

## Solutions 6

### 1. Curvature of bi-invariant metrics

Let  $G$  be a Lie group with a bi-invariant metric  $\langle \cdot, \cdot \rangle$  and Riemann curvature tensor  $R$ . Let  $X, Y, V, W \in \Gamma(TG)$  be left-invariant vector fields. Show that

- a)  $R(X, Y)W = \frac{1}{4} [W, [X, Y]]$ .
- b)  $\langle V, R(X, Y)W \rangle = R(V, W, X, Y) = \frac{1}{4} \langle [V, W], [X, Y] \rangle$ ,  
 in particular the sectional curvature is non-negative.

*Solution.* a) Let  $X, Y, W \in \Gamma(TG)$  be left-invariant vector fields. From Exercise 3 of Sheet 3 we know that  $D_X Y = \frac{1}{2} [X, Y]$  and Exercise 1b) of Sheet 2 implies that  $D_X Y$  is left-invariant as well. Analogous considerations hold for the other tuples of vector fields involved. Hence we compute

$$\begin{aligned} R(X, Y)W &= D_X D_Y W - D_Y D_X W - D_{[X, Y]} W \\ &= \frac{1}{2} D_X [Y, W] - \frac{1}{2} D_Y [X, W] - \frac{1}{2} [[X, Y], W] \\ &= \frac{1}{4} [X, [Y, W]] - \frac{1}{4} [Y, [X, W]] + \frac{1}{2} [W, [X, Y]] \\ &= \frac{1}{4} [X, [Y, W]] + \frac{1}{4} [Y, [W, X]] + \frac{1}{2} [W, [X, Y]]. \end{aligned}$$

From the Jacobi identity we obtain  $[X, [Y, W]] + [Y, [W, X]] = -[W, [X, Y]]$ , which implies the result.

b) From a) and Exercise 3 of Sheet 3 we get  $R(X, Y)W = \frac{1}{2} D_W [X, Y]$ , so we compute

$$\begin{aligned} \langle V, R(X, Y)W \rangle &= \frac{1}{2} \langle V, D_W [X, Y] \rangle \\ &= \frac{1}{2} W \langle V, [X, Y] \rangle - \frac{1}{2} \langle D_W V, [X, Y] \rangle \\ &= -\frac{1}{4} \langle [W, V], [X, Y] \rangle \\ &= \frac{1}{4} \langle [V, W], [X, Y] \rangle, \end{aligned}$$

where we have used that  $\langle V, [X, Y] \rangle$  is constant and  $D$  is compatible with  $\langle \cdot, \cdot \rangle$ .

Now, let  $p \in G$ ,  $E \subset TG_p$  a 2-dimensional subspace and  $u, v$  an orthonormal basis for  $E$ . Denote by  $U, V \in \Gamma(TG)$  the left-invariant vector fields with  $U_p = u$  and  $V_p = v$ , respectively. Then

$$\sec_p(E) = R_p(u, v, u, v) = \frac{1}{4} \langle [U, V]_p, [U, V]_p \rangle \geq 0.$$

## 2. Codazzi equation

Let  $M \subset \bar{M}$  be a submanifold of the Riemannian manifold  $(\bar{M}, \bar{g})$ . For the second fundamental form  $h$  of  $M$ , we define

$$(D_X^\perp h)(Y, W) := (\bar{D}_X(h(Y, W)))^\perp - h(D_X Y, W) - h(Y, D_X W),$$

where  $W, X, Y \in \Gamma(TM)$ . Show that the Codazzi equation

$$(\bar{R}(X, Y)W)^\perp = (D_X^\perp h)(Y, W) - (D_Y^\perp h)(X, W)$$

holds for all  $W, X, Y \in \Gamma(TM)$ .

*Solution.* As  $\bar{D}_Z W = D_Z W + h(Z, W)$  for  $W, Z \in \Gamma(TM)$ , we get

$$\begin{aligned} \bar{R}(X, Y)W &= \bar{D}_X \bar{D}_Y W - \bar{D}_Y \bar{D}_X W - \bar{D}_{[X, Y]} W \\ &= \bar{D}_X (D_Y W + h(Y, W)) - \bar{D}_Y (D_X W + h(X, W)) \\ &\quad - (D_{[X, Y]} W + h([X, Y], W)) \\ &= D_X D_Y W + h(X, D_Y W) + \bar{D}_X (h(Y, W)) \\ &\quad - D_Y D_X W - h(Y, D_X W) - \bar{D}_Y (h(X, W)) \\ &\quad - D_{[X, Y]} W - h(D_X Y - D_Y X, W) \\ &= R(X, Y)W \\ &\quad + \bar{D}_X (h(Y, W)) - h(D_X Y, W) - h(Y, D_X W) \\ &\quad - \bar{D}_Y (h(X, W)) + h(D_Y X, W) + h(X, D_Y W). \end{aligned}$$

Note that we used that  $D$  is torsion free, i.e.  $[X, Y] = D_X Y - D_Y X$ . Now, taking the normal part, we conclude that the Codazzi equation

$$(\bar{R}(X, Y)W)^\perp = (D_X^\perp h)(Y, W) - (D_Y^\perp h)(X, W)$$

holds.

### 3. Sectional curvature of submanifolds

Let  $(\overline{M}, \overline{g})$  be a Riemannian manifold with sectional curvature  $\overline{\text{sec}}$ . Let  $p \in \overline{M}$  and  $L \subset T\overline{M}_p$  an  $m$ -dimensional linear subspace.

- a) Prove that there is some  $r > 0$  such that for the open ball  $B_r(0) \subset T\overline{M}_p$ , the set  $M := \exp_p(L \cap B_r(0))$  is an  $m$ -dimensional submanifold of  $\overline{M}$ .
- b) Let  $g$  be the induced metric on  $M$  and let  $\text{sec}$  be the sectional curvature of  $M$ . Show that for  $E \subset TM_p$ , we have  $\text{sec}_p(E) = \overline{\text{sec}}_p(E)$  and if  $L$  is a 2-dimensional subspace, then  $\text{sec} \leq \overline{\text{sec}}$  on  $M$ .

*Solution.* a) First, we know that there is some  $r > 0$  such that the restriction of the exponential map to  $B_r(0)$ , i.e.  $\exp_p|_{B_r(0)}: B_r(0) \rightarrow \exp_p(B_r(0))$ , is a diffeomorphism. Furthermore, note that  $L \cap B_r(0)$  is an  $m$ -dimensional submanifold of  $B_r(0)$  and hence  $M = \exp_p(L \cap B_r(0))$  is an  $m$ -dimensional submanifold of  $\exp_p(B_r(0))$ . Finally, as  $\exp_p(B_r(0))$  is open in  $\overline{M}$ , it follows that  $M$  is a submanifold of  $\overline{M}$  as well.

b) Let  $u, v \in E$  be an orthonormal basis of  $E \subset TM_p$ . Then we have

$$\begin{aligned} \text{sec}_p(E) &= R_p(u, v, u, v) \\ &= \overline{R}_p(u, v, u, v) + \overline{g}_p(h_p(u, u), h_p(v, v)) - \overline{g}_p(h_p(u, v), h_p(u, v)) \\ &= \overline{\text{sec}}_p(E) + \overline{g}_p(h_p(u, u), h_p(v, v)) - \overline{g}_p(h_p(u, v), h_p(u, v)) \end{aligned}$$

We now prove that  $h_p(u, u) = h_p(v, v) = h_p(u, v) = 0$ . Extend  $u, v$  to an orthonormal basis  $e_1 = u, e_2 = v, e_3, \dots, e_m$  of  $T\overline{M}_p$ . Then this basis induces normal coordinates on  $\overline{M}$ . Hence, we have  $\Gamma_{ij}^k(p) = 0$  and thus  $(\overline{D}_{e_i} e_j)_p = 0$  for all  $i, j$ . In particular this implies that  $h_p(u, u) = h_p(v, v) = h_p(u, v) = 0$  as claimed.

Assume now that  $L \subset T\overline{M}_p$  is 2-dimensional and let  $q := \exp_p(x) \in M$  for  $x \in L \cap B_r(0)$ . By the above, we may assume that  $x \neq 0$ .

Define  $w := \frac{x}{|x|} \in TM_p$  and let  $c_w$  be the unique geodesic with  $c(0) = p$  and  $\dot{c}(0) = w$ . Then we have  $q = c_w(|x|)$  and  $u := \dot{c}_w(|x|) \in TM_q$  with  $|u| = 1$ . Furthermore, by Lemma 2.17, we get

$$h_q(u, u) = \left( \overline{D}_{\frac{d}{dt}} \dot{c}_w \Big|_{t=|x|} \right)^\perp = 0.$$

To compute the sectional curvature of  $E = TM_q$ , we extend  $u$  to an orthonormal basis  $u, v$  of  $E$  and get

$$\text{sec}_q(E) = R_q(u, v, u, v) = \overline{R}_q(u, v, u, v) - |h_q(u, v)|^2 \leq \overline{\text{sec}}_q(E)$$

as desired.