

Seminar talk

Consider a system of particles (e.g. a gas) interacting with one another.

Consider further \mathbb{R}^d to be the phase space of one individual particle (rather than the phase space of the entire system).

There are now different viewpoints:

(i) To describe the state of ~~the entire~~ an entire

an the entire system of N particles we consider the individual states ~~$\vec{z}_1(t), \dots, \vec{z}_N(t) \in \mathbb{R}^d$~~ $\in \mathbb{R}^N$

$z_1(t), \dots, z_N(t) \in \mathbb{R}^d$ in phase space. depending

(ii) Let $\mu_t \in \mathcal{P}(\mathbb{R}^d)$ be a probability measure on the phase space \mathbb{R}^d . Then given that the system consists of N particles, ~~we~~ there are ~~(approximately N)~~ $N\mu_t(A)$ particles with state in the region $A \subseteq \mathbb{R}^d$ at time t .

First some definitions:

Definition 1 (Interaction kernel)

We call a function $U: \mathbb{R}^d \times \mathbb{R}^d \longrightarrow \mathbb{R}^d$ satisfying

~~(1111)~~ (i) $U(z, z') = -U(z', z)$ for all $z, z' \in \mathbb{R}^d$
i.e. U is skew symmetric

(ii) $U \in C^1(\mathbb{R}^d \times \mathbb{R}^d, \mathbb{R}^d)$ and

$$\sup_{z' \in \mathbb{R}^d} |D_z U(z, z')| + \sup_{z \in \mathbb{R}^d} |D_{z'} U(z, z')| \leq L$$

an interaction kernel.

Note the following consequence of the definition

Lemma 1 Let $U: \mathbb{R}^d \times \mathbb{R}^d \longrightarrow \mathbb{R}^d$ be an interaction kernel then:

$$(i) \sup_{z' \in \mathbb{R}^d} \|U(z_1, z') - U(z_2, z')\| \leq L \|z_1 - z_2\|$$

$$(ii) \sup_{z \in \mathbb{R}^d} \|U(z, z_1) - U(z, z_2)\| \leq L \|z_1 - z_2\|$$

$$(iii) \|U(z, z')\| \leq L (\|z\| + \|z'\|) \text{ for all } z, z' \in \mathbb{R}^d.$$

For (iii) note that

$$\|U(z, z') - U(z', z')\| \leq \sup_{\substack{z \in \mathbb{R}^d \\ a \in \mathbb{R}^d}} \|U(z, a) - U(z', a)\|$$

$$\leq L(\|z - z'\|) \leq L(\|z\| + \|z'\|).$$

Thus we concluded the proof \square .

~~Definition 2 (empirical measure) The empirical measure of a N -tuple $z_N \in (\mathbb{R}^d)^N$ is a Borel probability measure on \mathbb{R}^d .~~

Let $z_N \in (\mathbb{R}^d)^N$, then with $z_N = (z_1, \dots, z_N)$ define

$$\mu_{z_N} = \frac{1}{N} \sum_{j=1}^N \delta_{z_j}.$$

This is a Borel probability measure, the so called empirical measure.

~~Definition 3~~ ^{Lemma 2} ~~Define~~ the The integral operator

$$K: \mathcal{P}_1(\mathbb{R}^d) \longrightarrow \text{Lip}(\mathbb{R}^d \times \mathbb{R}^d, \mathbb{R}^d) \text{ Lip}(\mathbb{R}^d, \mathbb{R}^d)$$

$$\text{defined by } \mu \longmapsto (K\mu)(z) := \int_{\mathbb{R}^d} U(z, z') d\mu(z')$$

is well defined.

Pf. Follows directly from Lemma 1. \square

Now let us return to the two different perspectives introduced in the beginning:

In view point (i) we described the state of our system of N particles by the individual states

$$z_1(t), \dots, z_N(t) \in \mathbb{R}^d.$$

Now let $V: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ be an interaction kernel, then we denote by $V(z_i, z_j)$ the interaction of the i th and j th particle.

we encode the dynamics of our system into the system system of ODEs

$$\frac{dz_i}{dt}(t) = \sum_{\substack{j=1 \\ j \neq i}}^N V(z_i, z_j) \quad i, j = 1, \dots, N.$$

Since V is skew symmetric $V(z, z) = 0$ for all $z \in \mathbb{R}^d$.

Rescaling the time variable and using this observation we can therefore rewrite the system into the following form:

$$\frac{dz_i}{dt} = \frac{1}{N} \sum_{j=1}^N K(z_i, z_j) \quad i=1, \dots, N. \quad (1)$$

Clearly the ~~probability~~ ^{empirical} measure $\mu_{z_N} = \sum_{j=1}^N \delta_{z_j}$ where $z_N = (z_1, \dots, z_N) \in (\mathbb{R}^d)^N$ is precisely the measure we sought in viewpoint (ii).

It turns out that the dynamics of the system in this viewpoint is controlled by the mean field PDE

$$\partial_t p + \operatorname{div}_z (p U p) = 0 \quad (2)$$

introduced in last week's talk.

We can ~~show~~ ^{prove} that $z_N = (z_1(t), \dots, z_N(t))$ solves (1) if and only if μ_{z_N} solves (2); the first of these directions we will be able to show today:

Theorem 1 Let $K: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ be an interaction

kernel, as defined above. Then

(i) For each $N \geq 1$ and each N -tuple $z_N^{\text{in}} = (z_{11}^{\text{in}}, \dots, z_{1N}^{\text{in}})$

$$(3) \quad \begin{cases} \dot{z}_i(t) = \frac{1}{N} \sum_{j=1}^N K(z_i(t), z_j(t)) & i=1, \dots, N \\ z_i(0) = z_i^{\text{in}} \end{cases}$$

has a unique solution of class C^1 on \mathbb{R} .

$$t \mapsto z_N(t) = (z_1(t), \dots, z_N(t)).$$

(ii) The empirical measure $\mu_{z_N(t)}$ is a weak solution of

$$(4) \quad \begin{cases} \partial_t \mu + \operatorname{div}_z(\mu V \mu) = 0 \\ \mu|_{t=0} = \mu^{\text{in}} := \mu_{z_N^{\text{in}}} \end{cases}$$

Before we continue with the proof, recall:

Theorem 2:

Assume $V \in C([0, T] \times \mathbb{R}^N, \mathbb{R}^N)$,

$$D_x V \in C([0, T] \times \mathbb{R}^N, \mathbb{R}^{N \times N})$$

and $\forall t \in [0, T] \forall x \in \mathbb{R}^N \quad |V(t, x)| \leq K(1 + |x|)$

for some $K \in \mathbb{R}$. Then for all $t \in [0, T]$ and $x \in \mathbb{R}^N$

there exists a unique characteristic defined on $[0, T]$ and satisfying $X(0) = x$. We denote it by $X(s, t, x)$ and we

have $X \in C^1([0, T]_s \times [0, T]_t \times \mathbb{R}_x^N)$ and

$\partial_s D_x X$ and $D_x \partial_s X$ exist and are equal in

$C([0, T]_s \times [0, T]_t \times \mathbb{R}_x^N)$. If moreover

Theorem 3 (Thm. 4.10 in last weeks talk)

Let $V \in C^1([0, T] \times \mathbb{R}^n)$ be a vector field that satisfies the conditions of theorem 2. and let X be its characteristic flow. Further let $\mu_0 \in \mathcal{M}^+(\mathbb{R}^n)$. Then the Cauchy problem

$$\begin{cases} \partial_t \mu + \operatorname{div}_z (\mu V) = 0 \\ \mu|_{t=0} = \mu_0 \end{cases}$$

has a unique weak solution

$$\mu(t) = X(t, 0, \cdot) \# \mu_0$$

Proof of Thm 1:

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Proof of Theorem 1:

(i) $Z = \begin{pmatrix} z_1 \\ \vdots \\ z_N \end{pmatrix}$, then

$$\dot{Z} = \frac{1}{N} \begin{pmatrix} \sum_{j=1}^N K(z_1, z_j) \\ \vdots \\ \sum_{j=1}^N K(z_N, z_j) \end{pmatrix} = \frac{1}{N} \sum_{j=1}^N \begin{pmatrix} K(z_1, z_j) \\ \vdots \\ K(z_N, z_j) \end{pmatrix}$$

$$=: a(t, Z)$$

where $\|a(t, Z)\|_1 \leq \frac{1}{N} \sum_{j=1}^N \left\| \begin{pmatrix} K(z_1, z_j) \\ \vdots \\ K(z_N, z_j) \end{pmatrix} \right\|_1$

$$= \frac{1}{N} \sum_{i,j=1}^N \|K(z_i, z_j)\|$$

$$\leq \|z_i - z_j\| L (\|z_i\|_1 + \|z_j\|_1) \quad (\text{Lemma 1.1.1})$$

$$\leq 2L \|z\| \leq 2L(1 + \|z\|)$$

\Rightarrow
Theorem 2

There exists a unique solution of class C^2 as required.

(ii)

Given the solution $z_N(t) = (z_1(t), \dots, z_N(t))$ to (3) defined

$$V(t, z) := \int_{\mathbb{R}^d} U(z, z') d\mu_{z_N(t)} = \frac{1}{N} \sum_{j=1}^N U(z, z_j)$$

Thus $V \in C([0, T] \times \mathbb{R}^N, \mathbb{R}^N)$ and $D_x V \in C([0, T] \times \mathbb{R}^N, \mathbb{R}^{N \times N})$

and finally $\|V(t, x)\| \leq \int_{\mathbb{R}^d} \|U(z, z')\| d\mu_{z_N(t)}$

$$\leq L \int_{\mathbb{R}^d} (\|z\| + \|z'\|) d\mu_{z_N(t)} = L\|z\| + L \cdot 2$$

$$\leq \max\{L_1, L_2\} (1 + \|z\|).$$

Thus by Thm 3 there exists a unique solution of

$$\begin{cases} \partial_t \rho + \operatorname{div}_z(\rho V) = 0 \\ \rho|_{t=0} = \rho|_{z_N^{\text{in}}} \end{cases}$$

which can be given by

$$\rho(t) = X(t, 0, \cdot) \# \rho_{z_N^{\text{in}}}$$

$$\rho(t)(\{z\}) \rho(\{z\}) = \rho|_{z_N^{\text{in}}} (X(t, 0, \cdot)^{-1}(\{z\})) = 1$$

if and only if $z \in \mathbb{R}^d$ is a component
of $z_N^{\text{in}} \in (\mathbb{R}^d)^N$

$$\text{Thus } \rho(t) = \frac{1}{N} \sum_{j=1}^N \delta_{z_j(t)} = \rho|_{z_N(t)}$$

$$\text{and so } \partial_t \rho_{k_N} + \text{div}(\rho_{k_N} V) = 0$$

$$\Rightarrow \partial_t \rho_{k_N} + \text{div}_z(\rho_{k_N} V|_{\rho_{k_N}}) = 0. \quad \square$$

We only used the existence part and the concrete formula from Theorem 3.