Introduction to Mathematical Finance Solution sheet 11

Solution 11.1 The dynamic programming principle (Proposition III.2.5) indicates that we should solve

$$\sigma_k(v_k) = \operatorname{ess\,sup}_{\pi_k,\gamma_k} \left(U_c(\gamma_k v_k) + E\left[\sigma_{k+1}\left(v_k(1 + \pi_k \cdot (R_{k+1} - 1) - \gamma_k)\right) |\mathcal{F}_k\right] \right)$$

by backwards induction to get candidate optimal solution.

- First note that $\sigma_T(v_T) = U_w(v_T) = \log(v_T)$
- Consider k = T 1:

$$\begin{aligned} \sigma_{T-1}(v_{T-1}) &= \operatorname{ess\,sup}_{\pi_{T-1},\gamma_{T-1}} \left(\log(\gamma_{T-1}v_{T-1}) + E\left[\sigma_T \left(v_{T-1}(1 + \pi_{T-1} \cdot (R_T - 1) - \gamma_{T-1}) \right) | \mathcal{F}_{T-1} \right] \right) \\ &= \operatorname{ess\,sup}_{\pi_{T-1},\gamma_{T-1}} \left(\log(\gamma_{T-1}) + \log(v_{T-1}) + E\left[\log(v_{T-1}) - \gamma_{T-1} \right] | \mathcal{F}_{T-1} \right] \right) \\ &= 2\log(v_{T-1}) + \operatorname{ess\,sup}_{\pi_{T-1},\gamma_{T-1}} \left(\log(\gamma_{T-1}) + E\left[\log((1 + \pi_{T-1} \cdot (R_T - 1) - \gamma_{T-1}) | \mathcal{F}_{T-1} \right] \right) \\ &= 2\log(v_{T-1}) + \\ &= 2\log(v_{T-1}) + \\ &= 2\log(v_{T-1}) + C_{T-1} \end{aligned}$$

where

$$C_{T-1} := \sup_{\pi,\gamma} \left(\log(\gamma) + E \left[\log(1 + \pi \cdot (R-1) - \gamma) \right] \right)$$

In the fourth equality above, we have used that R_T is independent of \mathcal{F}_{T-1} and π_{T-1} and γ_{T-1} are \mathcal{F}_{T-1} measurable. The random variable R appearing in the definition of C_{T-1} is distributed identically as the i.i.d random variables R_k .

• For a general $0 \le k \le T - 1$, if $\sigma_{k+1}(v_{k+1}) = (T - (k+1) + 1)\log(v_{k+1}) + \sum_{j=k+1}^{T-1} C_j$ for some constants C_j , then:

$$\begin{split} \sigma_{k}(v_{k}) &= \operatorname{ess\,sup}_{\pi_{k},\gamma_{k}} \left(\log(\gamma_{k}v_{k}) + E\left[\sigma_{k+1}\left(v_{k}(1+\pi_{k}\cdot(R_{k+1}-1)-\gamma_{k})\right)|\mathcal{F}_{k}\right] \right) \\ &= \operatorname{ess\,sup}_{\pi_{k},\gamma_{k}} \left(\log(\gamma_{k}) + \log(v_{k}) + \\ & E\left[(T-(k+1)+1)\{\log(v_{k}) + \log\left(1+\pi_{k}\cdot(R_{k+1}-1)-\gamma_{k}\right)\} + \sum_{j=k+1}^{T-1}C_{j}|\mathcal{F}_{k}\right] \right) \\ &= (T-k+1)\log(v_{k}) + \sum_{j=k+1}^{T-1}C_{j} \\ &\quad + \operatorname{ess\,sup}_{\pi_{k},\gamma_{k}} \left(\log(\gamma_{k}) + (T-k)E\left[\log((1+\pi_{k}\cdot(R_{k+1}-1)-\gamma_{k})|\mathcal{F}_{k}\right] \right) \\ &= (T-k+1)\log(v_{k}) + \sum_{j=k+1}^{T-1}C_{j} \\ &\quad \operatorname{ess\,sup}_{\pi_{k},\gamma_{k}} \left(\log(\gamma_{k}) + (T-k)E\left[\log((1+\pi\cdot(R_{k+1}-1)-\gamma)\right]_{|\pi=\pi_{k},\gamma=\gamma_{k}} \right) \\ &= (T-k+1)\log(v_{k}) + \sum_{j=k}^{T-1}C_{j} \\ &\quad \operatorname{ess\,sup}_{\pi_{k},\gamma_{k}} \left(\log(\gamma_{k}) + (T-k)E\left[\log((1+\pi\cdot(R_{k+1}-1)-\gamma)\right]_{|\pi=\pi_{k},\gamma=\gamma_{k}} \right) \\ &= (T-k+1)\log(v_{k}) + \sum_{j=k}^{T-1}C_{j} \end{split}$$

where

$$C_k := \sup_{\pi,\gamma} \left(\log(\gamma) + (T-k)E\left[\log(1 + \pi \cdot (R-1) - \gamma) \right] \right)$$

This proves by induction that for all $0 \le k \le T - 1$,

$$\sigma_k(v_k) = (T - k + 1)\log(v_k) + \sum_{j=k}^{T-1} C_j$$

Assume the constants C_k are finite and that there exist maximisers (π_k^*, γ_k^*) (constrained to statisfy $\gamma_k^* \geq 0$ and $1^T \pi_k^* = 1$ for all k). We then expect by the dynamic programming principle (π_k^*, γ_k^*) to be optimal for the original static utility optimization problem (??). Indeed the dynamic programming principle (Proposition III.2.5) tells us that for an optimal solution of (??), $\sigma_k(v_k)$ computed above is equal to the optimal remaining utility at time k. In particular,

$$E[\sigma_0(v_0)] = \mathcal{U}^*$$

is the optimal value of (??). To find the optimal strategy achieving this value \mathcal{U}^* , we first calculate backwards $\sigma_k(v_k)$ and the corresponding optimizers $\pi_k^*(v_k)$ and $\gamma_k^*(v_k)$. In general this backward step gives the optimal strategy as a function of the current wealth v_k . To get the optimal strategy we then need to iterate forward starting from the initial wealth v_0 : $W_0 = v_0$ and if W_k is known, set

$$\pi_{k}^{*} = \pi_{k}^{*}(W_{k})$$

$$\gamma_{k}^{*} = \gamma_{k}^{*}(W_{k})$$

$$W_{k+1} = W_{k} (1 + \pi_{k}^{*} \cdot (R_{k+1} - 1) - \gamma_{k}^{*})$$

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However, calculations simplify considerably in our setup, since the optimal γ_k^* and π_k^* do NOT depend on the current wealth v_k (see Remark below). **Remarks**

- 1. Note that the dynamic programming principle only gives a *candidate* solution to (??). To confirm the optimality, one should check the sufficient condition of the Martingale Optimality Principle, i.e. show that $J(\vartheta^*, c^*)$ is a true martingale (where recall that $c_k^* = \gamma_k^* W_k^{v_0, \pi^*, \gamma^*}$ and $\vartheta_{k+1}^{*,l} = \frac{\pi_k^{*,l} W_k^{v_0, \pi^*, \gamma^*}}{X_k^l}$).
- 2. The (candidate) optimal proportions γ_k^*, π_k^* are deterministic. But there is still trading and stochastic consumption involved because

$$c_k^* = \gamma_k^* W_k^{v_0, \pi^*, \gamma^*}$$

and

$$\vartheta_{k+1}^{*,l} = \frac{\pi_k^{*,l} W_k^{v_0,\pi^*,\gamma^*}}{X_k^l}$$

still depend on the randomly evolving wealth and asset values.

Solution 11.2

(a) First note by induction that X_n is $\sigma(X_0, \epsilon_0, ..., \epsilon_{n-1})$ measurable. Indeed it is clearly true for n = 0 and by induction, if X_n is $\sigma(X_0, \epsilon_0, ..., \epsilon_{n-1})$ measurable, then $X_n = f_n(X_0, \epsilon_0, ..., \epsilon_{n-1})$ for a certain measurable function f_n and so

$$X_{n+1} = \phi_n(X_n, \epsilon_n) = \phi_n(f_n(X_0, \epsilon_0, \dots, \epsilon_{n-1}), \epsilon_n)$$

is $\sigma(X_0, \epsilon_0, \ldots, \epsilon_n)$ measurable.

Since by assumption, ϵ_n is independent of $\sigma(X_0, \epsilon_0, \ldots, \epsilon_{n-1})$, we get by the above result that ϵ_n is independent of $\sigma(X_0, \ldots, X_n)$. Hence

$$E\left[\mathbb{1}_{\{X_{n+1}\in A\}}|\sigma(X_0,\ldots,X_n)\right] = E\left[\mathbb{1}_{\{\phi_n(X_n,\epsilon_n)\in A\}}|\sigma(X_0,\ldots,X_n)\right]$$
$$= P_n(X_n,A)$$

where in the last equality we used the following proposition: if X, Y are random variables such that X is \mathcal{G} measurable with respect to some sigma algebra \mathcal{G} and Y is independent of \mathcal{G} , then

$$E[f(X,Y)|\mathcal{G}] = E[f(z,Y)]\Big|_{z=X}$$

(b) The equality holds for $f = \mathbb{1}_A$ for any $A \in \mathcal{E}$ by the previous question. By linearity it also holds for simple functions, i.e functions for the form $f = \sum_{k=1}^{n} a_k \mathbb{1}_{A_k}$. Finally it also holds for positive measurable functions since every such functions is the increasing limit of a sequence of simple functions.

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Solution 11.3

(a) The proof is very similar to the solution of the question 11.1.a). Again by induction one can see that X_n and U_n are $\sigma(X_0, \epsilon_0, ..., \epsilon_{n-1})$ measurable. Indeed it is again clearly true for n = 0 and by induction, if X_n and U_n are $\sigma(X_0, \epsilon_0, ..., \epsilon_{n-1})$ measurable, then there exists some measurable functions f_n and g_n such that $X_n = f_n(X_0, \epsilon_0, ..., \epsilon_{n-1})$ and $U_n = g_n(X_0, \epsilon_1, ..., \epsilon_{n-1})$

$$X_{n+1} = \phi_n(X_n, U_n, \epsilon_n) = \phi_n(f_n(X_0, \epsilon_0, ..., \epsilon_{n-1}), g_n(X_0, \epsilon_0, ..., \epsilon_{n-1}), \epsilon_n)$$

is $\sigma(X_0, \epsilon_0, \ldots, \epsilon_n)$ measurable and thus so is U_{n+1} since U is adapted to the natural filtration of X.

Since by assumption, ϵ_n is independent of $\sigma(X_0, \epsilon_0, \ldots, \epsilon_{n-1})$, we get by the above result that ϵ_n is independent of $\sigma(X_0, \ldots, X_n)$. Hence we have (using the same proposition as in question 11.1.a)),

$$E\left[\mathbbm{1}_{\{X_{n+1}\in A\}}|\sigma(X_0,\ldots,X_n)\right] = E\left[\mathbbm{1}_{\{\phi_n(X_n,U_n,\epsilon_n)\in A\}}|\sigma(X_0,\ldots,X_n)\right]$$
$$= P_n^{(U_n)}(X_n,A)$$

(b) The solution follows the same ideas as question 11.1.b). The equality holds for $f = \mathbb{1}_A$ for any $A \in \mathcal{E}$ by the previous question. By linearity it also holds for simple functions, i.e functions for the form $f = \sum_{k=1}^{n} a_k \mathbb{1}_{A_k}$. Finally it also holds for positive measurable function since every such functions is the increasing limit of a sequence of simple functions.

Solution 11.4 As suggested by the hint, we use bakward induction for both questions.

(a) It is clearly true for n = N:

$$O_N(X_N) = \gamma(X_N) = E_{x_0}^{\eta^{min}} \left[\gamma(X_N) | \sigma(X_0, \dots, X_N) \right]$$

Now we suppose that the desired property holds for n + 1 and show that it

still holds for n

$$\begin{aligned} O_n(X_n) &= c_n(X_n, U_n^{(min)}(X_n)) + (P_n^{(U_n^{(min)}(X_n))}O_{n+1})(X_n) \quad (by \ definition) \\ &= c_n(X_n, U_n^{(min)}(X_n)) + E_{x_0}^{\eta^{min}} \left[O_{n+1}(X_{n+1}) | \sigma(X_0, \dots, X_n)\right] \\ (using \ the \ result \ from \ question \ 2) \\ &= c_n(X_n, U_n^{(min)}(X_n)) \\ &+ E_{x_0}^{\eta^{min}} \left[E_{x_0}^{\eta^{min}} \left[\sum_{k=n+1}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_{n+1}) \right] | \sigma(X_0, \dots, X_n) \right] \\ (by \ induction \ hypotheses) \end{aligned}$$

$$= c_n(X_n, U_n^{(min)}(X_n))$$

$$+ E_{x_0}^{\eta^{min}} \left[\sum_{k=n+1}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_n) \right]$$

$$(by \ tower \ property)$$

$$= E_{x_0}^{\eta^{min}} \left[\sum_{k=n}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_n) \right]$$

(b) Fix a strategy η corresponding to controls U. The claimed result is clearly true for n = N:

$$O_N(X_N) = \gamma(X_N) = E_{x_0}^{\eta} \left[\gamma(X_N) | \sigma(X_0, \dots, X_N) \right]$$

Now we suppose that the desired property holds for n + 1 and show that it

still holds for \boldsymbol{n}

$$\begin{split} O_n(X_n) &= c_n(X_n, U_n^{(min)}(X_n)) + (P_n^{(U_n^{(min)}(X_n))}O_{n+1})(X_n) \quad (by \ definition) \\ &\leq c_n(X_n, U_n(X_n)) + (P_n^{(U_n(X_n))}O_{n+1})(X_n) \quad (by \ definition \ of \ optimal \ strategy) \\ &= c_n(X_n, U_n(X_n)) + E_{x_0}^{\eta} \left[O_{n+1}(X_{n+1}) | \sigma(X_0, \dots, X_n)\right] \\ & (using \ the \ result \ from \ question \ 3) \\ &\leq c_n(X_n, U_n(X_n)) \\ & + E_{x_0}^{\eta} \left[E_{x_0}^{\eta} \left[\sum_{k=n+1}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_{n+1}) \right] | \sigma(X_0, \dots, X_n) \right] \\ & (by \ induction \ hypotheses \ + \ result \ from \ question \ (a)) \\ &= c_n(X_n, U_n(X_n)) \end{split}$$

$$+ E_{x_0}^{\eta} \left[\sum_{k=n+1}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_n) \right]$$

(by tower property)

$$= E_{x_0}^{\eta} \left[\sum_{k=n}^{N-1} c_k(X_k, U_k) + \gamma(X_N) | \sigma(X_0, \dots, X_n) \right]$$