

Last time

6.10.22

Linear Diff. Eqns with constant coefficients

Ⓘ Homogeneous eqn

$$y^{(k)} + a_{k-1} y^{(k-1)} + \dots + a_0 y = 0 \quad (*)$$

Thm. Let $P(\lambda) = \lambda^k + a_{k-1} \lambda^{k-1} + \dots + a_0$ be the characteristic equation of $(*)$. Let $\alpha_1, \dots, \alpha_r$ be pairwise distinct eigenvalues of $(*)$ with corresponding multiplicities m_1, \dots, m_r . Then the functions $f_{k,l} : \mathbb{R} \rightarrow \mathbb{C}$
 $x \mapsto x^l e^{\alpha_j x}$
for $1 \leq j \leq r$, $0 \leq l < m_j$ form a
lin. independent system of solutions of $(*)$

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Linear ODE with constant coefficients

$$y^{(k)} + a_{k-1}y^{(k-1)} + \dots + a_0y = b(x) \quad (*)$$

a_0, \dots, a_{k-1} are constants
 $b(x)$ is a continuous function.

To find a particular solution f_p we use "Method of undetermined coefficients".

- ① Choose an "Ansatz" which is similar to $b(x)$
- ② Put it into $(*)$, compare the coefficients of RHS and LHS to determine the constants in the Ansatz.

$b(x)$	Ansatz for f_p
$a e^{\alpha x}$	$c e^{\alpha x}$
$a \sin \beta x$ $a \cos \beta x$	$D \sin \beta x + \bar{E} \cos \beta x$
$a e^{\alpha x} \sin \beta x$ $b e^{\alpha x} \cos \beta x$	$e^{\alpha x} [D \sin \beta x + \bar{E} \cos \beta x]$
$P_n(x)$	$R_n(x)$
$P_n(x) e^{\alpha x}$	$R_n(x) e^{\alpha x}$
$P_n(x) e^{\alpha x} \sin \beta x$ $Q_n(x) e^{\alpha x} \cos \beta x$	$e^{\alpha x} [R_n(x) \cos \beta x + S_n(x) \sin \beta x]$

P_n, R_n, S_n polynomials of degree n .

Rk If $b(x)$ is a linear combination of these functions, use corresponding lin. comb. of Ansatz functions

Ex (1) $y'' + y' - 6y = 3e^{-4x}$

(H) $y'' + y' - 6y = 0$

\downarrow
 $\lambda^2 + \lambda - 6 = 0$

char. poly.

$(\lambda - 2)(\lambda + 3)$

$\lambda = 2, -3$

$y_H = c_1 e^{2x} + c_2 e^{-3x}$

For y_p particular solution

we try Ansatz $y_p = Ke^{-4x}$

$(Ke^{-4x})'' + (Ke^{-4x})' - 6Ke^{-4x} = 3e^{-4x}$

$16Ke^{-4x} - 4Ke^{-4x} - 6Ke^{-4x} = 3e^{-4x}$

$6Ke^{-4x} = 3e^{-4x}$

$\Rightarrow K = \frac{1}{2}$

$y_p = \frac{1}{2} e^{-4x}$

General soln $y_H + y_p$
 $c_1 e^{2x} + c_2 e^{-3x} + \frac{1}{2} e^{-4x}$

$$\textcircled{2} \quad y'' + y' - 6y = 50 \sin x$$

$$y_H = c_1 e^{2x} + c_2 e^{-3x}$$

Ansatz:

$$y_p = K_1 \sin x + K_2 \cos x$$

$$y_p' = K_1 \cos x - K_2 \sin x$$

$$y_p'' = -K_1 \sin x - K_2 \cos x$$

$$-6y_p = -6K_1 \sin x - 6K_2 \cos x$$

$$50 \sin x = (-7K_1 - K_2) \sin x + (K_1 - 7K_2) \cos x$$

$$\left. \begin{array}{l} -7K_1 - K_2 = 50 \\ K_1 - 7K_2 = 0 \end{array} \right\} \Rightarrow \begin{array}{l} K_1 = -7 \\ K_2 = -1 \end{array}$$

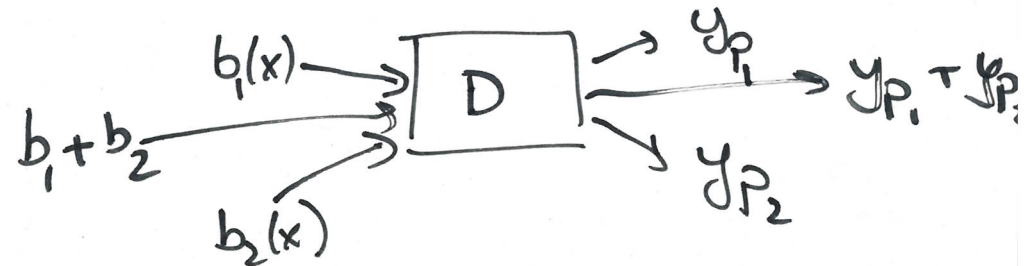
$$y_p = -7 \sin x - \cos x$$

Rmk. If we had

$$y'' + y' - 6y = 50 \sin x + 3e^{-4x}$$

$$y_p = \frac{1}{2} e^{-4x} + (-7 \sin x - \cos x)$$

"Superposition principle".



Exercise Try $y_p = K \sin x$

$$3) y'' + y' - 6y = 10e^{2x}$$

Recall $y_H = c_1 e^{2x} + c_2 e^{-3x}$.

Try $y_P = Ke^{2x}$

$$y_P'' + y_P' - 6y_P = 4Ke^{2x} + 2Ke^{2x} - 6Ke^{2x} = 0!$$

Try instead

$$y_P = Kxe^{2x}$$

$$y_P' = Ke^{2x} + 2Kxe^{2x}$$

$$y_P'' = 2Ke^{2x} + 2K[e^{2x} + 2xe^{2x}]$$

$$-6y_P = -6Kxe^{2x}$$

$$5Ke^{2x} + [2K + 4K - 6K]xe^{2x} = 10e^{2x}$$

$$\Rightarrow K = 2$$

$$y_P = 2xe^{2x}$$

general soln

$$y = y_H + y_P$$

$$c_1 e^{2x} + c_2 e^{-3x} + 2xe^{2x}$$

In general if $b(x)$ is a solution of homog. equation. Try $x b(x)$, $x^2 b(x)$, ... etc, depending on the multiplicity of the eigenvalue.

Rule In the "Ansatz"

method of the
disturbance function

is of the form

$$e^{\alpha x} \quad \alpha \in \mathbb{C}$$

for which α is

also a zero of

the charac. polynomial

ie $e^{\alpha x}$ is a solution

of the homog. equation

then if α is a
root of multiplicity

one then as

"Ansatz" we try

$$x e^{\alpha x}$$

if α is a root of

multiplicity 2, then

$$e^{\alpha x}, x e^{\alpha x} \text{ are}$$

both solns of homog

eqn, so try the

$$\text{next one } K x^2 e^{\alpha x}$$

Clicker

$$y'' - 4y = 4e^{2x}$$

$$X^2 - 4 = 0$$

$$(\lambda - 2)(\lambda + 2)$$

$$y_H = c_1 e^{2x} + c_2 e^{-2x}$$

$$y_p = K x e^{2x}$$

$$y_p' = K e^{2x} + 2K x e^{2x}$$

$$y_p'' = 2K e^{2x} + 2K [e^{2x} + 2x e^{2x}]$$

$$-4y_p = -4K x e^{2x}$$

$$4e^{2x} = 4K e^{2x}$$

$$K = 1$$

$$y_p = x e^{2x}$$

$$y_{\text{general}} = c_1 e^{2x} + c_2 e^{-2x} + x e^{2x}$$

$$\underline{x e^{2x} + e^{2x}}$$

$$\underline{x e^{2x} + e^{-2x}}$$

$$\underline{x e^{2x} + 2e^{2x}}$$

$$+ \pi e^{-2x}$$

are all solutions

Separation of Variables.

A diff. eqn of first order is called separable

if it is of the form

$$y' = b(x)g(y)$$

We can "separate" the variables

to write

$$\frac{dy}{dx} = b(x)g(y)$$

$$\frac{dy}{g(y)} = b(x)dx$$

As long as $g(y) \neq 0$.

If $g(y_0) = 0$ then $y = y_0$ is a soln.

Ex: $e^{2y} y' = x$

with $x > 0$.

$$\frac{dy}{e^{-2y}} = x dx$$

Integrate both sides

$$\int \frac{dy}{e^{-2y}} = \int x dx$$

$$\frac{e^{2y}}{2} = \frac{x^2}{2} + C$$

$$e^{2y} = x^2 + \tilde{C}$$

$$2y = \log(x^2 + C)$$

$$y = \frac{1}{2} \log(x^2 + C)$$

⑤ $y' = 1 + y^2$ $(1+y^2)$ is never zero.

$$\frac{dy}{dx} = 1 + y^2$$

$$\int \frac{dy}{1+y^2} = \int dx \Rightarrow \arctan y = x + C$$
$$y = \tan(x + C)$$

Differential calculus in \mathbb{R}^n .

In Analysis I we've seen
functions of 1 variable

$$f: \mathbb{R} \rightarrow \mathbb{R}$$
$$x \mapsto f(x)$$

$$f: \mathbb{R} \rightarrow \mathbb{R}^n$$
$$x \mapsto f(x) = (f_1(x), f_2(x), \dots, f_n(x))$$

$$f_i: \mathbb{R} \rightarrow \mathbb{R}.$$

f is continuous $\Leftrightarrow f_i$ is continuous $\forall i$

f is diff $\Leftrightarrow f_i$ is diff $\forall i$

We want to study
of functions

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m.$$

when $n > 1$

if $m > 1$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$
$$x \mapsto (f_1(x), f_2(x), \dots, f_m(x))$$

with $f_i(x): \mathbb{R}^n \rightarrow \mathbb{R}.$

For $n > 1$ a function

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m \text{ is}$$

also called a vector field.

$$f: \mathbb{R}^n \rightarrow \mathbb{R} \text{ is}$$

sometimes called a scalar field.

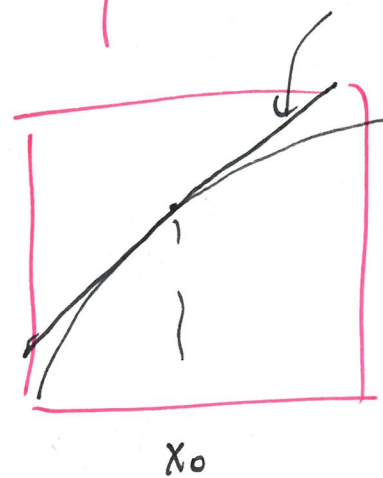
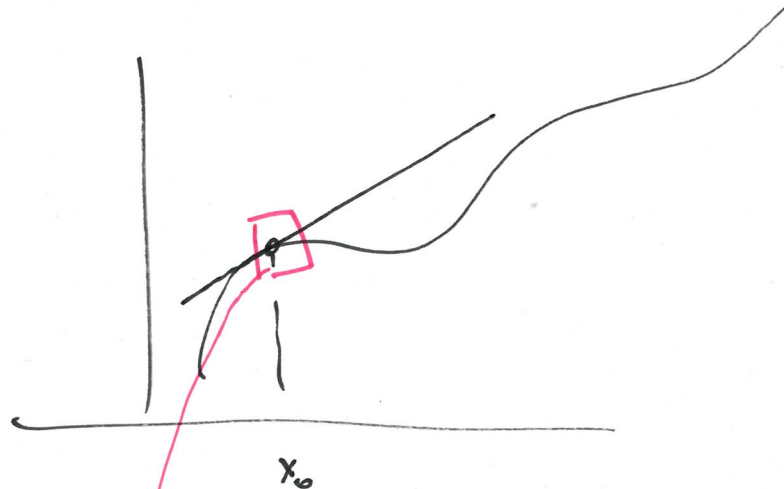
Examples (1) Linear maps.

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$x \mapsto Ax$$

for a $m \times n$ matrix A .

Recall



we can use
the tangent
line
as an
approx.
to the function
near x_0 .

A bit more generally

Affine maps

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$x \mapsto Ax + y_0$$

where $y_0 \in \mathbb{R}^m$ is
a fixed vector in \mathbb{R}^m .

② Quadratic forms

$$Q: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$Q(x_1, x_2, \dots, x_n) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j$$

$$n=2$$
$$Q(x, y) = ax^2 + bxy + cy^2$$

diagonal quadratic form

$$Q(x_1, x_2, \dots, x_n)$$

$$= x_1^2 + x_2^2 + \dots + x_n^2$$

Polynomial in n variables

Given $d \geq 0$ a polynomial
in n variables of degree
 $\leq d$ is a finite
sum of monomials
of degree $\leq d$.

A monomial is a function of the form

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$(x_1, x_2, \dots, x_n) \mapsto \alpha x_1^{d_1} x_2^{d_2} \dots x_n^{d_n}$$

degree of $(x_1^{d_1} \dots x_n^{d_n}) = d_1 + d_2 + \dots + d_n$

$$P(x, y, z) = x^3 + 2x^2y + xy^2 + 5z^4$$

degree of $P = 4$

In general degree of a Poly. of several variables

is the degree of its highest degree monomial

We can define new functions from old ones in various ways

① Cartesian Product of 2 functions

$$f_1: \mathbb{R}^n \rightarrow \mathbb{R}^s$$

$$f_2: \mathbb{R}^n \rightarrow \mathbb{R}^t$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^{s+t}$$
$$x \mapsto (f_1(x), f_2(x))$$

Any function $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $x \rightarrow (f_1(x), \dots, f_m(x))$

is in fact a

Cartesian product

of functions f_1, \dots, f_m

$$f_i: \mathbb{R}^n \rightarrow \mathbb{R}.$$

② Composition of functions.

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m \quad g: \mathbb{R}^m \rightarrow \mathbb{R}^t$$

$$g \circ f: \mathbb{R}^n \rightarrow \mathbb{R}^t$$

ex $g: \mathbb{R}^n \rightarrow \mathbb{R}$
 $(x_1, \dots, x_n) \mapsto x_1^2 + x_2^2 + \dots + x_n^2$

$f: \mathbb{R} \rightarrow \mathbb{R}$
 $x \mapsto e^x$

$(f \circ g)(x_1, \dots, x_n)$
 $= e^{x_1^2 + \dots + x_n^2}$