

INTRODUCTION

1 MATHEMATICAL DEFINITION OF STOCHASTIC PROCESSES

We want to describe random processes evolving in time.

→ discrete time $I = \mathbb{N}$

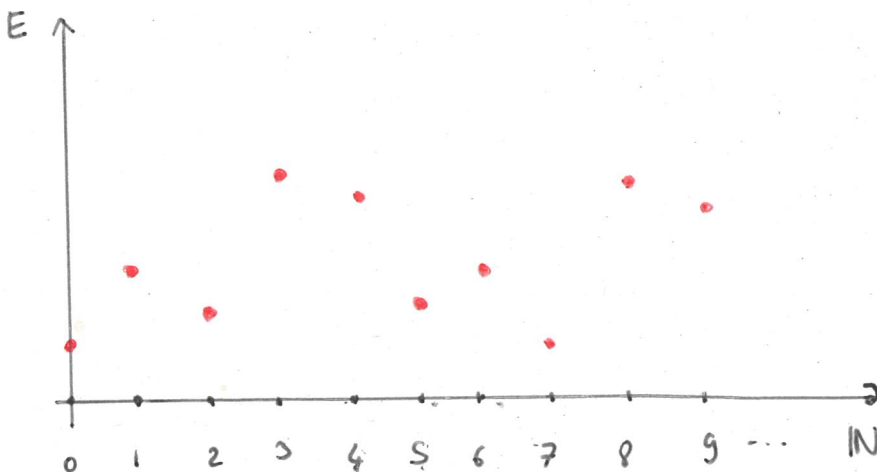
→ continuous time $\mathbb{R}_+ = [0, +\infty)$

Framework: In this chapter, we fix a probability space $(\Omega, \mathcal{F}, \mathbb{P})$.

Def. Let (E, \mathcal{E}) be a measurable space.

A discrete(-time) stochastic process with state space E is a collection of n.v. $(X_n)_{n \in \mathbb{N}}$ with values on E .

💡 discrete stochastic process = "random sequence"

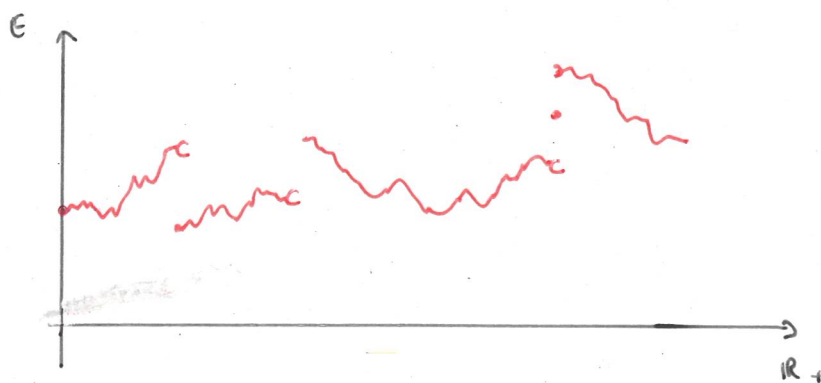


For fixed $\omega \in \Omega$ $(X_n(\omega))_{n \in \mathbb{N}}$ is a sequence of elements of E .

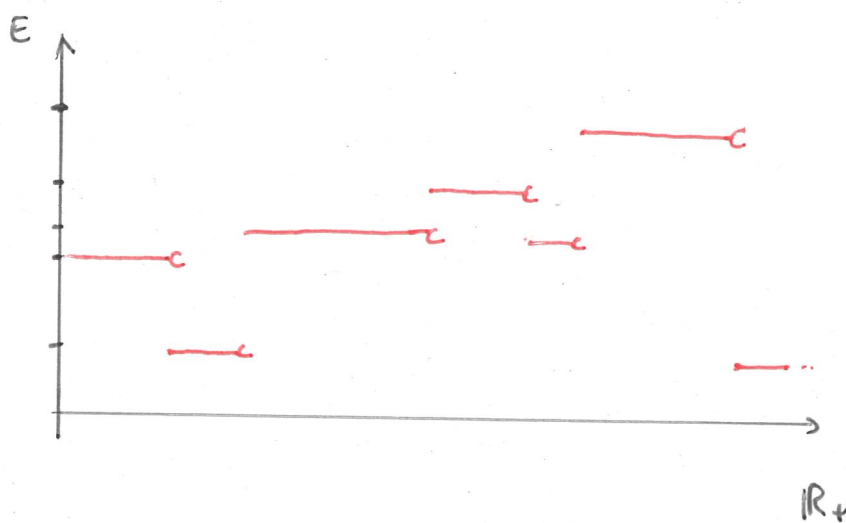
Def: A continuous (-time) stochastic process with state space E is a collection $(X_t)_{t \in \mathbb{R}_+}$ of n.v. with values in E .



continuous stochastic process = "random function".



In this class, we will consider jump processes (E finite or countable):



Rk: general stochastic process with state space E

→ collection $(X_t)_{t \in I}$ of n.v. with values in E

↳ A stochastic process is a collection of n.v. on the same probability space, nothing more!

less complicated more complicated
→

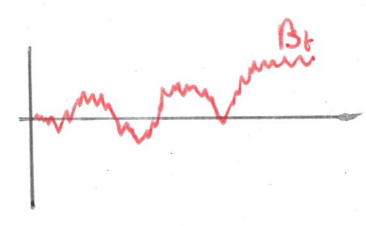
time space I	finite	infinite countable (e.g. $I = \mathbb{N}$)	uncountable ($I = \mathbb{R}_+$)
state space E	finite	infinite countable ($E = \mathbb{Z}$)	uncountable ($E = \mathbb{R}$)

Processes studied in this class:

- discrete time Markov Chains $I = \mathbb{N}$ E finite or countable
- Poisson processes / Renewal processes $I = \mathbb{R}_+$ $E = \mathbb{N}$
- Continuous-time Markov Chains $I = \mathbb{R}_+$ E finite or countable

Not in this class

- Brownian motion: $I = \mathbb{R}_+$ $E = \mathbb{R}$



Some questions about stochastic processes:

- Definition: a stochastic process is not always easy to define.
- Dependences: for $s, t \in I$ how do X_s and X_t depend on each other?
- long time behaviour? ($I = \mathbb{N}$ or \mathbb{R}_+)
how does (X_t) look like for t large?

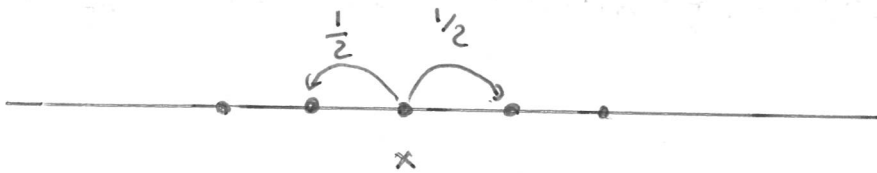
2. EXAMPLE 1: THE SIMPLE RANDOM WALK ON \mathbb{Z}^d

State space $E = \mathbb{Z}^d$.

$x, y \in \mathbb{Z}^d$ are neighbors if they are at Euclidean distance 1.

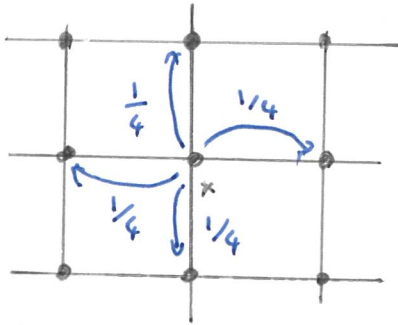
A particle starts at the origin and at each step, it jumps uniformly on one of its neighbors.

on \mathbb{Z} :

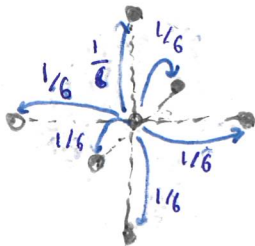


$$X_0 = 0 \quad \text{and} \quad P[X_{n+1} = y \mid X_n = x] = \begin{cases} \frac{1}{2} & \text{if } y \in \{x-1, x+1\} \\ 0 & \text{otherwise} \end{cases}$$

on \mathbb{Z}^2



on \mathbb{Z}^3



Definition? Let $(Z_n)_{n \geq 0}$ iid with $P[Z_n = \pm e_i] = \frac{1}{2d}$

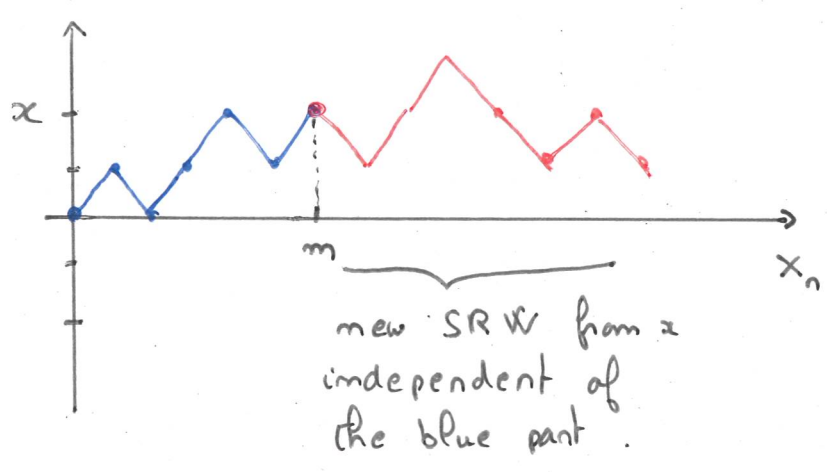
$$X_n := \sum_{k=1}^n Z_k$$

Dependence? $\forall m, n$ X_m and X_n are not independent (ex.)

Furthermore it satisfies the Markov property:

Condition on $X_m = x$, $(X_{m+n})_{n \geq 0}$ is a SRW

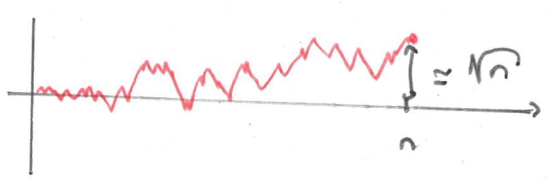
starting at x , independent of the first steps X_1, \dots, X_m .



Long-time behaviour?

d=1: By the central limit theorem we have

$$\frac{X_n}{\sqrt{n}} = \frac{Z_1 + \dots + Z_n}{\sqrt{n}} \xrightarrow[n]{(Law)} \mathcal{N}\left(0, \frac{1}{4}\right)$$

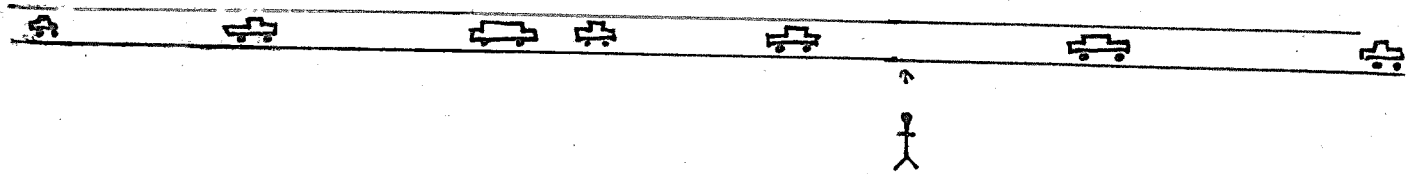


Is the state 0 visited infinitely many times?

Answer: (Polya's Theorem)

$$\sum_{n=0}^{\infty} \mathbb{1}_{X_n = 0} \begin{cases} = +\infty \text{ a.s. } d=1, 2 \\ < +\infty \text{ a.s. } d \geq 3 \end{cases}$$

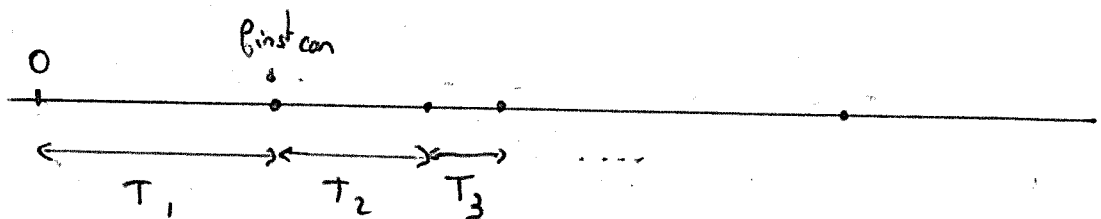
3 EXAMPLE 2 : POISSON PROCESS.



Goal: define and study

$N_t =$ Number of cars passing at a point during a time interval $[0, t]$

Definition? consider $T_1 =$ passage time of the first car
 $T_2 =$ time between the first & second car
:



Define for every $t \geq 0$

$$N_t = \# \{ \text{arrivals before time } t \}$$

$$= \sum_{i=1}^{\infty} \mathbb{1}_{T_1 + \dots + T_i \leq t}$$

→ $(N_t)_{t \geq 0}$ is a stochastic process, called Poisson Process (with intensity λ).

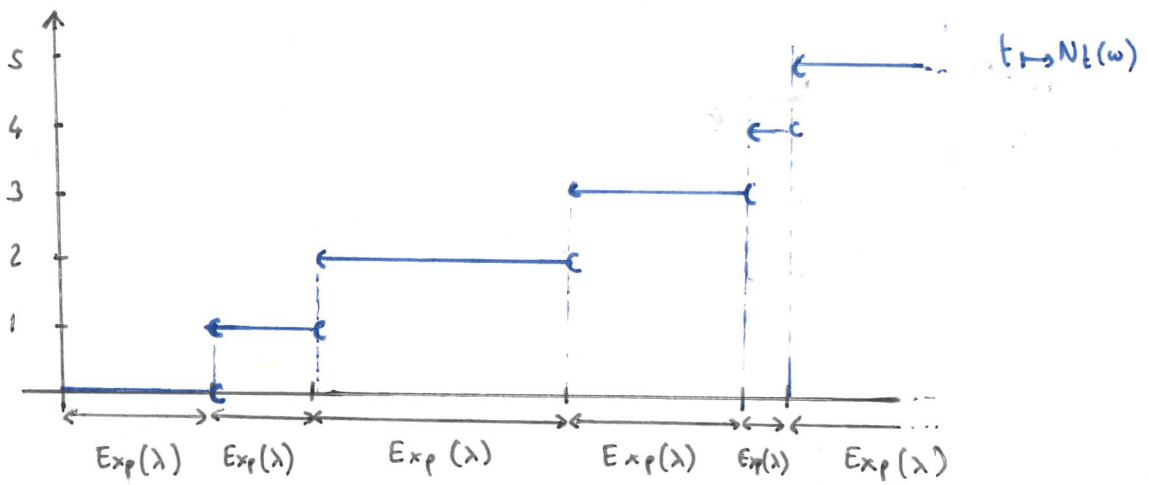


Fig: A possible trajectory of the Poisson process $(N_t)_t$.

Applications: arrival of customers in a queue, times at which telephone calls arrive at a call center, times at which claims arrive in an insurance company, times of emission for α particles by a radioactive source.

Hypotheses : $(T_i)_{i \geq 1}$ are i.i.d. \rightarrow "Right after the first car arrived, the time before the second arrival has the same law as T_1 , and is independent, and so on..."

$\bullet P[T_1 \geq t+s | T_1 \geq t] = P[T_1 \geq s].$

"memoryless property": knowing that at time t , no car has arrived, the law of the remaining waiting time is the same as the original waiting time.

\bullet The waiting times are "nice". $P[T_1 < \infty] = 1$,

$t \mapsto P[T_1 \geq t]$ is continuous (no atom) and $\forall t P[T_1 \geq t] > 0$.

Writing $g(t) = P[T_1 \geq t]$, we must have

$$\forall s, t \geq 0 \quad g(s) = P[T_1 \geq s] = \frac{P[T_1 \geq t+s]}{P[T_1 \geq t]} = \frac{g(t+s)}{g(t)}$$

Hence $\begin{cases} g(t+s) = g(t)g(s). & s, t \geq 0 \\ g(0) = 1. \end{cases}$

$\rightarrow \exists \lambda > 0$ s.t. $\forall t. g(t) = e^{-\lambda t}$

T_1, \dots, T_i, \dots are iid exponential random variables with some parameter $\lambda > 0$.

CHAPTER 1:
MARKOV CHAINS:
 GENERALITIES.

- Ref: [NORRIS] Markov Chains
 [DURRETT] Probability: Theory and examples.
 [SZNITMAN] Lecture notes 2017.

Framework: $(\Omega, \mathcal{F}, \mathbb{P})$ probability space
 • E , finite or countable, non empty set,
 equipped with the σ -algebra $\mathcal{P}(E)$.

Idea: A Markov Chain is a discrete time stochastic process $(X_n)_{n \in \mathbb{N}}$ without memory: Given a time k the future $(X_{k+n})_{n \geq 0}$ depends only on the current position X_k and is independent of the past.

- Motivation:
- application in \rightarrow Physics (e.g. evolution of a system in time)
 - \rightarrow Genetics (e.g. DNA sequences)
 - \rightarrow Computer science (e.g. Page Rank from Google simulations ...)
 - \rightarrow Mathematics (construction of measures ... resolution of PDEs ...)
 - \rightarrow Linguistics (e.g. original motivation of Markov 1856-1922)
 - \rightarrow Music (software for music generation)

Theoretical motivations:

- easy to define (one of the simplest process besides i.i.d)
- can be studied via algebraic tools (matrix theory ...)
and analysis (operator theory)

Goals of the chapter

- Define Markov chains. (MC) / weak Markov property
- Representation with transition probabilities

$$MC \iff \text{"matrix"} (P_{xy})_{x,y \in E}$$

- Existence theorem.
- Invariant / reversible distributions.
- Strong Markov properties, application to hitting times
- Application to Dirichlet problem.

DEFINITIONS

Def: A sequence $(X_n)_{n \in \mathbb{N}}$ of n.v. with values in E is a homogeneous discrete-time Markov chain (MC) if

$$(i) \forall n \geq 0 \quad \forall x_0, \dots, x_{n+1} \in E$$

$$IP[X_{n+1} = x_{n+1} \mid X_0 = x_0, \dots, X_n = x_n] = IP[X_{n+1} = x_{n+1} \mid X_n = x_n]$$

"one-step Markov Property"

$$(ii) \forall m, n \geq 0 \quad \forall x, y \in E$$

$$IP[X_{n+1} = y \mid X_n = x] = IP[X_{m+1} = y \mid X_m = x]$$

"homogeneity"

⚠ there is a small abuse of notation, because the events in the conditioning may have zero probability. By convention, when we write $P[A|B]$, we make the implicit assumption that $P[B] > 0$

e.g. (ii) corresponds to:

$$\forall m, n \geq 0 \quad \forall x, y \text{ satisfying } P[X_m = x] > 0 \quad P[X_n = x] > 0$$

$$P[X_{n+1} = y | X_n = x] = P[X_{m+1} = y | X_m = x]$$

Rk: (i) \Leftrightarrow $\left\{ \begin{array}{l} \forall f: E \rightarrow \mathbb{R} \text{ bounded} \\ E[f(X_{n+1}) | X_0, \dots, X_n] = E[f(X_{n+1}) | X_n] \text{ a.s.} \end{array} \right.$

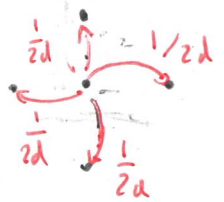
Example 1: If $(X_n)_{n \geq 0}$ are iid n.v. in E , then $(X_n)_{n \geq 0}$ is a M.C.

Example 2: Simple random walk on \mathbb{Z}^d

Let $(Z_n)_{n \geq 1}$ iid uniform in $\{\pm e_1, \dots, \pm e_d\}$. Then

$$X_n = \sum_{k=1}^n Z_k \quad (X_0 = 0)$$

defines a MC on \mathbb{Z}^d .



Indeed: $\forall x_0, \dots, x_{n+1} \in \mathbb{Z}^d$ ($x_0 = 0$)

$$\begin{aligned} & \mathbb{P} \{ X_{n+1} = x_{n+1} \mid X_0 = x_0, \dots, X_n = x_n \} \\ &= \mathbb{P} \{ Z_{n+1} = x_{n+1} - x_n \mid Z_1 = x_1 - x_0, \dots, Z_n = x_n - x_{n-1} \} \\ &= \mathbb{P} \{ Z_{n+1} = x_{n+1} - x_n \} \quad (\text{by independence}) \end{aligned}$$

and

$$\begin{aligned} \mathbb{P} \{ X_{n+1} = x_{n+1} \mid X_n = x_n \} &= \mathbb{P} \{ Z_{n+1} = x_{n+1} - x_n \mid Z_1, \dots, Z_n = x_n \} \\ &= \mathbb{P} \{ Z_{n+1} = x_{n+1} - x_n \} \end{aligned}$$

This proves (i)

For (ii), simply use that $\mathbb{P} \{ X_{n+1} = y \mid X_n = x \} = \mathbb{P} \{ Z_{n+1} = y - x \}$

$$= \begin{cases} \frac{1}{2d} & \text{if } y = x \pm e_i \\ 0 & \text{otherwise} \end{cases}$$

independent of n

2 TRANSITION PROBABILITIES

Def: A transition probability is a sequence $p = (p_{x,y})_{x,y \in E}$ a.t.

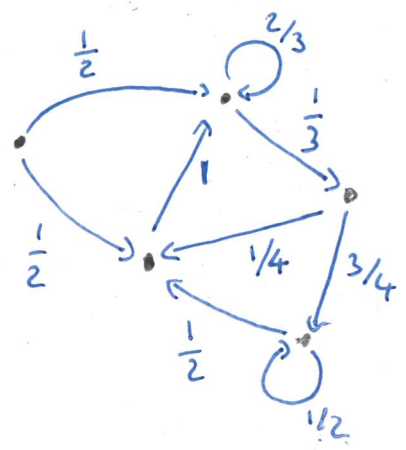
- $\forall x, y \in E \quad p_{x,y} \geq 0,$

- $\forall x \in E \quad \sum_{y \in E} p_{x,y} = 1.$

Different representations of a transition probability

- weighted oriented graph (E finite or infinite)

vertices = E weighted edges : $(x, y) \in E^2$ s.t. $p_{xy} > 0$



→ the sum of the weights of the edges exiting a vertex is equal to 1.

- matrix (E finite)

for simplicity $E = \{1, \dots, N\}$

$$P = \begin{pmatrix} p_{11} & \dots & p_{1N} \\ \vdots & & \vdots \\ p_{N1} & \dots & p_{NN} \end{pmatrix}$$

"Stochastic matrix"

- $p_{ij} \geq 0$ "non negative entries"
- $\sum_{j=1}^N p_{ij} = 1$
- ↳ each line sums to 1

- operator (E finite or infinite)

$\forall f \in L^\infty(E)$ define the function $Pf \in L^\infty(E)$ by

$$(Pf)(x) = \sum_{y \in E} p_{xy} f(y)$$


P positive ($\forall f \geq 0 \ Pf \geq 0$) and satisfies $P \mathbf{1} = \mathbf{1}$

↑
constat function

Def: Let p be a transition probability, μ proba measure on E .

A sequence of n.v. $(X_n)_{n \geq 0}$ with values in E is a Markov Chain with initial distribution μ and transition probability p (MC (μ, p)) if

$$\forall x_0, \dots, x_n \in E \quad \mathbb{P}[X_0=x_0, \dots, X_n=x_n] = \mu(x_0) p_{x_0 x_1} \dots p_{x_{n-1} x_n}$$

 p_{xy} = probability to jump from x to y .

Notation: $\mathcal{M} = \{ \text{proba. measure on } E \}$.

Prop: Let $(X_n)_{n \geq 0}$ be a sequence of n.v. with value in E . Then

$$((X_n)_{n \geq 0} \text{ is a MC}) \iff (\exists \mu \in \mathcal{M} \exists p \text{ } (X_n)_{n \geq 0} \text{ is MC}(\mu, p))$$

Proof:

\Rightarrow Define $\mu = \text{law of } X_0$ and set

$$p_{xy} = \begin{cases} \mathbb{P}[X_{n+1} = y | X_n = x] & \text{if } \exists n \quad \mathbb{P}[X_n = x] > 0 \\ 1_{x=y} & \text{otherwise.} \end{cases}$$

By homogeneity, p_{xy} is well-defined.

Furthermore, for every $x_0, \dots, x_n \in E$ we have.

$$\begin{aligned}
& \mathbb{P}[X_0 = x_0, \dots, X_n = x_n] \\
&= \underbrace{\mathbb{P}[X_0 = x_0]}_{= \gamma(x_0)} \cdot \prod_{i=1}^n \underbrace{\mathbb{P}[X_i = x_i \mid X_0 = x_0, \dots, X_{i-1} = x_{i-1}]}_{= \mathbb{P}[X_i = x_i \mid X_{i-1} = x_{i-1}] \text{ "by the 1-step Markov property"}} \\
& \hspace{15em} = p_{x_{i-1}, x_i} \text{ "by def. of } p \text{"} \\
&= \gamma(x_0) \cdot p_{x_0, x_1} \cdot \dots \cdot p_{x_{n-1}, x_n}.
\end{aligned}$$

It remains to check that p is a transition probability.

Let $x \in E$. If there exists $n \geq 0$ s.t. $\mathbb{P}[X_n = x] > 0$, then

$$\sum_{y \in E} p_{xy} = \sum_{y \in E} \mathbb{P}[X_{n+1} = y \mid X_n = x] = 1.$$

Otherwise,

$$\sum_{y \in E} p_{xy} = \sum_{y \in E} \mathbb{1}_{x=y} = 1.$$

⇐ Assume $(X_n)_{n \geq 0}$ is MC(γ, p).

Let $n \geq 0$ and x_0, \dots, x_{n+1} s.t. $\gamma(x_0) p_{x_0, x_1} \cdot \dots \cdot p_{x_n, x_{n+1}} > 0$

$$\begin{aligned}
& \text{We have } \mathbb{P}[X_{n+1} = x_{n+1} \mid X_0 = x_0, \dots, X_n = x_n] \\
&= \frac{\mathbb{P}[X_0 = x_0, \dots, X_{n+1} = x_{n+1}]}{\mathbb{P}[X_0 = x_0, \dots, X_n = x_n]} = p_{x_n, x_{n+1}}
\end{aligned}$$

Now let $n \geq 0$, $x, y \in E$ s.t. $P[X_n = x] > 0$.

$$\begin{aligned}
 P[X_{n+1} = y \mid X_n = x] &= \sum_{u_0, \dots, u_{n-1} \in E} P[X_{n+1} = y \mid X_0 = u_0, \dots, X_{n-1} = u_{n-1}, X_n = x] \\
 &\quad \times P[X_0 = u_0, \dots, X_{n-1} = u_{n-1} \mid X_n = x] \\
 &= P_{xy} \sum_{u_0, \dots, u_{n-1}} P[X_0 = u_0, \dots, X_{n-1} = u_{n-1} \mid X_n = x] \\
 &= P_{xy}
 \end{aligned}$$

This concludes (i) and (ii) are the def of MC. ■

Why is the representation of MC with μ and P nice?

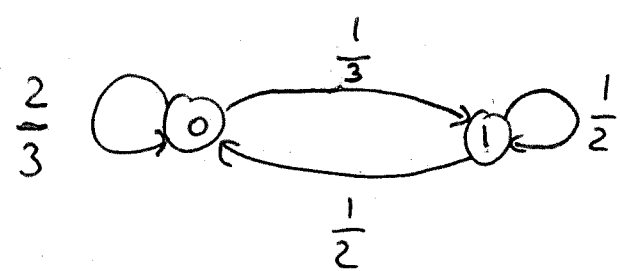
Assume $E = \{1, \dots, N\}$

Let $\mu \in \text{db}$ $\leftrightarrow \mu = (\mu_1, \dots, \mu_N)$

$$\begin{aligned}
 P[X_n = j] &= \sum_{i_0, \dots, i_{n-1}} P[X_0 = i_0, \dots, X_{n-1} = i_{n-1}, X_n = j] \\
 &= \sum_{i_0, \dots, i_{n-1}} \mu_{i_0} P_{i_0 i_1} \dots P_{i_{n-2} i_{n-1}} P_{i_{n-1} j} \\
 &= (\mu P^n)_j
 \end{aligned}$$

Example: the weather Markov Chain

0 = "cloudy day" 1 = "sunny day"



$$P = \begin{pmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

We start on a cloudy day. $X_0 = 0$ (ie. $\mu = \delta_0$)

What is the probability that the n -th day is sunny.

We have $P[X_n = 1] = (\mu P^n)_1$

$$P = \underbrace{\begin{pmatrix} 1 & -\frac{2}{5} \\ 1 & \frac{2}{5} \end{pmatrix}}_Q \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{6} \end{pmatrix} \underbrace{\begin{pmatrix} \frac{3}{5} & \frac{2}{5} \\ -1 & 1 \end{pmatrix}}_{Q^{-1}}$$

$$P^n = Q \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{6^n} \end{pmatrix} Q^{-1}$$

$$(1, 0) P^n \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{2}{5} - \frac{2}{5} \cdot \left(\frac{1}{6}\right)^n$$

3 EXISTENCE THEOREM

Question: For fixed p and μ , does there exist a stochastic process $(X_n)_{n \geq 0}$ which is a MC (μ, p) ?

Theorem

Let p be a transition probability on E . There exist

- a measurable space (Ω, \mathcal{F})
- a collection of probability measures $(P_x)_{x \in E}$
- a sequence of n.v. $(X_n)_{n \geq 0}$ on (Ω, \mathcal{F})

such that, for every x we have

under P_x , $(X_n)_{n \geq 0}$ is MC (δ_x, p)

Proof. We first fix a measure μ on E with $\mu(x) > 0$ for every x . and construct a MC (μ, p) on some abstract probability space (Ω, \mathcal{F}, P) .

- Consider
- X_0 a n.v with law μ
 - U_1, U_2, \dots iid uniform n.v. on $[0, 1]$

One can construct a measurable function

$$\Phi: E \times [0, 1) \longrightarrow E$$

such that $\forall x \in E \quad \mathbb{P}[\Phi(x, U_1) = y] = p_{xy}$

(order $E = \{x_1, x_2, \dots\}$ and then define for every i, j

$$s_{i,j} = \sum_{k < j} p_{x_i x_k} \quad \text{and} \quad \Phi(x_i, u) = x_j \text{ if } s_{i,j} \leq u < s_{i,j} + p_{x_i x_j}$$

Define by induction, for every $n \geq 0$

$$X_{n+1} = \Phi(X_n, U_{n+1})$$

Then we have for every $x_0, \dots, x_n \in E$

$$\begin{aligned} & \mathbb{P}[X_0 = x_0, X_1 = x_1, \dots, X_n = x_n] \\ &= \mathbb{P}[X_0 = x_0, \Phi(x_0, U_1) = x_1, \dots, \Phi(x_{n-1}, U_n) = x_n] \end{aligned}$$

$$\stackrel{\text{indep.}}{=} p(x_0) p_{x_0 x_1} \dots p_{x_{n-1} x_n}$$

Now define for every $x \quad P_x := \mathbb{P}[\cdot \mid X_0 = x]$

(well defined because $p(x) > 0$)

Then we have $\forall x \quad P_x [X_0 = x_0, \dots, X_n = x_n] = \delta_x(x_0) p_{x_0 x_1} \dots p_{x_{n-1} x_n} \cdot \blacksquare$

Framework for the rest of the chapter.

- E finite or countable
- p transition probability
- $(\Omega, \mathcal{F}, (P_x)_{x \in E})$ proba spaces.
- $(X_n)_{n \geq 0}$ a.v. s.t. X_n MC (δ_x, p) under P_x .

Notation: For every μ proba. measure on E

$$P_\mu := \sum_{x \in E} \mu(x) \cdot P_x$$

This implies $\forall x_0, \dots, x_n \in E$

$$P_\mu (X_0 = x_0, \dots, X_n = x_n) = \mu(x_0) p_{x_0 x_1} \dots p_{x_{n-1} x_n}$$

\hookrightarrow Under P_μ $(X_n)_{n \geq 0}$ is MC (μ, p) .

Rk: Under P_μ , $(X_n)_{n \geq 0}$ is a MC. Hence it satisfies

$\forall x_0, \dots, x_n, x_{n+1} \in E$

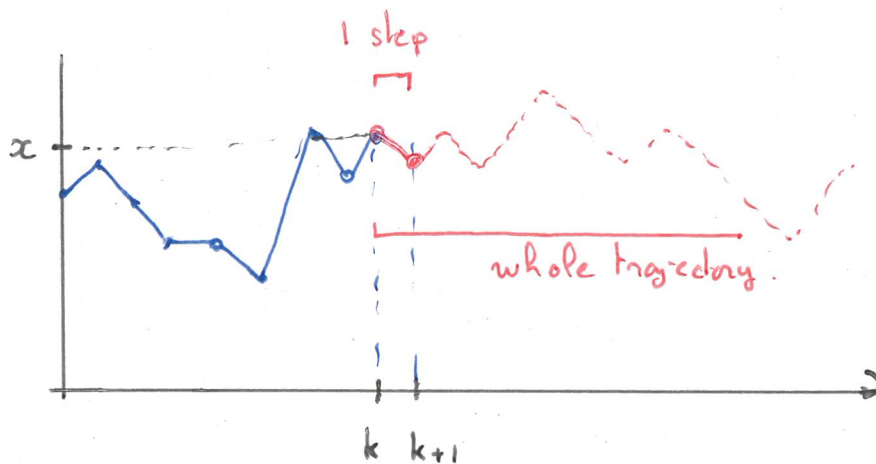
$$\begin{aligned} P_\mu [X_{n+1} = x_{n+1} \mid X_0 = x_0, \dots, X_n = x_n] &= P_\mu [X_{n+1} = x_{n+1} \mid X_n = x_n] \\ &= P_{x_n} [X_1 = x_{n+1}] \end{aligned}$$

"rephrasing of the 1-step Markov property"

4 SIMPLE MARKOV PROPERTY.

💡 The one-step Markov property says:

Condition on $X_k = x$, X_{k+1} is sampled like the first step of a MC (S_x, p) , independent of X_0, \dots, X_k .



The Markov property will say that the whole trajectory is sampled according to a MC (S_x, p) independent of the past.

Not: $\mathcal{F}_n = \sigma(X_0, \dots, X_n)$

Thm [Markov property] Let $\mu \in db$.

Let $x \in E$, $k \in \mathbb{N}$. For every $f: E^{\mathbb{N}} \rightarrow \mathbb{R}$ meas. bounded, for every $Z \in \mathcal{F}_k$ -measurable bounded, we have

$$(a) \quad E_{\mu} [f((X_{k+n})_{n \geq 0}) \cdot Z \mid X_k = x] = E_x [f((X_n)_{n \geq 0})] \cdot E_{\mu} [Z \mid X_k = x]$$

"Condition on $X_k = x$, $(X_{k+n})_{n \geq 0}$ is MC (S_x, p) , independent of \mathcal{F}_k ."

Corollary:

Let $\mu \in \mathcal{D}_b$, $x \in E$, $k \in \mathbb{N}$. For every $f: E^{\mathbb{N}} \rightarrow \mathbb{R}$ meas. bounded

$$E_{\mu} [f((X_{k+n})_{n \geq 0}) | X_k = x] = E_x [f((X_n)_{n \geq 0})]$$

Proof: take $z=1$ in the Markov property:

Rk: The statement (*) is equivalent to

$$\forall x_0, \dots, x_{k-1}, x_k \in E$$

$$(**) \quad E_{\mu} [f((X_{k+n})_{n \geq 0}) | X_0 = x_0, \dots, X_{k-1} = x_{k-1}, X_k = x_k] = E_{x_k} [f((X_n)_{n \geq 0})]$$

(exercise. Hint: take $z = \mathbb{1}_{X_0 = x_0, \dots, X_{k-1} = x_{k-1}}$)

Proof: We prove (**).

By approximating f by step functions and by linearity it suffices to prove (**) for $f = \mathbb{1}_A$ where $A \subseteq E^{\mathbb{N}}$ measurable.

$$P_{\mu} [(X_{k+n})_{n \geq 0} \in A | X_0 = x_0, \dots, X_k = x_k] = P_{x_k} [(X_n)_{n \geq 0} \in A]$$

By Dynkin's lemma, it suffices to prove the statement above for A of the form

$$A = \{ \omega \in E^{\mathbb{N}} : \omega_0 = y_0, \dots, \omega_N = y_N \} \quad \begin{array}{l} N \geq 0 \\ y_0, \dots, y_N \in E \end{array}$$

For such event A , we have

$$\begin{aligned}
 & P_{\mu} \left[(X_{k+n})_{n \geq 0} \in A \mid X_0 = x_0, \dots, X_k = x_k \right] \\
 &= P_{\mu} \left[X_k = y_0, \dots, X_{k+N} = y_N \mid X_0 = x_0, \dots, X_k = x_k \right] \\
 &\stackrel{=}{=} \frac{P(x_0) P_{x_0 x_1} \dots P_{x_{k-1} x_k} \cdot \mathbb{1}_{x_k = y_0} \cdot P_{y_0 y_1} \dots P_{y_{N-1} y_N}}{P(x_0) P_{x_0 x_1} \dots P_{x_{k-1} x_k}} \\
 &= \delta_{x_k}(y_0) P_{y_0 y_1} \dots P_{y_{N-1} y_N} = P_{x_k} \left[(X_n)_{n \geq 0} \in A \right]
 \end{aligned}$$

5. n-STEP TRANSITION PROBABILITIES

Def: For every $n \geq 0$, for every $x, y \in E$, define

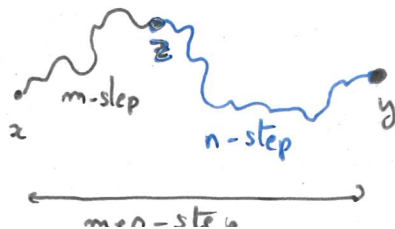
$$P_{x,y}^{(n)} := P_x [X_n = y]$$

"probability to reach y from x in n steps"

Prop. [Chapman-Kolmogorov]

For every $m, n \geq 0$, $x, y \in E$, we have

$$P_{x,y}^{(m+n)} = \sum_{z \in E} P_{x,z}^{(m)} P_{z,y}^{(n)}$$



Proof:
$$P_x [X_{m+n} = y] = \sum_{z \in E} P_x [X_{m+n} = y | X_m = z] P_x [X_m = z]$$

$$\stackrel{MP}{=} \sum_{z \in E} P_x [X_m = z] P_z [X_n = y]$$

$$= \sum_{z \in E} P_x [X_m = z] P_z [X_n = y] \quad \blacksquare$$

Prop: [matrix interpretation]

Assume $E = \{1, \dots, N\}$ for some $N \geq 1$. Write $P = (P_{ij})_{1 \leq i, j \leq N}$.

Then the matrix $(P_{ij}^{(n)})_{1 \leq i, j \leq N}$ is the n -th power of P :

$\forall n \geq 0$

$$(P_{ij}^{(n)})_{1 \leq i, j \leq N} = P^n$$

Furthermore, for every distribution μ on E , and every function $f: E \rightarrow \mathbb{R}$ we have

$\forall n \geq 0$

$$E_\mu [f(X_n)] = \mu P^n f$$

where we identify μ with the row vector $\mu = (\mu(1), \dots, \mu(N))$ and f with the column vector $f = \begin{pmatrix} f(1) \\ \vdots \\ f(N) \end{pmatrix}$.

Proof: The first equation follows from $P_{ik}^{(n+1)} = \sum_j P_{ij}^{(n)} P_{jk}$ by induction. For the second equation, we use the def. of the expectation

$$E_\mu [f(X_n)] = \sum_{y \in E} f(y) P_\mu [X_n = y] = \sum_{\substack{x \in E \\ y \in E}} \mu(x) \underbrace{P_x [X_n = y]}_{= P_{xy}^{(n)}} f(y) \quad \blacksquare$$

Dictionary probability \leftrightarrow algebra for E finite

$E = \{1, \dots, N\}$

Probability	Linear Algebra
distribution μ on E	$\mu = (\mu_1, \dots, \mu_N) \in \mathbb{R}_+^N$ with $\sum_i \mu_i = 1$
measurable map $f: E \rightarrow \mathbb{R}$	$f = \begin{pmatrix} f_1 \\ \vdots \\ f_N \end{pmatrix} \in \mathbb{R}^N$
Markov Chain	$\left\{ \begin{array}{l} \text{row vector } \mu \quad \sum_{i=1}^N \mu_i = 1 \\ \text{stochastic matrix } P \end{array} \right.$
$E_\mu[f(X_n)]$	$\mu P^n f$
law of X_n	μP^n
$(E_x[f(X_n)])_{x \in E}$	$P^n f$

See exercises for a general method to compute $P_x[X_n = y]$.

6 STATIONARY DISTRIBUTIONS

Motivation: write μ_n for the distribution of X_n under P_μ

\hookrightarrow we have $\begin{cases} \mu_0 = \mu \\ \mu_{n+1} = \mu_n \cdot P \end{cases}$ "law of $X_{n+1} = f(\text{law of } X_n)$ "

\rightarrow we expect that for n large $\mu_n \approx$ fixed point of $\lambda \mapsto \lambda P$

Def: Let π be a distribution on E (= proba measure on E)

We say that π is stationary (for P) if

$$\forall y \in E \quad \sum_x \pi(x) P_{xy} = \pi(y)$$

Probabilistic interpretation:

If π is a stationary distribution, then for every $n \geq 0$

$$P_\pi [X_n = x] = \pi(x)$$

Equivalently, if $(X_n)_{n \geq 0}$ is a MC (π, P) then the law of X_n is π at every time $n \geq 0$.

This follows from the definition by induction:

- For $n=0$ $P_\pi [X_0 = x] = \pi(x)$ by definition.

- For $n \geq 1$ $P_\pi [X_n = y] = \sum_{x \in E} \underbrace{P_\pi [X_n = y | X_{n-1} = x]}_{\substack{= P_{xy} \\ \uparrow \\ \text{M.P.}}} \underbrace{P_\pi [X_{n-1} = x]}_{\substack{= \pi(x) \\ \uparrow \\ \text{induct.}}}$
 $\stackrel{\uparrow}{=} \pi(y)$
 π stationary.

Algebraic interpretation: $E = \{1, \dots, N\}$ $\pi = (\pi(1), \dots, \pi(N))$

$$\pi \text{ stationary} \Leftrightarrow \boxed{\pi P = \pi}$$

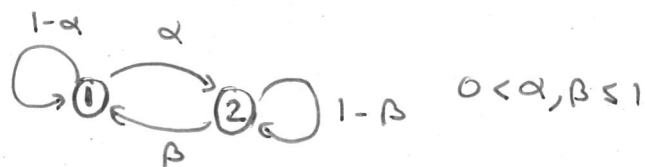
" π is a left eigen vector associated to the eigen value 1"

Rk: Since $P \mathbf{1} = \mathbf{1}$ we know that 1 is an eigen value for P^t as well (because the spectrum of P is the same as the spectrum of P^t).

Therefore, there exists $v \in \mathbb{R}^N \setminus \{0\}$ s.t. $P^t v = v$ i.e. $v^t P = v^t \implies$ it is a priori not clear that there exists such a vector with ≥ 0 entries...

Examples:

• "2-state" - MC $E = \{1, 2\}$



$$\pi = \left(\frac{\beta}{\alpha + \beta}, \frac{\alpha}{\alpha + \beta} \right) \text{ unique stationary distrib.}$$

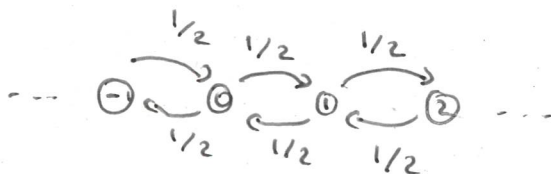
• degenerate 2-state MC ($\alpha = \beta = 0$)



Any $\pi = \alpha \delta_1 + (1-\alpha) \delta_2$, $\alpha \in [0, 1]$ is stationary

\implies infinitely many stationary distributions.

• SRW on \mathbb{Z}



π is stationary $\implies \forall x \quad \pi(x) = \frac{1}{2} \pi(x-1) + \frac{1}{2} \pi(x+1)$

$\implies \forall x \quad \pi(x) - \pi(x-1) = \pi(x+1) - \pi(x) \implies \pi$ is linear

\implies There is no stationary distribution.

Rk: for the simple random walk the constant measures

$$\mu(x) = 1 \text{ satisfy } \mu P = \mu$$

↳ "invariant" measure (but not a probability measure)

7. REVERSIBILITY

Def: A distribution π on E is said to be reversible (for p) if

$$\forall x, y \in E \quad \pi(x) p_{xy} = \pi(y) p_{yx} \quad \text{"detailed balance"}$$

Rk: Why is it called reversibility?

$$\pi \text{ reversible} \iff \forall x, y \in E \quad P_{\pi} [X_0 = x, X_1 = y] = P_{\pi} [X_0 = y, X_1 = x]$$

More generally, one can prove by induction that π is reversible iff

$$\forall n \quad \forall x_0, \dots, x_n \in E \quad P_{\pi} [X_0 = x_0, \dots, X_n = x_n] = P_{\pi} [X_0 = x_n, \dots, X_n = x_0]$$

$$\rightsquigarrow P_{\pi} \left[\begin{array}{c} \text{trajectory from } x_0 \text{ to } x_n \end{array} \right] = P_{\pi} \left[\begin{array}{c} \text{trajectory from } x_n \text{ to } x_0 \end{array} \right]$$

"If X_0 is sampled according to π then the probability of a given trajectory is equal to the probability of its reversed version"

Motivation: • criterion for stationarity (see next proposition)

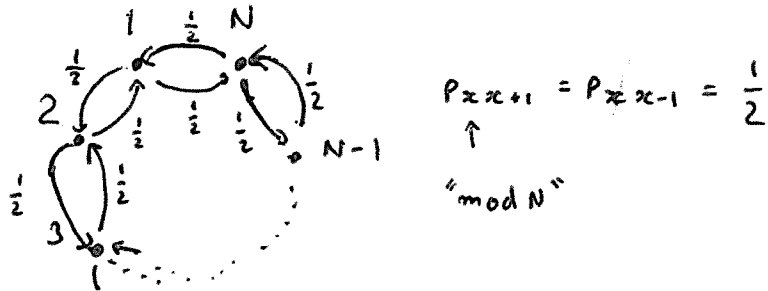
• appear often for dynamics in physics (see Ex. 3 below)

Prop. Let π be a reversible distribution
 Then π is invariant.

Proof. For every $y \in E$, we have

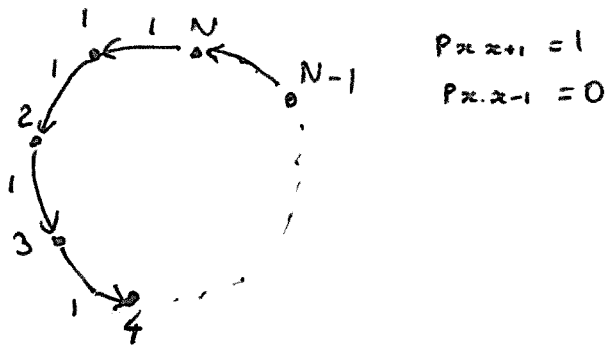
$$\sum_{x \in E} \pi(x) P_{xy} \stackrel{\text{(Rev.)}}{=} \sum_{x \in E} \pi(y) P_{yx} = \pi(y) \underbrace{\sum_{x \in E} P_{yx}}_{=1} \quad \blacksquare$$

Example 1: Sym. RW on a torus $E = \{1, \dots, N\}$



The uniform measure $\pi(x) = \frac{1}{N}$ is reversible.

Example 2: totally asymmetric RW on the torus



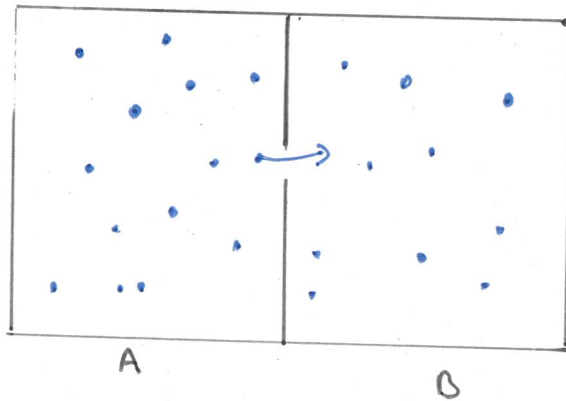
Assume \exists a reversible proba π

then $\forall x \quad \pi(x) = \pi(x) \underbrace{P_{xx+1}}_{=1} \stackrel{\text{(rev)}}{=} \pi(x+1) P_{x+1x} = 0$ contradiction

\rightarrow No reversible distrib. (But uniform distrib. is invariant.)

Example 3: Ehrenfest model of Diffusion.

Two containers A and B are placed adjacent to each other and gas is allowed to pass through a small aperture joining them. A total of N gas molecules is distributed between the containers.



(A and B are assumed to be of the same size)

Model: We consider a discrete time \mathbb{N} , and we write

X_n = Number of particles in A at time n .

At each time, a uniformly chosen molecule passes through the aperture.

$\hookrightarrow (X_n)$ is a Markov Chain on the state space $E = \{1, \dots, N\}$ and the transition probability is given by

$P_{xx+1} = 1 - \frac{x}{N}$	$0 \leq x < N$
$P_{xx-1} = \frac{x}{N}$	$0 < x \leq N$
$P_{xy} = 0$	$y \notin \{x-1, x+1\}$

Let us look for a reversible distribution. $\pi = (\pi_x)_x$

We must have $\pi_x P_{x \rightarrow x+1} = \pi_{x+1} P_{x+1 \rightarrow x}$

$$\text{ie } \pi_{x+1} = \frac{N-x}{x+1} \pi_x$$

By induction we find $\forall x \in \{0, \dots, N\}$ $\pi_x = \frac{N \times \dots \times (N-x+1)}{1 \times \dots \times x} \pi_0 = \binom{N}{x} \pi_0$

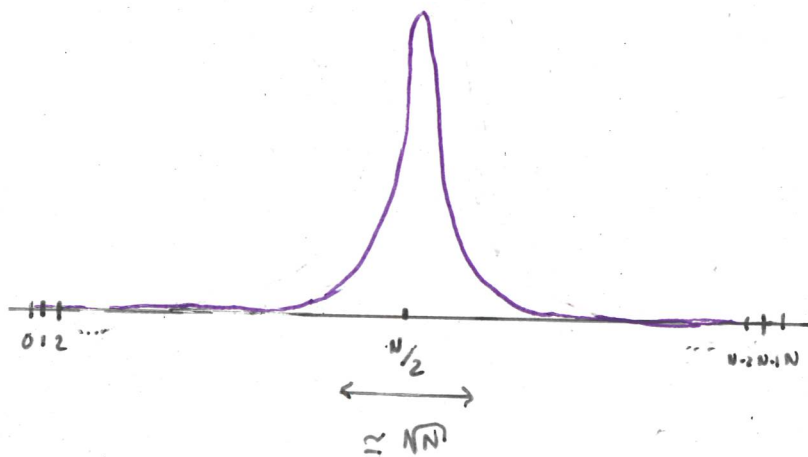
The condition $\sum_x \pi_x = 1$ imposes $\pi_0 = \left(\sum_x \binom{N}{x} \right)^{-1} = \frac{1}{2^N}$

We find $\pi_x = \frac{1}{2^N} \binom{N}{x}$ " π is Binomial $(N, \frac{1}{2})$ "

Conversely, one can check that the Binomial distribution is reversible.

At equilibrium^(*), the number of particles in the container A is distributed like a Binomial $(N, \frac{1}{2})$.

^(*) when X_{n+1} has the same law as X_n



distribution of the number of molecules in A.

8 COMMUNICATION CLASSES

Rk. graph theoretical notion.

($p \leftrightarrow$ weighted oriented graph)

Def: Let $x, y \in E$. Write

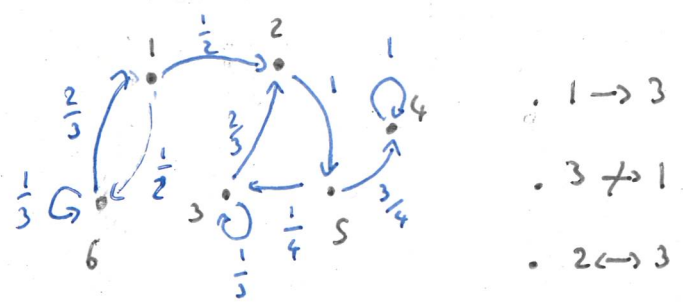
- $x \rightarrow y$ if $\exists n \geq 0$ s.t. $P_{xy}^{(n)} > 0$ "y can be reached from x"
- $x \leftrightarrow y$ if ($x \rightarrow y$ and $y \rightarrow x$) "x and y communicate"

Rk: Since $P_{xy}^{(n)} = \sum_{z_1, \dots, z_{n-1} \in E} P_{xz_1} P_{z_1 z_2} \dots P_{z_{n-2} z_{n-1}} P_{z_{n-1} y}$

we have $(x \rightarrow y) \Leftrightarrow (\exists z_1, \dots, z_{n-1} P_{xz_1}, \dots, P_{z_{n-1} y} > 0)$

seeing p as a oriented graph $x \rightarrow y$ corresponds to the existence of an oriented path from x to y .

Example



Probabilistic interpretation:

$$x \rightarrow y \underset{\substack{\uparrow \\ \text{by def}}}{\Leftrightarrow} \exists n \geq 0 \quad P_x[X_n = y] > 0 \underset{\substack{\uparrow \\ \text{ex.}}}{\Leftrightarrow} P_x[\exists n \geq 0 X_n = y] > 0$$

Prop.
 \leftrightarrow is an equivalence relation on E .

Proof. Since $P_{xx}^{(0)} = 1$, we have $x \leftrightarrow x$ for every $x \in E$.

• If $x \leftrightarrow y$ and $y \leftrightarrow z$, then there exist $m, n \geq 0$ such that $P_{xy}^{(m)}, P_{yz}^{(n)} > 0$. Therefore,

$$P_{xz}^{(m+n)} = \sum_{u \in E} P_{xu}^{(m)} P_{uz}^{(n)} \geq P_{xy}^{(m)} P_{yz}^{(n)} > 0.$$

(CK)

Hence $x \rightarrow z$, and $z \rightarrow x$ equivalently. \square

Def. • The equivalence classes of \leftrightarrow are called communication classes.

• The chain p is said to be irreducible if there is a unique communication class

Rk: p irreducible $\Leftrightarrow \forall x, y \quad x \rightarrow y$

communication class \Leftrightarrow strongly connected component of G

p irreducible $\Leftrightarrow G$ is strongly connected

In the example before, there are 3 communication classes

$$\Leftrightarrow C_1 = \{1, 6\} \quad C_2 = \{2, 3, 5\} \quad C_3 = \{4\}$$

Motivation: we will see that

(p irreducible) \Rightarrow (p has at most 1 stationary distrib.)

\hookrightarrow algebraic proof for E finite (see exercises)

\hookrightarrow probabilistic proof (see next chapter).

Def: A communication class C is closed if for every $x, y \in E$

$$(x \in C, x \rightarrow y) \Rightarrow y \in C$$

Probabilistic interpretation: Let C be a communication class

C is closed $\Leftrightarrow \forall x \in C \ P_x[\forall n \geq 0 \ X_n \in C] = 1$

\hookrightarrow once the Markov chain enters in a closed class, it stays in it forever.

Proof: C not closed $\Leftrightarrow \exists x \in C \ \exists y \in E \setminus C \ x \rightarrow y$

$$\Leftrightarrow \exists x \in C \ \exists y \in E \setminus C \ P_x[\exists n \ X_n = y] > 0$$

$$\Leftrightarrow \exists x \in C \ P_x[\exists n \ X_n \in E \setminus C] > 0$$

$E \setminus C$ at most countable \nearrow

$$\Leftrightarrow \exists x \in C \ P_x[\forall n \ X_n \in C] < 1.$$

Thm [Strong Markov property]

Let μ be a distribution on E . Let T be a (\mathcal{F}_n) -stopping time.

Let $x \in E$. For every $f: E^{\mathbb{N}} \rightarrow \mathbb{R}$ meas. bounded,

for every z \mathcal{F}_T -measurable bounded, we have.

$$E_{\mu} [f((X_{T+n})_{n \geq 0}) \cdot z \mid T < \infty, X_T = x] = E_x [f((X_n)_{n \geq 0})] E_{\mu} [z \mid T < \infty, X_T = x]$$

"condition on $\{T < \infty, X_T = x\}$, $(X_{T+n})_{n \geq 0}$ is MC (δ_x, P) , independent of \mathcal{F}_T "

Proof: We prove the equation multiplied by $P[T < \infty, X_T = x]$

$$E_{\mu} [f((X_{T+n})_{n \geq 0}) z \mathbb{1}_{T < \infty, X_T = x}]$$

$$= \sum_{k=0}^{\infty} E_{\mu} [f((X_{k+n})_{n \geq 0}) z \mathbb{1}_{T=k} \mathbb{1}_{X_k = x}]$$

$$= \sum_{k=0}^{\infty} E_{\mu} [f((X_{k+n})_{n \geq 0}) \cdot \underbrace{z \mathbb{1}_{T=k}}_{\in \mathcal{F}_k} \mid X_k = x] P_{\mu} [X_k = x]$$

$$\stackrel{MP}{=} E_x [f((X_n)_{n \geq 0})] \times \sum_{k=0}^{\infty} E_{\mu} [z \mathbb{1}_{T=k, X_k = x}]$$

$$= E_{\mu} [z \mathbb{1}_{T < \infty, X_T = x}]$$

APPLICATION : REFLECTION PRINCIPLE FOR THE SRW.

Consider the SRW on \mathbb{Z} ($E = \mathbb{Z}$ and $p_{xy} = \frac{1}{2} \mathbb{1}_{|x-y|=1}$)

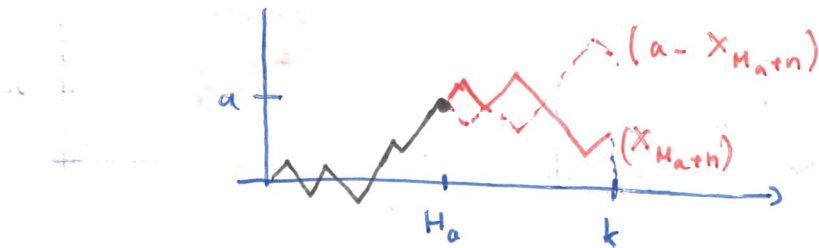
Let $k \geq 0$ even and $a \geq 1$ odd

$$P_0 \left[\max_{0 \leq m \leq k} X_m \geq a \right] = P_0 \left[|X_k| \geq a \right].$$

Proof: Recall $H_a = \min \{ n \geq 1 : X_n = a \}$

$$\begin{aligned} \text{We have } P_0 \left[\max_{0 \leq m \leq k} X_m \geq a \right] &= P_0 \left[H_a \leq k \right] \\ &= P_0 \left[X_n > a \right] + P_0 \left[H_a \leq k, X_k < a \right]. \end{aligned}$$

💡 The law of $(X_{H_a+n})_{n \geq 0}$ is the same as $(a - X_{H_a+n})_{n \geq 0}$



By reflecting the last part of the trajectory, we can prove $P_0 \left[X_n > a \right] = P_0 \left[H_a \leq k, X_k < a \right]$

We have

$$P_0 \left[H_a \leq k, X_k < a \right] = \sum_{m=0}^k P_0 \left[X_k < a, H_a = m \right]$$

By the strong Markov property, we have

$$\begin{aligned}
 P_0 [X_k < a, H_a = m] &\stackrel{(*)}{=} P_a [X_{k-m} < a] P_0 [H_a = m] \\
 &= P_a [X_{k-m} > a] P_0 [H_a = m] \\
 &\quad \text{Symmetry} \\
 &= P_0 [X_k > a, H_a = m]
 \end{aligned}$$

(to justify $(*)$, one can use the strong Markov property

as follows: $P_0 [X_k < a, H_a = m] = P_0 [X_k < a, H_a = m, H_a < \infty]$

$$\begin{aligned}
 &= P_0 [X_{H_a+k-m} < a, H_a = m \mid H_a < \infty, X_{H_a} = a] P_0 [H_a < \infty] \\
 &\stackrel{\text{SMP}}{=} P_a [X_{k-m} < a] P_0 [H_a = m \mid H_a < \infty, X_{H_a} = a] \\
 &= P_a [X_{k-m} < a] P_0 [H_a = m]
 \end{aligned}$$

Plugging the identity above in the sum, we get

$$\begin{aligned}
 P_0 [H_a \leq k, X_k < a] &= \sum_{m=0}^k P_0 [X_k > a, H_a = m] \\
 &= P_0 [X_k > a, H_a \leq k] \\
 &= P_0 [X_k > a]
 \end{aligned}$$

□

CHAPTER 2 :
 MARKOV CHAINS :
 LONG-TIME BEHAVIOUR —

Framework:

- E finite or countable set ,
- $P = (P_{xy})_{x,y \in E}$ transition probability,
- (Ω, \mathcal{F}) measurable space equipped with $(P_x)_{x \in E}$ proba measures.
- $(X_n)_{n \geq 0}$ MC (S_x, P) under P_x .

Not. 1. for $\mu = (\mu_x)_{x \in E}$ distribution on E , write $P_\mu = \sum_x \mu_x P_x$

Questions: • Fixe $x \in E$. Will $(X_n)_{n \geq 0}$ visit x infinitely many times?
 • What is the distribution of X_n for n large?

I RECURRENCE / TRANSIENCE

Notation: For $x \in E$ $H_x = \min \{ n \geq 1 : X_n = x \}$

Def. Let $x \in E$. We say that

- x is recurrent if $P_x [H_x < \infty] = 1$. "the chain always come back at x "
- x is transient if $P_x [H_x < \infty] < 1$. "the chain may never come back"

Notation: For $x \in E$, write $V_x = \sum_{n \geq 1} \mathbb{1}_{X_n = x}$.

"total number of visits of x "

Thm [DICHOTOMY THM]

Let $x \in E$.

- If x is recurrent, then $V_x = +\infty$ P_x -a.s.
- If x is transient, then $E_x[V_x] < \infty$ P_x -a.s.

↳ it is impossible to have $P_x[V_x < \infty] > 0$ and $E_x[V_x] = \infty$.

Lemma: For every $i \geq 0$, $x \in E$, we have

$$P_x[V_x \geq i] = p_x^i \quad \text{where } p_x = P_x[H_x < \infty].$$

Proof: Define for every $i \geq 0$, $T_i = \min \{ n \geq 1 : \sum_{k=1}^n \mathbb{1}_{X_k = x} = i \}$

T_i = "time of the i -th visit of x "

(conventions: $\min \emptyset = +\infty$, $T_0 = 0$)

T_i is a stopping time because

$$\{T_i = n\} = \left\{ \sum_{k=1}^{n-1} \mathbb{1}_{X_k = x} = i-1, X_n = x \right\} \in \mathcal{F}_n.$$

For every $i \geq 1$, we have

$$\begin{aligned} P_x [V_x \geq i] &= P_x [T_i < \infty, T_{i-1} < \infty] \\ &= P_x \left[\underbrace{T_i < \infty}_{\{\exists n \geq 1: X_{T_{i-1}+n} = x\}} \mid T_{i-1} < \infty, X_{T_{i-1}} = x \right] \underbrace{P_x [T_{i-1} < \infty]}_{P_x [V_x \geq i-1]} \end{aligned}$$

$$\stackrel{\text{St. MP}}{=} P_x [T_i < \infty] P_x [V_x \geq i-1]$$

$$= p_x P_x [V_x \geq i-1] \stackrel{\text{induction}}{=} p_x^i \quad \blacksquare$$

Proof of the theorem:

If x is recurrent, we have

$$P_x [V_x = +\infty] = P_x \left[\bigcap_{i \geq 1} \{V_x \geq i\} \right] \stackrel{\text{lemma}}{=} \lim_{i \rightarrow \infty} P_x [V_x \geq i] \stackrel{\uparrow}{=} 1$$

($\{V_x \geq i\} \supset \{V_x \geq i+1\}$) lemma.

If x is transient, we have

$$\begin{aligned} E_x [V_x] &= \sum_{i \geq 1} P_x [V_x \geq i] \\ &= \sum_{i \geq 1} p_x^i = \frac{p_x}{1-p_x} < \infty \quad \blacksquare \end{aligned}$$

Rk: $E_x [V_x] = E_x \left[\sum_{n \geq 0} \mathbb{1}_{X_n = x} \right] = \sum_n P_{xx}^{(n)}$

We conclude this section with a useful consequence of the dichotomy theorem, when E is finite.

Prop. Assume E is finite. Then there exists a recurrent state $x \in E$.

Proof: Observe that

$$\sum_{x \in E} V_x = \sum_{x \in E} \sum_{n \geq 0} \mathbb{1}_{X_n = x}$$

$$= \sum_{n \geq 0} \left(\sum_{x \in E} \mathbb{1}_{X_n = x} \right) = +\infty$$

= 1

For $y \in E$, we have $\sum_x E_y[V_x] = +\infty$.

Hence, there must exist $x \in E$ s.t. $E_y[V_x] = +\infty$.

Using that $V_x = V_x \mathbb{1}_{H_x < \infty}$, we find

$$+\infty = E_y[V_x \mathbb{1}_{H_x < \infty}] \stackrel{\text{St. MP}}{=} (1 + E_x[V_x]) P_y[H_x < \infty]$$

$$\leq E_x[V_x]$$

Therefore, $E_x[V_x] = +\infty$, which concludes that x is recurrent.

Illustration:

x recurrent ($p_x = 1$)



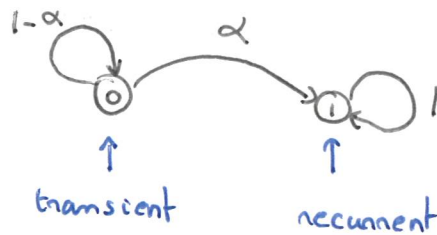
The chain always come back

x transient ($p_x < 1$) ∞



The chain escits after a geometric number of visits -

Example : two-state MC. $\alpha \in (0, 1]$



2 RECURRENCE / TRANSIENCE FOR THE SRW ON \mathbb{Z}^d .

In this section we consider the SRW (simple random walk on \mathbb{Z}^d):

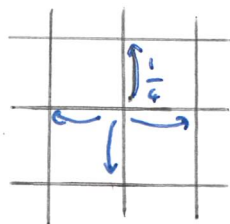
$E = \mathbb{Z}^d, d \geq 1$ $p_{x,y} = \begin{cases} \frac{1}{2d} & \text{if } |x_1 - y_1| + \dots + |x_d - y_d| = 1 \\ 0 & \text{otherwise.} \end{cases}$

Thm: For the SRW (ie the chain with transition p as above),

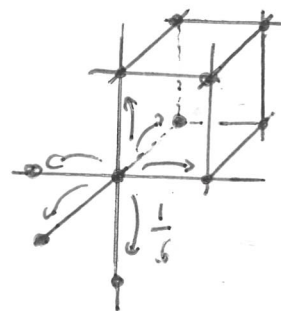
- every state is
- recurrent if $d = 1, 2,$
- transient if $d \geq 3$.



$d = 1$



$d = 2$



$d = 3$

Proof: Let $(Z_k)_{k \geq 1}$ be iid n.v. (on some $(\Omega, \mathcal{F}, \mathbb{P})$)

with $\mathbb{P}[Z_1 = \pm e_i] = \frac{1}{2d}$ $i = 1, \dots, d$.

Define $X_n = \sum_{k=1}^n Z_k \rightarrow (X_n)_{n \geq 0}$ is a MC (S_0, P)

$$E[V_0] = E\left[\sum_{n \geq 1} \mathbb{1}_{X_n=0}\right] = \sum_{n \geq 1} \mathbb{P}[X_n=0]$$

💡 $\mathbb{P}[X_n=x] = \mathbb{P}[Z_1 + \dots + Z_n = x] = \sum_{\delta_1 + \dots + \delta_n = x} \mathbb{P}[Z_1 = \delta_1] \dots \mathbb{P}[Z_n = \delta_n]$

\hookrightarrow not easy to calculate...

$$\left(\mathbb{P}[X_n=x]\right)_{x \in \mathbb{Z}^d} \xleftrightarrow[\text{transform}]{\text{Fourier}} E[e^{iX_n}] = E[e^{iZ_1}]^n$$

easy to calculate

Define $\forall \varphi \in \mathbb{T}^d := [-\pi, \pi)^d$ $\varphi(\varphi) = E[e^{i\varphi \cdot Z_1}]$,

$$\begin{aligned} \text{We have } \varphi(\varphi) &= \frac{1}{2^d} \sum_{i=1}^d (e^{i\varphi \cdot e_i} + e^{-i\varphi \cdot e_i}) \\ &= \frac{1}{d} \sum_{i=1}^d \cos(\varphi_i) \end{aligned}$$

Fix $n \geq 0$: By independence, the characteristic function of X_n is

$$\begin{aligned} \varphi_{X_n}(\varphi) &:= E[e^{i\varphi \cdot X_n}] = E[e^{i\varphi \cdot Z_1 + \dots + i\varphi \cdot Z_n}] \\ &= \varphi(\varphi)^n \end{aligned}$$

By Fourier inversion, we have

$$\mathbb{P}[X_n = 0] = \frac{1}{(2\pi)^d} \int_{\mathbb{T}^d} \varphi(\mathcal{Y})^n d\mathcal{Y}$$

(This can be checked directly:

$$\int_{[0, 2\pi)^d} \varphi(\mathcal{Y})^n d\mathcal{Y} = \int_{[-\pi, \pi)^d} \sum_{x \in \mathbb{Z}^d} \mathbb{P}[X_n = x] e^{i\mathcal{Y} \cdot x} d\mathcal{Y}$$

$$\begin{aligned} & \stackrel{\text{Fub.}}{=} \sum_{x \in \mathbb{Z}^d} \mathbb{P}[X_n = x] \underbrace{\int_{[0, 2\pi)^d} e^{i\mathcal{Y} \cdot x} d\mathcal{Y}}_{= \begin{cases} (2\pi)^d & x=0 \\ 0 & x \neq 0 \end{cases}} \end{aligned}$$

Therefore,

$$(2\pi)^d \sum_{n \geq 0} \mathbb{P}[X_n = 0] = \sum_{n \geq 1} \int_{\mathbb{T}^d} \varphi(\mathcal{Y})^n d\mathcal{Y}$$

monotone convergence $\nearrow = \lim_{\alpha \nearrow 1} \sum_{n \geq 1} \int_{\mathbb{T}^d} (\alpha \varphi(\mathcal{Y}))^n d\mathcal{Y}$

Fubini. $\nearrow = \lim_{\alpha \nearrow 1} \int_{\mathbb{T}^d} \frac{1}{1 - \alpha \varphi(\mathcal{Y})} d\mathcal{Y}$

monotone convergence $\nearrow = \int_{\mathbb{T}^d} \frac{1}{1 - \varphi(\mathcal{Y})} d\mathcal{Y}$

Using $\forall \varphi_i \in [-\pi, \pi)$ $\frac{\varphi_i^2}{4} \leq 1 - \cos(\varphi_i) \leq \frac{\varphi_i^2}{2}$ (8)

we get $\frac{1}{4d} \|\varphi\|_2^2 \leq 1 - \varphi(\varphi) \leq \frac{1}{2d} \|\varphi\|_2^2$,

And therefore

$$\sum \mathbb{P}[X_n = 0] < \infty \Leftrightarrow \int_{B(0,1)} \frac{d\varphi}{\|\varphi\|_2^2} < \infty$$

$$\Leftrightarrow d > 2$$

(For the last equivalence, we can use a change of variable

into polar coordinates $\int_{B(0,1)} \frac{d\varphi}{\|\varphi\|_2^2} = \int_{n=0}^1 \frac{\text{Area}(\partial B(0,r))}{r^2} dr$
 $= C \int_{n=0}^1 r^{d-3} dr$.

or, one can use homogeneity: Define $A_i = B(0, \frac{1}{2^i}) \setminus B(0, \frac{1}{2^{i+1}})$

Using the change of variable $\Psi = 2^i \varphi$, we find

$$\int_{A_i} \frac{d\varphi}{\|\varphi\|_2^2} = \int_{A_0} \frac{2^{2i} d\Psi}{\|\Psi\|_2^2} \times (2^i)^{-d} d\Psi = (2^i)^{2-d} \int_{A_0} \frac{d\Psi}{\|\Psi\|_2^2} =: I_0$$

Therefore $\int_{B(0,1)} \frac{d\varphi}{\|\varphi\|_2^2} = \sum_{i=0}^{\infty} \int_{A_i} \frac{d\varphi}{\|\varphi\|_2^2} = I_0 \sum_{i=0}^{\infty} (2^i)^{2-d}$
 $< \infty$ iff $d > 2$ □

3 CLASSIFICATION OF STATES.

Thm: Let $x, y \in E$ such that $x \rightarrow y$.

If x is recurrent, then y is recurrent and

$$P_x [H_y < \infty] = P_y [H_x < \infty] = 1. \text{ (in particular we have } x \leftrightarrow y \text{)}$$



at each visit of x , the chain has > 0 probability to hit y . since x is visited infinitely many times, y must also be visited infinitely many times.

Proof: Assume $y \neq x$ and x recurrent

Let $x, z_1, \dots, z_{k-1}, y$ distinct such that $p_{xz_1}, \dots, p_{z_{k-1}y} > 0$

$$\text{We have } 0 = P_x [H_x = +\infty]$$

$$\geq P_x [X_1 = z_1, \dots, X_k = y, \forall n \geq 1 \quad X_{k+n} \neq x]$$

$$\stackrel{\text{SiMP}}{=} \underbrace{P_x [X_1 = z_1, \dots, X_k = y]}_{> 0} \underbrace{P_y [\forall n \geq 1 \quad X_n \neq x]}_{= P_y [H_x = +\infty]}$$

Hence $P_y [H_x < \infty] = 1$.

Now, let us prove that y is recurrent. Define

$$m, n \text{ s.t. } P_{xy}^{(n)}, P_{yx}^{(m)} > 0.$$

$$\text{We have } E_y[V_y] = \sum_{k \geq 1} P_{yy}^{(k)} \geq \sum_{k \geq 1} P_{yy}^{(m+k+n)}$$

$$\stackrel{CK}{\geq} \underbrace{P_{yx}^{(m)}}_{>0} \underbrace{\left(\sum_{k \geq 1} P_{xx}^{(k)} \right)}_{=+\infty} \underbrace{P_{xy}^{(n)}}_{>0}$$

Therefore y is recurrent. It remains to prove

$P_x[H_y < \infty] = 1$, which follows from $y \rightarrow x$ and y is recurrent, as before. ■

Corollary 1: Let C be a communication class for p .

Either $\forall x \in C$, x is recurrent, ("C is recurrent")

or $\forall x \in C$, x is transient. ("C is transient")

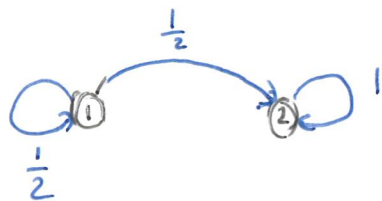
Proof: If $x \leftrightarrow y$ we have $(x \text{ recurrent}) \Leftrightarrow (y \text{ recurrent})$. ■

Corollary 2: A recurrent class is always closed.

pp: Let C be a recurrent class. If $x \in C$ and $x \rightarrow y$ then we must have $y \rightarrow x$ (because x recurrent), therefore $y \in C$.

Corollary 2 give a criterion for transience: If $x \rightarrow y$ but $y \not\rightarrow x$, then x is transient.

Example:



$1 \rightarrow 2$ but $2 \not\rightarrow 1$. Hence 1 is transient.

In general one can always partition

$$E = T \cup R_1 \cup R_2 \cup \dots$$

where $T = \{x : x \text{ is transient}\}$ "T is the union of all the transient classes"
 R_1, R_2, \dots are the recurrent classes.

If the chain starts at $x \in R_i$, then $X_n \in R_i \forall n \geq 1$ a.s.

If it starts at $x \in T \xrightarrow{\text{case 1}} \forall n X_n$ stays on T

$\xrightarrow{\text{case 2}}$ X_n moves at some time to some R_i and stays there.

4 POSITIVE / NULL RECURRENCE

Notation: For $x \in E$ $m_x := E_x[H_x]$

Def: Let x be a recurrent state [i.e. $P_x[H_x < \infty] = 1$]

We say that x is • positive recurrent if $m_x < \infty$

• null recurrent if $m_x = +\infty$.

Thm: [density of visit times]

Let $x, y \in E$ s.t. $x \leftrightarrow y$. Then

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n P_{xy}^{(k)} = \frac{1}{m_y}$$

Rk: Write $V_y^{(n)} = \sum_{k=1}^n \mathbb{1}_{X_k=y}$ "visits of y before time n "

$\frac{1}{n} \sum_{k=1}^n P_{xy}^{(k)} = E_x \left[\frac{V_y^{(n)}}{n} \right]$ "expected proportion of time spent at y "

If y transient or null-recurrent ($m_y = +\infty$)

$$\lim_{n \rightarrow \infty} E_x \left[\frac{V_y^{(n)}}{n} \right] = 0 \quad \text{"null density of visits."}$$

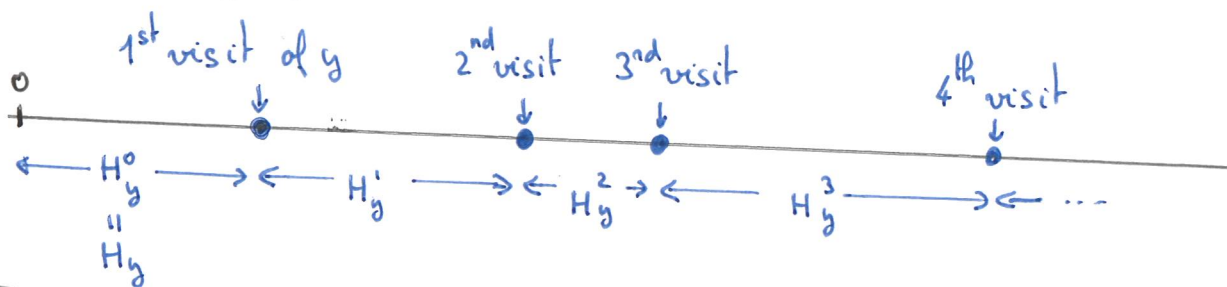
If y positive recurrent:

$$\lim_{n \rightarrow \infty} E_x \left[\frac{V_y^{(n)}}{n} \right] > 0 \quad \text{">0 density of visits."}$$

Def [inter-visit time]

Let $y \in E$. Define $H_y^0 = H_y$ and by induction

$$\forall i \geq 1 \quad H_y^i := \begin{cases} \min \{ n \geq 1 : X_{H_y^0} + \dots + X_{H_y^{i-1}+n} = y \} & \text{if } H_y^{i-1} < \infty \\ +\infty & \text{if } H_y^{i-1} = +\infty. \end{cases}$$



Lemma: Let $x, y \in E$ s.t. $x \leftrightarrow y$. Assume that y is recurrent.

Then for every $j \geq 1$, $t_0, \dots, t_j \in \mathbb{N}$.

$$P_x [H_y^0 = t_0, \dots, H_y^j = t_j] = P_x [H_y = t_0] P_y [H_y = t_1] \dots P_y [H_y = t_j]$$

In particular, under P_x , $H_y^1, \dots, H_y^j, \dots$ are iid with law $P_x [H_y^j = t] = P_y [H_y = t]$

Proof: By induction on j . (for simplicity, we write $H^i = H_y^i$)

By def. we have $\forall t \in \mathbb{N} \quad P_x [H^0 = t] = P_x [H_y = t]$.

Let $j \geq 0$ and assume that the equation holds.

First, observe that

$$\begin{aligned} P_x [H^0 < \infty, \dots, H^j < \infty] &= \sum_{t_0, \dots, t_j} P_x [H^0 = t_0, \dots, H^j = t_j] \\ &= \underbrace{P_x [H_y < \infty]}_{=1} \cdot \underbrace{P_y [H_y < \infty]^j}_{=1} = 1. \end{aligned}$$

Hence the stopping time $T = H_y^0 + \dots + H_y^j$ is finite P_x -a.s.

and $X_T = y$ by definition. Hence,

for every $t_0, \dots, t_{j+1} \in \mathbb{N}$, we have

$$P_x [H^0 = t_0, \dots, H^{j+1} = t_{j+1}] = P_x \left[\underbrace{H^0 = t_0, \dots, H^j = t_j}_{\in \mathcal{F}_T} \mid T < \infty, X_T = y, \underbrace{H^{j+1} = t_{j+1}}_{\min\{n \geq 1: X_{T+n} = y\} = t_{j+1}} \right]$$

St. MP

$$= P_x [H^0 = t_0, \dots, H^j = t_j] P_y [\min\{n \geq 1: X_n = y\} = t_{j+1}]$$

$$\stackrel{\text{induction}}{=} P_x [H_y^0 = t_0] P_y [H_y^1 = t_1] \dots P_y [H_y^j = t_{j+1}] \quad \blacksquare$$

Proof of the theorem.

If y is transient, then, we have $E_y[V_y] < \infty$

and therefore, by the strong Markov property we also

have $E_x[V_y] < \infty$. Hence, for every $n \geq 1$

$$\frac{E_x[V_y^{(n)}]}{n} \leq \frac{E_x[V_y]}{n} \xrightarrow{n \rightarrow \infty} 0.$$

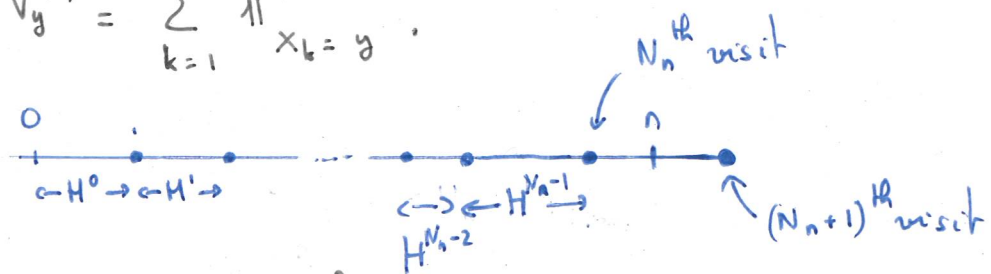
Now let us assume that y is recurrent. By the lemma, the random variables H^1, H^2, \dots are iid under P_x and satisfy $E_x[H^1] = E_y[H_y] = m_y$.

Hence by the law of large numbers, and using $P_x[H^0 < \infty] = 1$, we have

$$\lim_{i \rightarrow \infty} \frac{H^0 + \dots + H^i}{i} = m_y \quad P_x - a.s.$$

(this includes the case $m_y = +\infty$)

Write $N_n = V_y^{(n)} = \sum_{k=1}^n \mathbb{1}_{X_k = y}$.



By definition, we have for every $n \geq 1$

$$H^0 + \dots + H^{N_n-1} \leq n < H^0 + \dots + H^{N_n}$$

Hence for every $n \geq 1$

$$\frac{N_n}{H^0 + \dots + H^{N_n}} < \frac{V_y^{(n)}}{n} \leq \frac{N_n}{H^0 + \dots + H^{N_n-1}}$$

$\xrightarrow{P_x - a.s.} \frac{1}{m_y}$

And we can conclude that $E_x \left[\frac{V_y^{(n)}}{n} \right] \xrightarrow{n \rightarrow \infty} \frac{1}{m_y}$ by dominated cv.

Prop. [Classification of recurrent classes]

Let R be a recurrent class. Then

- either $\forall x \in R$ x is > 0 recurrent, "R is a > 0 rec. class"
- or $\forall x \in R$ x is null recurrent. "R is a null rec. class"

Proof: Let $x, y \in E$ s.t. $x \leftrightarrow y$. Assume x > 0 recurrent.

Fixe $k \geq 0$ s.t. $P_{xy}^{(k)} > 0$

By Chapman-Kolmogorov, we have

$$\forall j \geq 1 \quad P_{xy}^{(k+j)} \geq P_{xx}^{(j)} P_{xy}^{(k)}$$

Hence

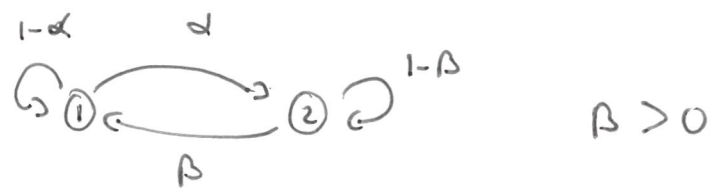
$$\underbrace{\frac{1}{n} \sum_{i=1}^n P_{xy}^{(i)}}_{\downarrow n \rightarrow \infty} \geq \underbrace{\left(\frac{1}{n} \sum_{j=1}^{n-k} P_{xx}^{(j)} \right)}_{\downarrow n \rightarrow \infty} \underbrace{P_{xy}^{(k)}}_{> 0}$$

$$\frac{1}{E_y[H_y]} \geq \frac{1}{E_x[H_x]} P_{xy}^{(k)}$$

Therefore $\frac{1}{E_y[H_y]} > 0$ and y is > 0 recurrent.

Examples:

• 2-state MC



For $k \geq 1$ $P_1[H_1 \geq k] = P_1[X_1 = \dots = X_{k-1} = 2]$
 $= \alpha(1-\beta)^{k-1}$

Hence $E_1[H_1] = \sum_k \alpha(1-\beta)^{k-1} < \infty$ 1 is > 0 -rec.

• SRW on \mathbb{Z} .



We have

$$P_0 [H_0 \geq k] \geq P_0 [X_1 = -1, \max_{1 \leq m \leq k} (X_m) \leq -1]$$

$$\stackrel{\text{SIMP}}{=} P_0 [X_1 = -1] P_{-1} [\max_{0 \leq m \leq k-1} (X_m) \leq -1]$$

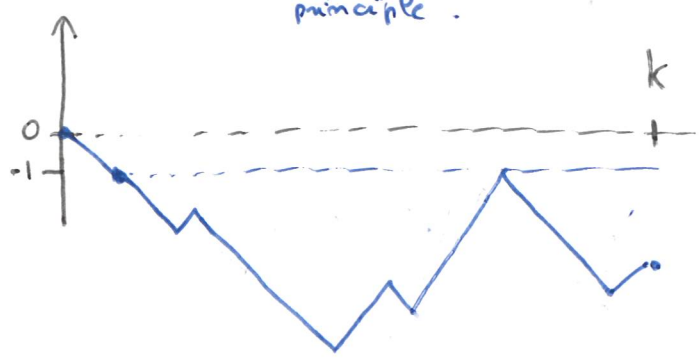
$$\stackrel{\uparrow}{=} \frac{1}{2} P_0 [\max_{0 \leq m \leq k-1} (X_m) \leq 0]$$

translation invariance



$$= P_0 [|X_{k-1}| = 0] \text{ if } k \text{ is odd}$$

reflection principle



$$\text{Hence } E_0 [H_0] \geq \sum_{\substack{k \text{ odd} \\ k \geq 1}} P_0 [|X_{k-1}| = 0] = +\infty$$

because the SRW on \mathbb{Z} is recurrent.

Hence 0 is null-recurrent (and therefore every $x \in \mathbb{Z}$ is null-recurrent by irreducibility)

We finish this section with a simple condition ensuring positive recurrence

Prop. Any finite recurrent class is positive recurrent. In particular, if E is finite, then every recurrent state is >0 recurrent.

Proof: Let R be a finite recurrent class, $x \in R$. Since R is closed we have for every $n \geq 1$

$$1 = P_x [X_n \in R] = \sum_{y \in R} P_{xy}^{(n)}$$

Hence $1 = \sum_{y \in R} \left(\frac{1}{n} \sum_{k=1}^n P_{xy}^{(k)} \right)$
 $\quad \quad \quad \underbrace{\hspace{10em}}_{\xrightarrow{n \rightarrow \infty} \frac{1}{E_y[H_y]}}$

Therefore, there must exist $y \in R$ s.t. $E_y[H_y] < \infty$, which implies that the class is >0 recurrent. ■

5. STATIONARY DISTRIBUTIONS FOR IRREDUCIBLE CHAINS.

Theorem: Assume that p is irreducible.

- If the chain is transient or null recurrent, then there is no stationary distribution.
- If the chain is >0 recurrent, then there exists a unique stationary distribution, given by

$$\forall x \in E \quad \pi(x) = \frac{1}{E_x[H_x]}$$

Proof. Assume that the chain is transient or null recurrent

Assume for contradiction that there exists a stationary distribution π . For every $x \in E$, we have

$$\begin{aligned} \forall n \geq 1 \quad \pi(x) &= \frac{1}{n} \sum_{k=1}^n P_{\pi} [X_k = x] \\ &\stackrel{\text{Fubini}}{=} \sum_{y \in E} \pi(y) \underbrace{\frac{1}{n} \sum_{k=1}^n P_y [X_k = x]}_{\xrightarrow{n \rightarrow \infty} \frac{1}{E_x[H_x]} = 0} \end{aligned}$$

Hence, by dominated convergence, we have

$$\forall x \in E \quad \pi(x) = \frac{1}{E_x[H_x]} = 0,$$

which contradicts $\sum_{x \in E} \pi(x) = 1$.

• Now assume that the chain is >0 recurrent.

The same calculation as before shows that the only possible candidate is given by

$$\forall x \quad \pi(x) := \frac{1}{E_x[H_x]}$$

To conclude one needs to prove that the measure defined above is indeed a stationary distribution.

First, fix $k \geq 1$. We have

$$\begin{aligned} \forall y \in E \quad \frac{1}{E_y[H_y]} &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{j=k}^n P_{yy}^{(j)} \\ &\stackrel{CK}{=} \lim_{n \rightarrow \infty} \sum_{x \in E} \left(\frac{1}{n} \sum_{j=k}^n P_{yx}^{(j-k)} \right) P_{xy}^{(k)} \\ &\stackrel{\text{Fatou}}{\geq} \sum_{x \in E} \liminf_{n \rightarrow \infty} \left(\frac{1}{n} \sum_{j=k}^n P_{yx}^{(j-k)} \right) P_{xy}^{(k)} \\ &= \sum_{x \in E} \frac{1}{E_x[H_x]} P_{xy}^{(k)} \end{aligned}$$

Similarly, we have, for a fixed x

$$\begin{aligned} 1 &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{j=1}^n P_x[X_j \in E] = \lim_{n \rightarrow \infty} \sum_{y \in E} \frac{1}{n} \sum_{j=1}^n P_x[X_j = y] \\ &\stackrel{\text{Fatou}}{\geq} \sum_{y \in E} \frac{1}{E_y[H_y]} \end{aligned}$$

In order to conclude one needs to prove that the two inequalities above are equalities.

First by summing the first inequality over y we have

$$\sum_{y \in E} \frac{1}{E_y[H_y]} \geq \sum_{y \in E} \left(\sum_{x \in E} \frac{1}{E_x[H_x]} P_{xy}^{(k)} \right) = \sum_{x \in E} \frac{1}{E_x[H_x]}$$

And therefore the inequality (1) should be an equality and we have for every $k \geq 1$

$$\forall y \quad \frac{1}{E_y[H_y]} = \sum_{x \in E} \frac{1}{E_x[H_x]} P_{xy}^{(k)} \quad (*)$$

We now use this equality to prove that (2) is also an equality. Fix $y \in E$. (By >0 recurrence, $\frac{1}{E_y[H_y]} > 0$)

$$\begin{aligned} \text{We have} \quad \frac{1}{E_y[H_y]} &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n \left(\sum_{x \in E} \frac{1}{E_x[H_x]} P_{xy}^{(k)} \right) \\ &= \lim_{n \rightarrow \infty} \sum_{x \in E} \frac{1}{E_x[H_x]} \times \left(\frac{1}{n} \sum_{k=1}^n P_{xy}^{(k)} \right) \end{aligned}$$

$$\stackrel{\text{(dominated convergence)}}{=} \sum_{x \in E} \frac{1}{E_x[H_x]} \times \frac{1}{E_y[H_y]}$$

Hence $\pi(x) = \frac{1}{E_x[H_x]}$ defines a distribution, which is stationary, by (*).

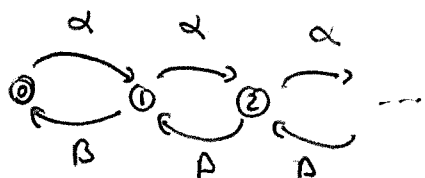
Applications

- The SRW on \mathbb{Z} is null-recurrent.

(We already prove this result by showing $E_0[H_0] = +\infty$, here we give a second proof).

The SRW on \mathbb{Z} is recurrent, but has no stationary distribution, hence it is null recurrent.

- Consider the reflected random walk on \mathbb{N} $\alpha + \beta = 1$ $\alpha < \beta$



$$E = \mathbb{N}$$

$$P_{i,i+1} = \alpha \quad i \geq 1$$

$$P_{i,i-1} = \beta \quad i \geq 1$$

$$P_{0,1} = 1$$

One can check that $\lambda_i = \left(\frac{\alpha}{\beta}\right)^i$ $i \geq 1$ and $\lambda_0 = \alpha$

defines an invariant measure $(\forall i \geq 1 \quad \lambda_i = \lambda_{i-1}\alpha + \lambda_{i+1}\beta$
and $\lambda_0 = \lambda_1\beta)$

Therefore $\pi_i = \frac{1}{\sum_{j \geq 0} \lambda_j} \lambda_i$ is a stationary distribution

The reflected random is > 0 recurrent if $\alpha < \beta$.

6 PERIODICITY.

Def. Let $x \in E$. The period of x is defined by

$$d_x = \gcd \{ n \geq 1 : P_{xx}^{(n)} > 0 \}.$$

(Convention: $\gcd(\emptyset) = +\infty$)

Prop. Let $x, y \in E$ s.t. $x \leftrightarrow y$. Then $d_x = d_y$.

Proof: Let $x \neq y$. We prove that $d_y \mid d_x$.

First, let us fix $k, l \geq 0$ s.t. $P_{yy}^{(k)}, P_{xy}^{(l)} > 0$

Since $P_{yy}^{(k+l)} \geq P_{yx}^{(k)} P_{xy}^{(l)} > 0$ we have $d_y \mid k+l$.

Now, we prove that d_y is a common divisor of $\{ n \geq 1 : P_{xx}^{(n)} > 0 \}$. (this will imply $d_y \mid d_x$)

For every $n \geq 1$ satisfying $P_{xx}^{(n)} > 0$, we have

$$P_{yy}^{(k+n+l)} \geq P_{yx}^{(k)} P_{xx}^{(n)} P_{xy}^{(l)} > 0,$$

hence $d_y \mid k+l+n$. Since $d_y \mid k+l$, we also have $d_y \mid n$. ■

Consequence: if the chain is irreducible, we have

$$\forall x, y \in E \quad d_x = d_y.$$

Def: We say that the chain p is aperiodic if

$$\forall x \in E \quad d_x = 1$$

Prop: Let $x \in E$. We have

$$(d_x = 1) \Leftrightarrow (\exists n_0 \geq 1 \text{ s.t. } \forall n \geq n_0 \quad p_{xx}^{(n)} > 0)$$

We use the following lemma from number theory -

Lemma: Let $A \subset \mathbb{N} \setminus \{0\}$ stable under addition

($x, y \in A \Rightarrow x + y \in A$). Then

$$(\gcd(A) = 1) \Leftrightarrow (\exists n_0 \in \mathbb{N} \text{ s.t. } \{n \in \mathbb{N} : n \geq n_0\} \subset A)$$

Proof: \Leftarrow follows from the fact that $\gcd(n_0, n_0+1) = 1$

\Rightarrow Assume $\gcd(A) = 1$. Let $a \in A$ arbitrary and $a = \prod_{i=1}^k p_i^{\alpha_i}$ be its prime factorization ($k \geq 0$, p_1, \dots, p_k primes, $\alpha_1, \dots, \alpha_k \geq 1$)

Since $\gcd(A) = 1$, one can find $b_1, \dots, b_k \in A$ s.t. $\forall i \quad p_i \nmid b_i$. This implies

$$\gcd(a, b_1, \dots, b_k) = 1.$$

Write $d = \gcd(b_1, \dots, b_k)$. By Bezout (Reem), we can pick $u_1, \dots, u_k \in \mathbb{Z}$ s.t.

$$u_1 b_1 + \dots + u_k b_k = d$$

Now, choose an integer λ large enough s.t.
 $w_i + \lambda a \geq 0$ for every i and define

$$b = (u_1 + \lambda a) b_1 + \dots + (u_k + \lambda a) b_k \\ = d + \lambda (b_1 + \dots + b_k) a$$

The first expression shows that $b \in A$, and the second expression implies that $\gcd(a, b) = \gcd(a, d) = 1$

To summarize, we found $a, b \in A$ s.t.

$$\gcd(a, b) = 1.$$

Without loss of generality, we may assume $a < b$. Since $\gcd(a, b) = 1$, the set $B = \{b, 2b, \dots, ab\}$ covers all the residue classes modulo a . Since $a < b$, this implies that $B + \{ka, k \in \mathbb{N}\}$ includes every number $\geq ab$.

This concludes the proof of the lemma by choosing $n_0 = ab$ ■

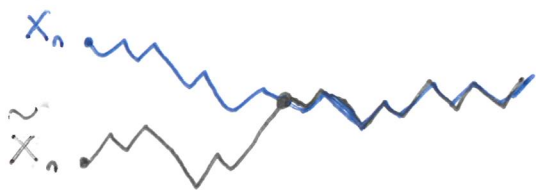
Proof of the proposition:

The set $A_x = \{n \geq 1 \text{ s.t. } p_{xx}^{(n)} > 0\}$ is stable under addition because $p_{xx}^{(m+n)} \geq p_{xx}^{(m)} p_{xx}^{(n)}$ for every $m, n \geq 1$.

The proof follows by applying the lemma to $A = A_x$ ■

7 THE COUPLING METHOD.

Goal: define two Markov chains $(X_n) \sim MC(p, p)$ and $(\tilde{X}_n) \sim MC(v, p)$ on the same probability space such that $X_n = \tilde{X}_n$ for n large.



To achieve that we first consider two independent chains $(X_n), (Y_n)$. We show that the two chains meet a.s. (under some assumptions on p) at some random time T . And then, we ask that the chains follow the same trajectory for $t \geq T$.

In order to introduce a suitable probability space, we consider the product chain, defined below.

Def: [Product chain]

Define for every $w = (x, y)$ and $w' = (x', y')$ in E^2

$$\bar{P}_{w, w'} = P_x x' P_y y'.$$

Rk: $\sum_{w' \in E^2} \bar{P}_{w, w'} = \sum_{x', y' \in E} P_x x' P_y y' = 1.$

Therefore \bar{P} is a transition probability on E^2 .

Notation: Consider

• $(\Omega, \mathcal{F}, (P_w)_{w \in E^2})$ proba spaces.

• $(W_n)_{n \geq 0} = (X_n, Y_n)_{n \geq 0}$ n.v. on (Ω, \mathcal{F}) s.t.

$\forall w \in E^2$ W_n is MC (S_w, \bar{P}) under P_w

[If μ, ν are distributions on E . $\mu \otimes \nu$ is a distribution on E^2 and we write.

$$P_{\mu \otimes \nu} = \sum_{(x,y) \in E^2} \mu(x) \nu(y) P_{(x,y)} \quad]$$

Prop: Let μ, ν be two distributions on E .

Under $P_{\mu \otimes \nu}$, $(X_n)_{n \geq 0}$ is MC (μ, p) and $(Y_n)_{n \geq 0}$ is MC (ν, p) and they are independent.

Proof: For every $k \geq 0$ $x_0, \dots, x_k, y_0, \dots, y_k \in E$ we have

$$\begin{aligned} & P_{\mu \otimes \nu} [X_0 = x_0, \dots, X_k = x_k, Y_0 = y_0, \dots, Y_k = y_k] \\ &= P_{\mu \otimes \nu} [W_0 = (x_0, y_0) \dots W_k = (x_k, y_k)] \\ &= \mu(x_0) p_{x_0, x_1} \dots p_{x_{k-1}, x_k} \nu(y_0) p_{y_0, y_1} \dots p_{y_{k-1}, y_k} \end{aligned}$$

By summing over all possible $y_0, \dots, y_k \in E$, this implies that $(X_n)_n$ is MC (μ, p) , and equivalently

$(Y_n)_n$ is MC (ν, p) .

To prove independence we need to show that for every measurable sets $A, B \subset E^N$

$$P_{x_0,0} [X \in A, Y \in B] = P_{x_0,0} [X \in A] P_{y_0,0} [Y \in B]$$

The computation above shows that it holds for sets of the form $A = \{(x_0, \dots, x_k)\} \times E^N$ $B = \{(y_0, \dots, y_l)\} \times E^N$.

Therefore, it holds for every cylindrical sets, and then for any measurable sets, by Dynkin's lemma. ■

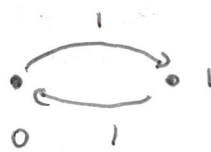
Proposition:

If the chain p is irreducible, aperiodic and >0 recurrent, then \bar{p} is also irreducible, aperiodic and >0 recurrent.

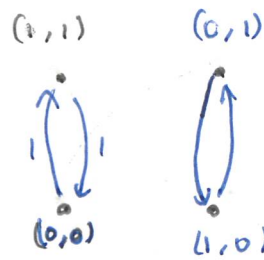
Rk: p irreducible $\not\Rightarrow \bar{p}$ irreducible in general.

(aperiodicity is important)

for example



p irreducible



\bar{p} not irreducible

Proof: Let $w = (x, y), w' = (x', y') \in E^2$. By irreducibility, one can pick $k, l \geq 0$ s.t. $P_{xx'}^{(k)}, P_{yy'}^{(l)} > 0$.

For every $n \geq \max(k, l)$ we have

$$\bar{P}_{ww'}^{(n)} = P_{xx'}^{(n)} P_{yy'}^{(n)} \underset{CK}{\geq} P_{xx'}^{(k)} \underbrace{P_{xx'}^{(n-k)}}_{>0 \text{ for } n \text{ large}} P_{yy'}^{(l)} \underbrace{P_{yy'}^{(n-l)}}_{>0 \text{ for } n \text{ large}} > 0 \quad \uparrow \text{ for } n \text{ large}$$

This proves that \bar{p} is irreducible aperiodic.

Since p is irr., >0 recurrent, it admits a stationary distribution π . For every $(y, y') \in E^2$,

we have

$$\pi(y) \times \pi(y') = \sum_{x \in E} \pi(x) p_{xy} \sum_{x' \in E} \pi(x') p_{x'y'}$$

$$= \sum_{(x, x') \in E^2} \pi(x) \pi(x') p_{xy} p_{x'y'}$$

Hence $\pi \otimes \pi$ is stationary for \bar{p} , which implies that

\bar{p} is >0 recurrent. ■

Def. $T := \min \{ n \geq 0 : X_n = Y_n \}$

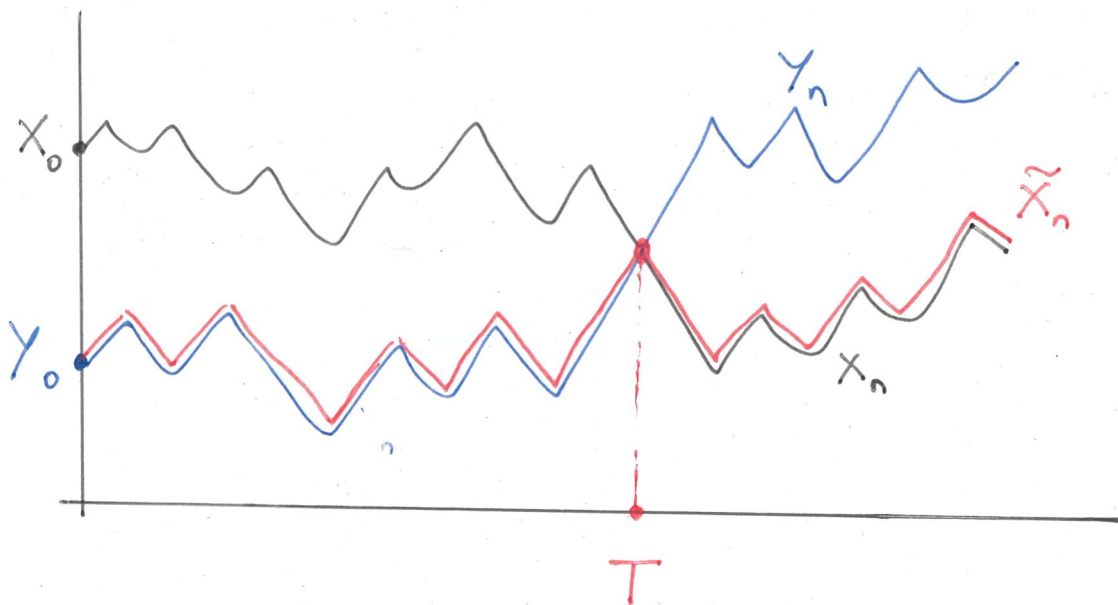
Rk: $T = H_A$ where $A = \{ (x, y) \in E^2 : x = y \}$
and therefore T is a stopping time.

Prop: For every μ, ν distributions on E .

$$\forall n \geq 0 \quad \sum_{x \in E} |P_\mu[X_n = x] - P_\nu[X_n = x]| \leq 2P_{\mu \otimes \nu}[T > n]$$

Proof: We consider the product Markov chain $W_n = (X_n, Y_n)$
under $P_{\mu \otimes \nu}$. Define for every n

$$\tilde{X}_n = \begin{cases} Y_n & \text{if } n < T \\ X_n & \text{if } n \geq T \end{cases}$$



We prove that (\tilde{X}_n) is MC (ν, P) under $P := P_{Y \otimes \nu}$

Let $n \geq 0$ and $x_0, \dots, x_n \in E$. By distinguishing between the possible values for T , we have

$$P[\tilde{X}_0 = x_0, \dots, \tilde{X}_n = x_n] = \sum_{k \in \mathbb{N} \cup \{\infty\}} P[\tilde{X}_0 = x_0, \dots, \tilde{X}_n = x_n, T = k]$$

If $k > n$, the summand is equal to

$$\nu(x_0) P_{x_0, x_1, \dots, P_{x_{n-1}, x_n}} \times P[T = k \mid Y_0 = x_0, \dots, Y_n = x_n]$$

If $k \leq n$, the summand is equal to

$$P[\underbrace{Y_0 = x_0, \dots, Y_k = x_k}_{\in \mathcal{G}_T}, T = k, X_{T+1} = x_{k+1}, \dots, X_{T+n-k} = x_n]$$

$$\begin{aligned} \text{St M.P} &= P[Y_0 = x_0, \dots, Y_k = x_k, T = k] \times P_{(x_k, x_k)}[X_1 = x_{k+1}, \dots, X_{n-k} = x_n] \\ &= \nu(x_0) P_{x_0, x_1, \dots, P_{x_{k-1}, x_k}} P[T = k \mid Y_0 = x_0, \dots, Y_k = x_k] \cdot \dots = P_{x_k, x_{k+1}, \dots, P_{x_{n-1}, x_n}} \end{aligned}$$

$$= \nu(x_0) P_{x_0, x_1, \dots, P_{x_{n-1}, x_n}} \times P[T = k \mid Y_0 = x_0, \dots, Y_n = x_n]$$

For the last equality we use independence between $(X_n)_n$ and $(Y_n)_n$ to write $P[T = k \mid Y_0 = x_0, \dots, Y_k = x_k]$ as $P[\forall i < k X_i \neq x_i, X_k = x_k] = P[T = k \mid Y_0 = x_0, \dots, Y_n = x_n]$

Finally using $\sum_{k \in \mathbb{N} \cup \{\infty\}} P[T=k | Y_0=x_0, \dots, Y_n=x_n] = 1$,

we obtain

$$IP[\tilde{X}_0=x_0, \dots, \tilde{X}_n=x_n] = v(x_0) p_{x_0, x_1} \dots p_{x_{n-1}, x_n}$$

We use the coupling between $(X_n)_n$ and $(\tilde{X}_n)_n$ to conclude the proof. For every $n \geq 0$

$$\begin{aligned} \sum_{x \in E} |P_y[X_n=x] - P_0[X_n=x]| &= \sum_{x \in E} |IP[X_n=x] - IP[\tilde{X}_n=x]| \\ &= \sum_{x \in E} |IP[X_n=x, T \leq n] + IP[X_n=x, T > n] - IP[\tilde{X}_n=x, T \leq n] - IP[\tilde{X}_n=x, T > n]| \\ &\leq \sum_{x \in E} IP[X_n=x, T > n] + IP[\tilde{X}_n=x, T > n] = 2 IP[T > n] \quad \blacksquare \end{aligned}$$

8 CONVERGENCE FOR IRREDUCIBLE APERIODIC CHAINS -

Thm Assume that the chain p is irreducible aperiodic and admits a stationary distribution π .
 Then for every distribution μ on E and every $x \in E$

$$\lim_{n \rightarrow \infty} P_y[X_n=x] = \pi(x)$$

Rk: Equivalently

- Under P_μ $X_n \xrightarrow[n \rightarrow \infty]{(law)}$ X_∞ where $X_\infty \sim \pi$.
- $\forall f : E \rightarrow \mathbb{R}$ bounded

$$\lim_{n \rightarrow \infty} E_\mu [f(X_n)] = \int_E f d\pi.$$

Proof: Consider the product chain $(X_n, Y_n)_{n \geq 0}$ introduced in the previous section. Since \bar{p} is irreducible, ≥ 0 recurrent, the stopping time $T = \min\{n \geq 0 : X_n = Y_n\}$ is finite $P_{\mu \otimes \pi}$ -a.s. (indeed for a fixed $a \in E$, we have $T \leq H_{(a,a)} < \infty$ a.s.). For every $x \in E$

$$\begin{aligned} |P_\mu [X_n = x] - \pi(x)| &= |P_\mu [X_n = x] - P_{\pi \otimes \pi} [X_n = x]| \\ &\leq 2 P_{\mu \otimes \pi} [T > n] \xrightarrow[n \rightarrow \infty]{} 0 \quad \blacksquare \end{aligned}$$

Thm: Assume that the chain p is irreducible aperiodic, null recurrent or transient. Then for every distribution μ and every $x \in E$ we have

$$\lim_{n \rightarrow \infty} P_\mu [X_n = x] = 0$$

Lemma: Assume that the product chain \bar{p} is irreducible recurrent. Then for every distribution μ and every $i \geq 0$, we have

$$\lim_{n \rightarrow \infty} |P_{\mu} [X_n = x] - P_{\mu} [X_{n+i} = x]| = 0$$

Proof: Define $\mu_i(y) = P_{\mu} [X_i = y]$ (" $\mu_i = \mu P^i$ ")

Observe that

$$\begin{aligned} P_{\mu_i} [X_n = x] &= \sum_y \mu_i(y) P_y [X_n = x] \\ &\stackrel{\text{SIMP}}{=} \sum_y P_{\mu} [X_i = y] P_y [X_{n+i} = x | X_i = y] \\ &= P_{\mu} [X_{n+i} = x] \end{aligned}$$

Consider the product chain $(X_n, Y_n)_{n \geq 0}$ under $P_{\mu} \otimes \mu_i$ and define $T = \min \{ n : X_n = Y_n \}$. ($T < \infty$ a.s. since \bar{p} is rec.)

$$\begin{aligned} \text{Hence } |P_{\mu} [X_n = x] - P_{\mu} [X_{n+i} = x]| &= |P_{\mu} [X_n = x] - P_{\mu_i} [X_n = x]| \\ &\leq 2 P_{\mu \times \mu_i} [T > n] \xrightarrow{n \rightarrow \infty} 0 \quad \square \end{aligned}$$

Proof of the theorem.

Case 1: Assume that the chain \bar{p} is transient.

Consider the product chain (X_n, Y_n) under $P_{\gamma \otimes \gamma}$.

Since (x, x) is a transient state the last visit time $L := \max \{ n : (X_n, Y_n) = (x, x) \}$ is $< \infty$

$P_{\gamma \otimes \gamma}$ a.s. Hence

$$\begin{aligned} P_{\gamma} [X_n = x]^2 &= P_{\gamma \otimes \gamma} [X_n = x, Y_n = x] \\ &\leq P_{\gamma \otimes \gamma} [L \geq n] \xrightarrow{n \rightarrow \infty} 0 \end{aligned}$$

Case 2: Assume that \bar{p} is recurrent.

Let $y \in E$. we wish to prove

$$P_{y,x}^{(n)} \xrightarrow{n \rightarrow \infty} 0.$$

Fix $\varepsilon > 0$ and k s.t.

$$\frac{1}{k+1} \sum_{i \leq k} P_{x,x}^{(i)} < \varepsilon$$

Define $H = \min \{ j \geq n : X_j = x \}$ (H is a stopping time)

For every $n \geq 0$ we have

$$\frac{1}{k+1} \sum_{i=0}^k P_{\bar{p}} [X_{n+i} = x] \leq \frac{1}{k+1} \sum_{i=0}^k P_{\bar{p}} [X_{H+i} = x]$$

$$\stackrel{\text{Step 1}}{=} \frac{1}{k+1} \sum_{i=0}^k P_{\bar{p}} [X_i = x] \leq \epsilon$$

Now,

$$P_{\bar{p}} [X_n = x] = \frac{1}{k+1} \sum_{i=0}^k P_{\bar{p}} [X_n = x]$$

$$\leq \frac{1}{k+1} \sum_{i=0}^k |P_{\bar{p}} [X_n = x] - P_{\bar{p}} [X_{n+i} = x]|$$

$$+ \underbrace{\frac{1}{k+1} \sum_{i=0}^k P_{\bar{p}} [X_{n+i} = x]}_{\leq \epsilon}$$

Since \bar{p} is irreducible and recurrent, the lemma concludes that

$$\limsup_{n \rightarrow \infty} P_{\bar{p}} [X_n = x] \leq \epsilon$$