

Lecture

12 Mai 2021



Last week (\mathfrak{g}, Θ) CSA non-opt type
 $\langle x, r \rangle := -B_{\mathfrak{g}}(x, \Theta(r)) \quad \forall x, r \in \mathfrak{g}$
 $\text{by } \alpha \in \text{max. Abelian, } \alpha \in \alpha^* \Rightarrow$
root space associated to a root α of \mathfrak{g} in \mathfrak{g}
 $\mathfrak{g}_\alpha := \{x \in \mathfrak{g} : \text{ad}_{\mathfrak{g}}(\text{H})x = \alpha(\text{H})x + \text{H} \cdot \alpha\}$
 $\Rightarrow \mathfrak{g} = \mathfrak{g}_0 \oplus \sum_{\alpha \in \Sigma} \mathfrak{g}_\alpha \quad \text{orthog. w.r.t. } \langle \cdot, \cdot \rangle$

Three reasons to study root spaces / systems:

- Classif. of complex s.s. Lie algs.
- Study b.d. repr. of S.L.-gps.
- Study geom. properties of RSS

Recall $x \in F$ regular if $\text{Cent}_F(x) \cap F$ Abelian. If $x \in DC \Rightarrow DC \subset \text{Cent}_F(x) \cap F$
 $\Rightarrow DC$ max. ab. $\Leftrightarrow \exists x \in DC$ s.t. $DC = \text{Cent}_F(x) \cap F$.

Lemma III-14 A vector $\alpha \in \mathcal{O} \setminus \mathcal{E}_0 3$ is regular iff $\alpha(H) \neq 0 \vee \alpha \in \mathcal{Z}$

Corollary III.15 $\Omega_{reg} = \Omega \setminus \bigcup_{\alpha \in \Sigma} \text{ker } \alpha$

Set of regular elements in Ω .

Pf (\Rightarrow) $H \in \mathfrak{X}$ regular \Rightarrow
 $\mathfrak{X} = \text{Centr}_g(H) \cap \mathbb{P}$ and suppose
 $\exists \alpha \in \Sigma$ s.t. $\alpha(H) = 0$. Let $X \in \mathfrak{X}_\alpha$:
 $X = X_k + X_p$, $X_k = X + \Theta(X)$, $X_p = X - \Theta(X)$
 $\Rightarrow \forall A \in \mathfrak{X} \quad \text{ad}_g(A)(X) = \alpha(A)X$
 $\text{ad}_g(A)(X_k + X_p) = \alpha(A)(X_k + X_p)$
 $\frac{\alpha(A)}{A} \in \mathbb{P}$ $\frac{X_p}{X} \in \mathbb{P}$ since $\{A, X\} \subset \mathbb{P}$
 $\{A, X_p\} \subset \mathbb{P}$ } \Rightarrow
 $\Rightarrow \text{ad}(A)X_p = \alpha(A)X_k \quad \forall A \in \mathfrak{X}$
 If $A = H$, since $\alpha(H) = 0 \Rightarrow$
 $\Rightarrow \text{ad}(H)X_p = 0 \Rightarrow X_p \in \text{Centr}_g(H) \cap \mathbb{P}$
 $\Rightarrow 0 = \text{ad}(A)X_p = \alpha(A)X_k \quad \forall A \in \mathfrak{X}$
 But $\alpha \in \Sigma$, that is $\alpha \neq 0 \Rightarrow X_k = 0$
 $\Rightarrow X = X_p \in \mathfrak{X} \Leftrightarrow \mathfrak{X}_\alpha \subset \mathfrak{X} \subset \mathfrak{I}_0$ ↴
III.13
 (\Leftarrow) Assume $\alpha(H) \neq 0 \quad \forall \alpha \in \Sigma$
 and that $\text{Centr}_g(H) \cap \mathbb{P}$ not Abelian.

Defn Let \mathfrak{t}_reg be max. Abelian.
 A connected component of
 \mathfrak{t}_reg is called a **Weyl chamber** in \mathfrak{t}_reg .

Fact A Weyl chamber can also
 be described as an equiv. class,
 where $h_1 \sim h_2 \Leftrightarrow \alpha(h_1)$ and
 $\alpha(h_2)$ have
 the same sign
 $\forall \alpha \in \Sigma$.

Ex. $SL(3, \mathbb{R})$

singular vectors

 $\alpha^\perp = \ker \alpha$
 $\beta^\perp = \ker \beta$
 $(\alpha + \beta)^\perp = \ker(\alpha + \beta)$

$\alpha^* \rightarrow \alpha$ where $\alpha(H) = \text{Bij}(H_1, H_\alpha)$
 $\alpha \rightarrow H_\alpha$ H_α is a root vector

Ex. $(\mathfrak{sl}(n,\mathbb{R}), \Theta)$, $\Theta(x) = -x^t$.

E_{ij} := elem. matrix $= \begin{cases} 1 & \text{in } (i,j) \\ 0 & \text{otherwise} \end{cases}$

$H_j := E_{jj} - E_{j+1,j+1} \Rightarrow \{E_{ij}, i \neq j, H_j, j=1, \dots, n\}$

is a basis of $\mathfrak{sl}(n,\mathbb{R})$

Ex. $n=2$ $e_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $e_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

\mathfrak{H} max. Ab. $\Rightarrow \mathfrak{H} = \{\text{diag}(t_1, \dots, t_n) : \sum t_i = 0, t_i \in \mathbb{R}\}$

$\forall h \in \mathfrak{H}$, $h = \text{diag}(t_1, \dots, t_n) \Rightarrow$

$$\Rightarrow \text{ad}(h) E_{ij} = (t_i - t_j) E_{ij} \quad \left\{ \begin{array}{l} + i \neq j \\ \text{ad}(h) H_j = 0 \end{array} \right.$$

$\Rightarrow \exists n(n-1)$ non-zero roots

$$\alpha_{ij}(A) := A_{ii} - A_{jj}$$

and $n(n-1)$ one-dim. root spaces,

$$E_{ij} := \frac{1}{\alpha_{ij}} E_{ij} \Rightarrow \mathfrak{sl}(n,\mathbb{R}) = \mathfrak{H} \oplus \sum_{i \neq j} \mathbb{R} E_{ij}$$

Claim \exists 1-1 corr. between Weyl chambers and elements in S_n

Recall $\mathfrak{sl}(2,\mathbb{R}) = \text{span} \left\{ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\}$

$$\begin{aligned} [e_+, e_-] &= h \\ [h, e_+] &= 2e_+ \\ [h, e_-] &= -2e_- \end{aligned}$$

Lemma III.16 (\mathfrak{H}, Θ) OSLA of non-opt type, \mathfrak{H} max. Abelian.

If $\alpha \in \Sigma$ and $x \in \mathfrak{H}_\alpha$. Let x_α be the unique positive multiple of x such that $\langle x_\alpha, x_\alpha \rangle = \frac{2}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)}$.

$$\text{let } y_\alpha := -\Theta(x_\alpha) - h_\alpha$$

$$h_\alpha := \frac{2H_\alpha}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} \Rightarrow$$

$$[x_\alpha, y_\alpha] = h_\alpha, [h_\alpha, x_\alpha] = 2x_\alpha, [h_\alpha, y_\alpha] = -2y_\alpha$$

Corollary III.17 Given $\alpha \in \Sigma$, $x \in \mathfrak{H}_\alpha$ and $x_\alpha, y_\alpha, h_\alpha$ as above \Rightarrow

$$\begin{aligned} \mathfrak{sl}(2,\mathbb{R}) &\longrightarrow \mathfrak{H} \\ e_+ &\longmapsto x_\alpha \\ e_- &\longmapsto y_\alpha \\ h &\longmapsto h_\alpha \end{aligned}$$

is an injective Lie algebra homomorphism with image

$$\begin{aligned} A &= \text{diag}(A_{11}, \dots, A_{nn}) & \lambda_i \neq \lambda_j \\ B &= \text{diag}(B_{11}, \dots, B_{nn}) & \mu_i \neq \mu_j \end{aligned} \quad \left. \begin{array}{l} A, B \\ \text{are} \end{array} \right\} \text{w.r.t.}$$

$\exists! \delta \in S_n$ s.t. $\lambda_{\delta(i)} > \dots > \lambda_{\delta(n)}$
and $\tau \in S_n$ s.t. $\mu_{\tau(i)} > \dots > \mu_{\tau(n)}$
 A, B are in the same weyl chambers $\Leftrightarrow (\lambda_i - \lambda_j)(\mu_i - \mu_j) > 0$
 $\forall i \neq j$.

One can show that $\delta = \tau \Rightarrow$

$$\Rightarrow \mathfrak{H}^+ := \{\text{diag}(t_1, \dots, t_n) : t_1 > \dots > t_n\}$$

Theorem III.12 $\mathfrak{H} \subset \mathfrak{H}$ max. Ab. Then Σ

is a root system, that is

- (1) Σ spans \mathfrak{H}^*
- (2) $\forall \alpha, \beta \in \Sigma \Rightarrow \beta - \frac{2B_{\mathfrak{H}}(H_\alpha, H_\beta)}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} \in \Sigma$
- (3) $\frac{2B_{\mathfrak{H}}(H_\alpha, H_\beta)}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} \in \mathbb{Z}$.

$$\text{span}\{x_\alpha, y_\alpha, h_\alpha\} =: \mathfrak{sl}(2,\mathbb{R})_x \subset \mathfrak{H}.$$

Rk $x_\alpha \in \mathfrak{H}_\alpha$, $y_\alpha \in \mathfrak{H}_{-\alpha}$, $h_\alpha \in \mathfrak{H}$ cf

Pf of Lemma III.16

$$\begin{aligned} h_\alpha \in \mathfrak{H}, x_\alpha \in \mathfrak{H}_\alpha &\Rightarrow \\ [h_\alpha, x_\alpha] &= \alpha(h_\alpha)x_\alpha. \text{ By defn. of } h_\alpha \\ \Rightarrow \alpha(h_\alpha) &= \frac{2\alpha(H_\alpha)}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} = \\ &= \frac{2B_{\mathfrak{H}}(H_\alpha, H_\alpha)}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} = 2 \end{aligned}$$

Same for $[h_\alpha, y_\alpha] = -2y_\alpha$.

To show that $[x_\alpha, y_\alpha] = h_\alpha$:

$$[x_\alpha, y_\alpha] \stackrel{\text{def}}{=} [x_\alpha, -\Theta(x_\alpha)] = -[(x_\alpha, \Theta(x_\alpha))]$$

$$h_\alpha = \frac{2H_\alpha}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} \stackrel{\text{defn}}{=} \frac{\langle x_\alpha, x_\alpha \rangle H_\alpha}{B_{\mathfrak{H}}(H_\alpha, H_\alpha)} = x_\alpha$$

It will be enough to show:

Lemma III.18 Let $\alpha \in \Sigma$, $x \in \mathfrak{H}_\alpha \Rightarrow$

$$\Rightarrow [x, \Theta(x)] = -\langle x, x \rangle H_\alpha$$

$$\text{Pf} - \langle X, X \rangle + h_\alpha \in \mathcal{D}$$

First step: $[X, \Theta(X)] \in \mathcal{D} = \mathcal{Y}_0 \cap \mathcal{P}$ ✓

- $X \in \mathcal{Y}_\alpha \Rightarrow \Theta(X) \in \mathcal{Y}_{-\alpha} \Rightarrow$
 $\Rightarrow [X, \Theta(X)] \in \mathcal{Y}_{\alpha-\alpha} = \mathcal{Y}_0$
- $\Theta([X, \Theta(X)]) = [\Theta(X), X] =$
 $= -[X, \Theta(X)] \in \mathcal{P}$.

Second step $-\langle X, X \rangle + h_\alpha =$

$$= \text{B}_{\mathcal{Y}}(X, \Theta(X)) + h_\alpha$$

$$1+2 \Rightarrow [X, \Theta(X)] - \text{B}_{\mathcal{Y}}(X, \Theta(X)) \in \mathcal{D}$$

Third step is orthogonal to \mathcal{D}

w.r.t. the inner product $\langle \cdot, \cdot \rangle \Rightarrow$
 \Rightarrow it is zero.

let $Y \in \mathcal{D} \subset \mathcal{P}$

$$\langle [X, \Theta(X)], Y \rangle = -\text{B}_{\mathcal{Y}}([X, \Theta(X)], \Theta(Y))$$

Remark $\alpha(R_\alpha) = 2$

$$\alpha(H) = \text{B}_{\mathcal{Y}}(H, H_\alpha)$$

Thm III.19(1) Every f.d. rep. of $\mathfrak{sl}(2, \mathbb{R})$ is a direct sum of irreduc. repns.

(2) Every f.d. repn. of $\mathfrak{sl}(2, \mathbb{R})$ is classified, up to isom., by its dimension. If $\rho: \mathfrak{sl}(2, \mathbb{R}) \rightarrow \text{GL}(W)$ is an irred. repn. $\Rightarrow \rho(h)$ is diagonalizable with eigenvalues

$$\{(\dim V - 1) - 2n : n = 0, \dots, \dim V - 1\}$$

$$= \{1 - \dim V, 3 - \dim V, \dots, -3 + \dim V, \dim V - 1\}$$

$$= \text{B}_{\mathcal{Y}}([X, \Theta(X)], Y) =$$

$$= -\text{B}_{\mathcal{Y}}(\Theta(X), [X, Y])$$

$$= -\text{B}_{\mathcal{Y}}(\Theta(X), -\alpha(Y)X)$$

$$= \text{B}_{\mathcal{Y}}(\Theta(X), X) \alpha(Y)$$

$$= \text{B}_{\mathcal{Y}}(\Theta(X), X) \underbrace{\text{B}_{\mathcal{Y}}(H_\alpha, Y)}_{\text{scalar prod.}}$$

$$= \text{B}_{\mathcal{Y}}(\Theta(X), X) (-\langle H_\alpha, \Theta(Y) \rangle)$$

$$= \text{B}_{\mathcal{Y}}(\Theta(X), X) \langle H_\alpha, Y \rangle$$

$$\Rightarrow \langle [X, \Theta(X)] - \text{B}_{\mathcal{Y}}(\Theta(X), X) H_\alpha, Y \rangle = 0$$

$$\forall Y \in \mathcal{D} \quad \blacksquare$$





