{sec}$  is constant.

*Solution.* a) In the following, let  $e_1, e_2, e_3$  be an orthonormal basis of  $TM_p$ . First, note that  $R_{iijk} = R_{jkii} = 0$  by the symmetry properties of  $R$ .

We denote the components of  $\text{ric}$  by  $R_{ij}$ . Then, for  $\{i, j, k\} = \{1, 2, 3\}$ , we have

$$\begin{aligned}R_{ii} &= R_{iiii} + R_{jiji} + R_{kiki} = R_{ijij} + R_{ikik}, \\R_{ij} &= R_{iiij} + R_{jijj} + R_{kikj} = R_{ikjk}\end{aligned}$$

and therefore, we get

$$\begin{aligned}2R_{ijij} &= R_{ii} + R_{jj} - R_{kk}, \\R_{ikjk} &= R_{ij}.\end{aligned}$$

Observe now, that we can compute all other components of  $R$  by symmetry properties. Hence  $R$  is uniquely determined by  $\text{ric}$ .

b) Let  $e_1, e_2$  be a orthonormal basis of  $E \subset TM_p$  and choose  $e_3$  such that  $e_1, e_2, e_3$  is an orthonormal basis of  $TM_p$ . Then we have

$$2 \text{sec}_p(E) = 2R_{1212} = R_{11} + R_{22} - R_{33} = k + k - k = k$$

and hence  $\text{sec}_p(E) = \frac{k}{2}$ .

### 3. Divergence and Laplacian

Let  $(M, g)$  be a Riemannian manifold with Levi-Civita connection  $D$ . The *divergence*  $\operatorname{div}(Y)$  of a vector field  $Y \in \Gamma(TM)$  is the contraction of the  $(1, 1)$ -tensor field  $DY: X \mapsto D_X Y$  and the *Laplacian*  $\Delta: C^\infty(M) \rightarrow C^\infty(M)$  is defined by  $\Delta f := \operatorname{div}(\operatorname{grad} f)$ . Show that:

- a)  $\operatorname{div}(fY) = Y(f) + f \operatorname{div} Y$ ,
- b)  $\Delta(fg) = f\Delta g + g\Delta f + 2\langle \operatorname{grad} f, \operatorname{grad} g \rangle$ ,
- c) Compute  $\Delta f$  in local coordinates.

*Solution.* a) Let  $p \in M$  and let  $e_1, \dots, e_n$  be an orthonormal basis of  $TM_p$ . Then we have

$$\begin{aligned} \operatorname{div}_p(fY) &= \sum_{i=1}^n \langle D_{e_i}(fY), e_i \rangle \\ &= \sum_{i=1}^n \langle e_i(f)Y_p + f(p)D_{e_i}Y, e_i \rangle \\ &= \sum_{i=1}^n e_i(f) \langle Y_p, e_i \rangle + \sum_{i=1}^n f(p) \langle D_{e_i}Y, e_i \rangle \\ &= Y_p(f) + f(p) \operatorname{div}_p(Y) \\ &= (Y(f) + f \operatorname{div}(Y))(p) \end{aligned}$$

and hence  $\operatorname{div}(fY) = Y(f) + f \operatorname{div} Y$ .

b) First, recall the definition of  $\operatorname{grad} f$  from Exercise Sheet 3, i.e.  $X(f) = \langle \operatorname{grad} f, X \rangle$  and note that

$$\langle \operatorname{grad}(fg), X \rangle = X(fg) = X(f)g + fX(g) = \langle \operatorname{grad}(f)g + f \operatorname{grad}(g), X \rangle,$$

for all  $X \in \Gamma(M)$  and thus  $\operatorname{grad}(fg) = \operatorname{grad}(f)g + f \operatorname{grad}(g)$ .

Therefore, we get

$$\begin{aligned} \Delta(fg) &= \operatorname{div}(\operatorname{grad}(fg)) \\ &= \operatorname{div}(\operatorname{grad}(f)g + f \operatorname{grad}(g)) \\ &= \operatorname{div}(\operatorname{grad} f)g + \operatorname{grad}(f)(g) + f \operatorname{div}(\operatorname{grad}(g)) + \operatorname{grad}(g)(f) \\ &= \Delta(f)g + f\Delta(g) + 2\langle \operatorname{grad} f, \operatorname{grad} g \rangle. \end{aligned}$$

c) In the following, we use Einstein notation. From Exercise Sheet 3, we already know that

$$\begin{aligned}\operatorname{grad} f &= g^{ik} f_i A_k, \\ D_{A_i} Y &= (A_i(Y^k) + Y^j \Gamma_{ij}^k) A_k.\end{aligned}$$

Therefore, we have

$$\operatorname{div}(Y) = A_k(Y^k) + Y^j \Gamma_{kj}^k.$$

Hence, we get

$$\begin{aligned}\Delta f &= \operatorname{div}(\operatorname{grad} f) \\ &= A_k(g^{ik} f_i) + g^{ij} f_i \Gamma_{kj}^k.\end{aligned}$$

With  $G := \det(g_{ij})$ , we can simplify this as follows. We have by the Jacobi formula and the chain rule

$$\Gamma_{kj}^k = \frac{1}{2} g^{kl} A_j(g_{kl}) = \frac{1}{2G} A_j(G) = \frac{1}{\sqrt{G}} A_j(\sqrt{G})$$

and therefore

$$\begin{aligned}\Delta f &= A_j(g^{ij} f_i) + g^{ij} f_i \frac{1}{\sqrt{G}} A_j(\sqrt{G}) \\ &= \frac{1}{\sqrt{G}} A_j(\sqrt{G} g^{ij} f_i).\end{aligned}$$