

24.11.22

Extrema of $f: X \rightarrow \mathbb{R}$

$X \subset \mathbb{R}^n$; differentiable.

Thm If $x_0 \in X$ is a local extrema of f then

$$\nabla f(x_0) = 0.$$

Thm If $f: X \rightarrow \mathbb{R}$ is differentiable in the interior of X , and if X is closed and bounded, then global extrema of f exists and it is either at a point x_0 with

$\nabla f(x_0) = 0$ or at a point on the boundary of X .

x_0 is a non-degenerate critical point of $f \in C^2(X: \mathbb{R})$ if $\det(\text{Hess}_f(x_0)) \neq 0$

Thm $f: X \rightarrow \mathbb{R}$, $f \in C^2$

$x_0 \in X$ a critical point of f

Then ① If $\text{Hess}_f(x_0) > 0$

then x_0 is a local minimum

② If $\text{Hess}_f(x_0) < 0$ then

x_0 is a local maximum

③ If $\text{Hess}_f(x_0)$ is indefinite

then x_0 is a saddle point.

Rk If $X \subset \mathbb{R}^2$ $f: X \rightarrow \mathbb{R}$

$$\text{Hess}_f(x_0) = \begin{pmatrix} a & b \\ b & c \end{pmatrix} \quad \text{then}$$

- 1) x_0 is a loc. min if $a > 0, ac - b^2 > 0$
- 2) x_0 is a loc. max if $a < 0, ac - b^2 > 0$
- 3) x_0 is a saddle pt if $ac - b^2 < 0$

Line Integrals

(Path Integrals)

Let γ be vector

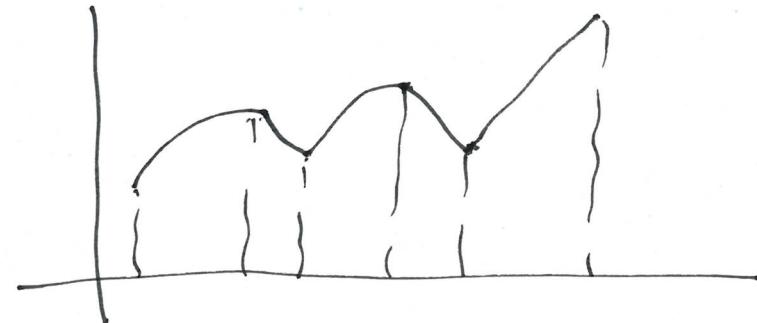
valued function on an
interval $[a, b]$

$$\gamma: [a, b] \rightarrow \mathbb{R}^n$$
$$t \mapsto (\gamma_1(t), \gamma_2(t) \dots \gamma_n(t))$$

which is continuous and

piecewise C^1 , ie $\exists t \geq 1$
and partition $a = t_0 < t_1 < \dots < t_k = b$

$$\gamma|_{[t_{k-1}, t_k]} \in C^1$$



We say γ is a parametrized curve, and $\gamma(t)$ is a parametrization of the curve

$$\text{Im } \gamma = \gamma([a, b])$$

Examples

1) $\gamma: [0,1] \rightarrow \mathbb{R}^3$
 $t \mapsto (1+t, 2t, 3-t)$

If $t \in \mathbb{R}$ then we get
the line

$$r(t) = \vec{a} + b\vec{t}$$

is the parametrization of

the segment in \mathbb{R}^3

which goes through the point $\vec{a} = (1, 2, 3)$

in the direction of

$$\vec{b} = (1, 1, -1)$$

at $t=1$ you are at

$$(2, 3, 2) = a + b = c$$

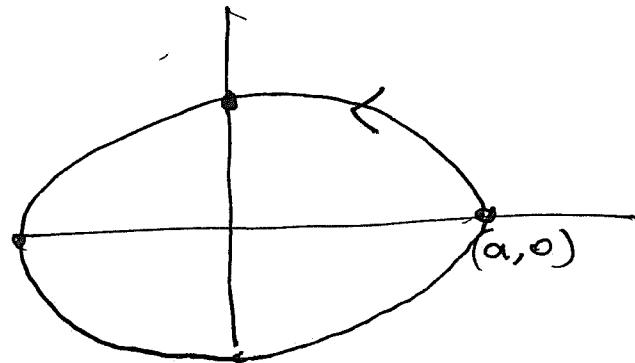
$$\gamma(t) = a(1-t) + ct$$

② In general if \vec{x}_0, \vec{x}_1 are 2 points in \mathbb{R}^n

Then $\gamma: [0,1] \rightarrow \mathbb{R}^n$
 $t \mapsto \vec{x}_0(1-t) + \vec{x}_1 t$

is the line segment which starts at \vec{x}_0 and ends at \vec{x}_1 .

$$\textcircled{3} \quad \gamma: [0, 2\pi] \rightarrow (a \cos t, b \sin t)$$



is a parametrization of
an Ellipse.

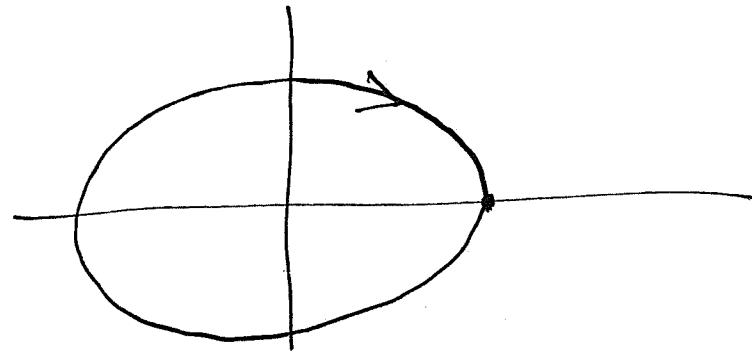
If $a=b$ then

$$\gamma: [0, 2\pi] \rightarrow (a \cos t, a \sin t)$$

is a parametrization of
the circle of radius a
traced in counterclockwise
direction.

$$\textcircled{4} \quad \alpha: [0, 2\pi] \rightarrow \mathbb{R}^2$$

$$t \rightarrow (a \cos(2\pi-t), b \sin(2\pi-t))$$



traces the ellipse in
the opposite direction



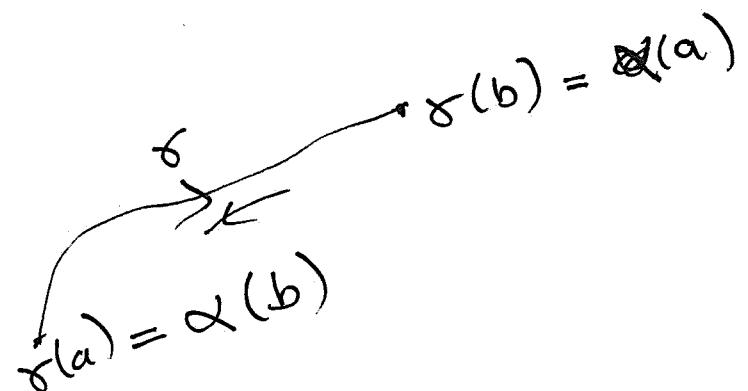
⑤. In general

if $\gamma: [a, b] \rightarrow \mathbb{R}^n$
 $t \rightarrow \gamma(t)$
is a curve

then $\alpha: [a, b] \rightarrow \mathbb{R}^n$

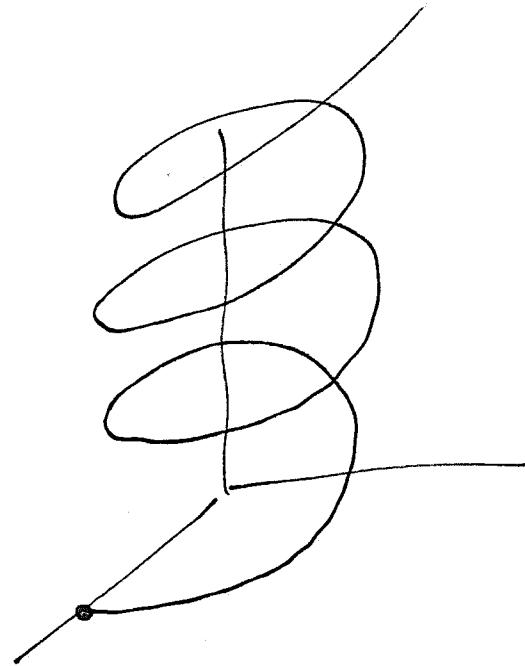
$$\alpha(t) := \gamma(b+a-t)$$

traces the same
curve in the
opposite direction

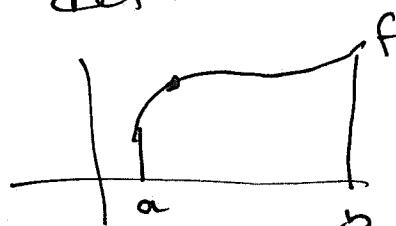


⑥ $\gamma: \mathbb{R} \rightarrow \mathbb{R}^3$

$$t \rightarrow (a \cos t, a \sin t, t)$$



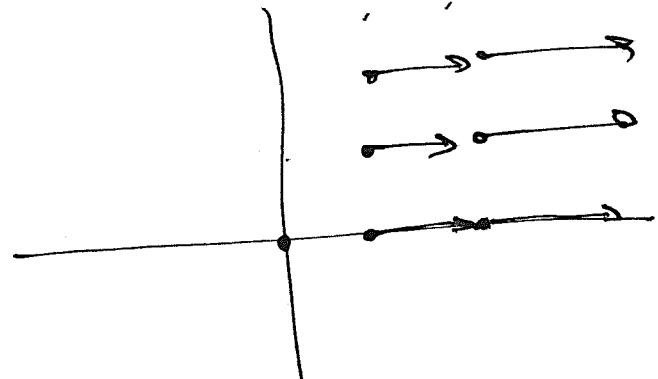
⑦ If $f: \mathbb{R} \rightarrow \mathbb{R}$
a function - Then its graph
determines a curve in \mathbb{R}^2



$$\gamma: [a, b] \rightarrow \mathbb{R}^2$$
$$t \rightarrow (t, f(t))$$

let $v: \mathbb{R}^n \rightarrow \mathbb{R}^n$
be a vector field.

e.g. $v: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $(x, y) \rightarrow (x, 0)$



Defn. Let $\gamma: [a, b] \rightarrow \mathbb{R}^n$
a curve in \mathbb{R}^n . $X \subset \mathbb{R}^n$
a subset of \mathbb{R}^n which
contains the image of γ .

$v: X \rightarrow \mathbb{R}^n$ a
continuous function

The Integral

$$\int_a^b (v(\gamma(t)) \cdot \gamma'(t)) dt$$

↓
scalar product
 $\in \mathbb{R}$.

is called the
line or the path
integral of v along
 γ .

Other Notations

$$\int_{\gamma} v \cdot ds$$

If $v = (v_1(x), v_2(x), \dots, v_n(x))$

$$\gamma(t) = (\gamma_1(t), \gamma_2(t), \dots, \gamma_n(t))$$

ds represents $\gamma'(t) dt$

If $n=2$ $\gamma = \frac{I}{t} \rightarrow \gamma(t) = (\gamma_1(t), \gamma_2(t))$

$$\int_{\gamma} v \cdot ds = \int_a^b \left(v_1(\gamma(t)) \begin{pmatrix} \gamma_1'(t) \\ \gamma_2'(t) \end{pmatrix} \right) \cdot \begin{pmatrix} \gamma_1'(t) \\ \gamma_2'(t) \end{pmatrix} dt$$

$$\int_a^b \left[v_1(\gamma(t)) \cdot \gamma_1'(t) + v_2(\gamma(t)) \gamma_2'(t) \right] dt$$

$$\int_a^b f_1(x, y) dx + f_2(x, y) dy$$

$$x = \gamma_1(t) \quad y = \gamma_2(t)$$

$$dx = \gamma_1'(t) dt \quad dy = \gamma_2'(t) dt$$

Ex ① $v(x, y) = (-y, x)$

$$\gamma(t) = (\cos t, \sin t)$$

$$0 \leq t \leq 2\pi$$

$$\int_0^{2\pi} \langle v(\gamma(t)), \gamma'(t) \rangle dt$$

$$\begin{aligned} v(r(t)) &= v(\cos t, \sin t) \\ &= (-\sin t, \cos t) \end{aligned}$$

$$v'(t) = (-\sin t, \cos t)$$

$$\langle v(r(t)), v'(t) \rangle$$

$$\sin^2 t + \cos^2 t = 1$$

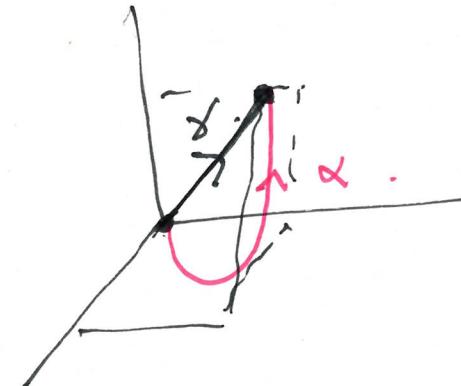
$$\int v \, ds = \int_0^{2\pi} 1 \, dt = 2\pi$$

②. $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$
 $(x, y, z) \rightarrow (y^2, xz, 1)$

$$\gamma: [0, 1] \rightarrow \mathbb{R}^3$$

$$t \rightarrow (t, t, t)$$

$$v'(t) = (1, 1, 1)$$



$$\begin{aligned} \alpha: [0, 1] &\rightarrow \mathbb{R}^3 \\ t &\rightarrow (t, t^2, t^3) \\ \alpha'(t) &= (1, 2t, 3t^2) \end{aligned}$$

$$\begin{aligned} \int f \, ds &= \int_0^1 \langle f(\gamma(t)), \gamma'(t) \rangle \, dt \\ &= \int_0^1 \langle (t^2, t^3, 1), (1, 1, 1) \rangle \, dt \\ &= \int_0^1 2t^2 + 1 \, dt = \left. \frac{2t^3}{3} + t \right|_0^1 = 5/3 \end{aligned}$$

$$\int_{\alpha} f ds = \int_0^1 \langle f(\alpha(t)), \alpha'(t) \rangle dt$$

$$\int_0^1 \langle f(t, t^2, t^3), (1, 2t, 3t^2) \rangle dt$$

$$\int_0^1 (t^4, t^4, 1) \cdot (1, 2t, 3t^2) dt$$

$$= \int_0^1 t^4 + 2t^5 + 3t^2 dt$$

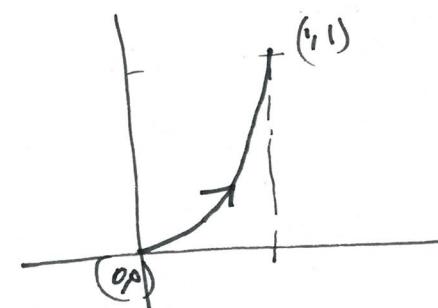
$$= - \dots$$

$$= 23/15.$$

Clicker

$$v: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(x, y) \mapsto (x^2 - 2y, 2x + y)$$



$$\gamma: [0, 1] \rightarrow \mathbb{R}^2$$

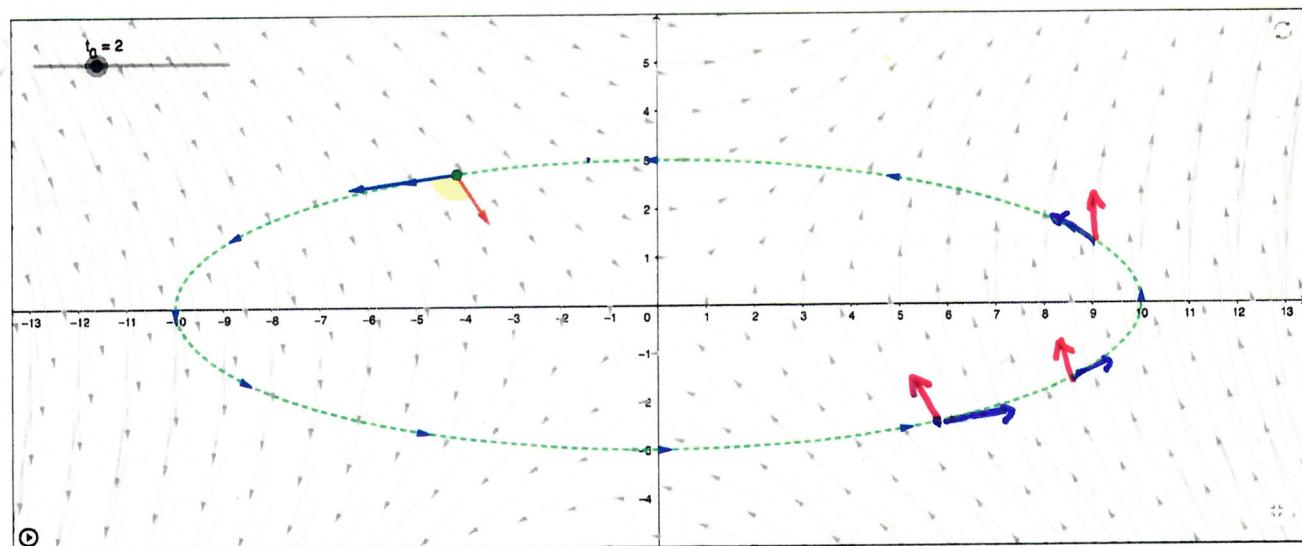
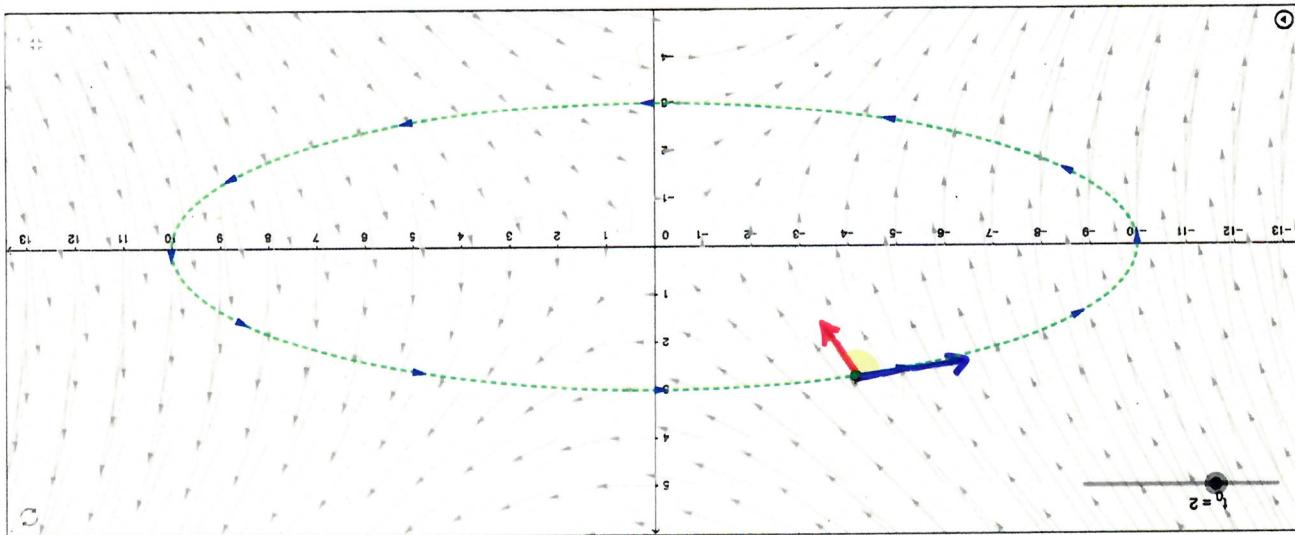
$$t \mapsto (t, t^3)$$

$$v(\gamma(t)) = v(t, t^3) = (t^2 - 2t^3, 2t + t^3)$$

$$\gamma'(t) = (1, 3t^2) dt$$

$$\int_0^1 \langle v(\gamma(t)), \gamma'(t) \rangle dt = \int_0^1 t^2 - 2t^3 + 6t^3 + 3t^5 - t^2 + 4t^3 + 3t^5 dt$$

$$= -11/6$$



$$\int_a^b f(s) ds := \int_a^b \underbrace{f(\gamma(t))}_{\text{red vector}} \cdot \underbrace{\gamma'(t)}_{\text{blue vector}} dt$$

scalar product

Geogebra: Line Integral of a vector field in 2-space

Author: Kristen Beck

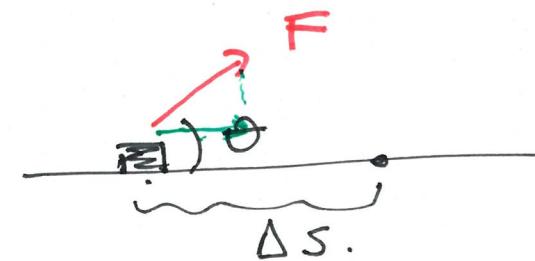
<https://www.geogebra.org/m/YzWyyM47>

Why do we define such an integral?

Assume you have a point mass that moves under influence of a constant vector field. $\vec{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

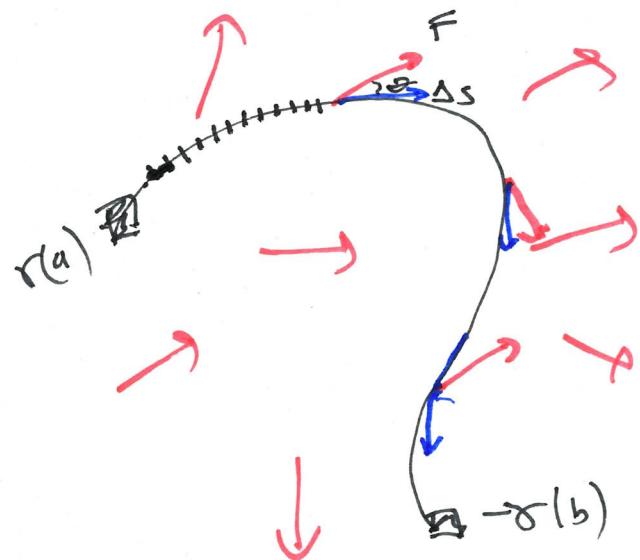
if it is moved by a distance Δs , then the work done is given by

$$w = \vec{F} \cdot \vec{\Delta s} = |\vec{F}| |\vec{\Delta s}| \cos \theta$$



$$|\vec{F}| \cos \theta$$

Now suppose it is moved along a curve under the influence of a force field that changes at every pt.



$$\Delta w = \vec{F} \cdot \Delta s$$

Divide the curve into small pieces $\Delta \gamma_i = \gamma_i(t_{i+1}) - \gamma_i(t_i)$

$$w = \sum \Delta w_i = \sum \vec{F}(\gamma(t_i)) \cdot \Delta \gamma_i$$

$$\sum \vec{F}(x(t_i), y(t_i)) \cdot \frac{\Delta \gamma_i}{\Delta t} \cdot \Delta t$$

let $\Delta t \rightarrow 0$.

$$\int_a^b \vec{F}(\gamma(t)) \cdot \gamma'(t) dt$$

Properties of the path integrals

- ① It is independent of orientation preserving reparametrization of the curve.

reparametrization : if $\gamma: [a, b] \rightarrow \mathbb{R}^n$

$\sigma: [c, d] \rightarrow [a, b]$ which is C^1 s.t. $\sigma(c) = a, \sigma(d) = b$

and $\sigma'(t) > 0$ then

$$\tilde{\gamma} := \gamma \circ \sigma: [c, d] \rightarrow \mathbb{R}^n$$

is a reparametrization of γ .

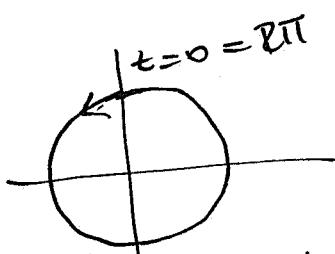
For the line integral:

$$\oint f = \mathbb{R}^n \rightarrow \mathbb{R}^n$$

a vector field

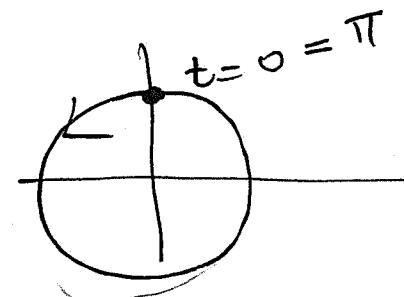
$$\boxed{\int_{\gamma} f \, ds = \int_{\tilde{\gamma}} f \, ds}$$

Ex: $\gamma: [0, 2\pi] \rightarrow \mathbb{R}^2$
 $t \rightarrow (\sin t, \cos t)$



$$\sigma: [0, \pi] \rightarrow [0, 2\pi]$$
$$t \rightarrow 2t$$

$$\tilde{\gamma} = \gamma \circ \sigma: [0, \pi] \rightarrow \mathbb{R}^2$$
$$t \rightarrow (\sin 2t, \cos 2t)$$



$$\int_c^d f((\gamma \circ \sigma)(t)) \cdot (\gamma \circ \sigma)'(t) dt$$
$$= \int_a^b f(\gamma(\sigma(t))) \cdot \gamma'(\sigma(t)) \cdot \sigma'(t) dt.$$
$$\int_c^d f(\gamma(\sigma(t))) \cdot \gamma'(\sigma(t)) \cdot \sigma'(t) dt -$$

(let $\sigma(t) = u$. $\sigma'(t) dt = du$.)

$$\int_a^b f(\gamma(u)) \gamma'(u) \cdot du$$

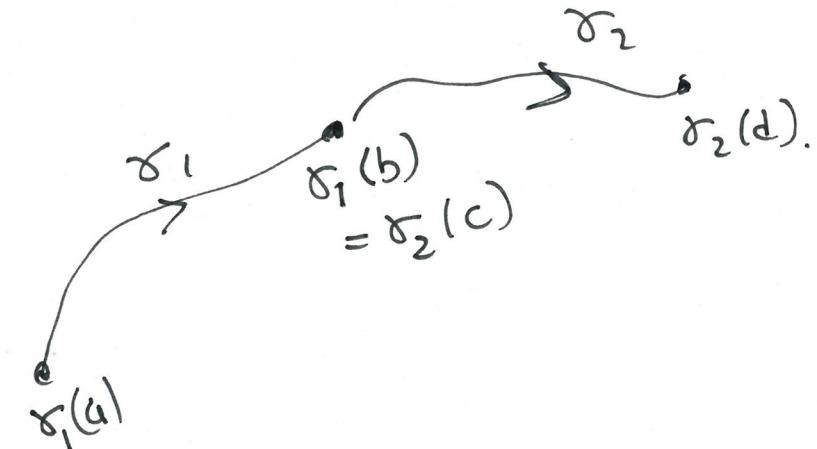
② Let $\gamma_1: [a, b] \rightarrow \overset{\text{scr}}{X} \subset \mathbb{R}^n$.

$\gamma_2: [c, d] \rightarrow X$

2 paths with $\gamma_1(b) = \gamma_2(c)$

Define $\gamma_1 + \gamma_2$ as the path formed by concatenation of these 2 curves.

$$(\gamma_1 + \gamma_2)(t) = \begin{cases} \gamma_1(t) & t \in [a, b] \\ \gamma_2(t - b + c) & t \in [b, d + b - c]. \end{cases}$$



Then $\int f ds = \int f ds$

$$\begin{aligned} & \gamma_1 + \gamma_2 & \gamma_1 \\ & + \int f ds. & \gamma_2 \end{aligned}$$

(3) If $\gamma: [a, b] \rightarrow \mathbb{R}^n$
 a path. let $-\gamma: [a, b] \rightarrow \mathbb{R}^n$
 some path traced in the
 opposite direction

$$(-\gamma)(t) = \gamma(a+b-t)$$

Then $\int_{-\gamma} f ds = - \int_{\gamma} f ds.$

Analog of $\int_a^b f dx = \int_b^a f dx$

$$= - \int_b^a f dx$$

Recall fund. thm.

$$\text{if } F' = f$$

$$\int_a^b f dx = \int_a^b F'(x) dx \\ = F(b) - F(a).$$

Is there an analog for
 the path integral?

Important example

Suppose $f: X \rightarrow \mathbb{R}^n$

$x \in \mathbb{R}^n$ a vector field

such that $\exists g: X \rightarrow \mathbb{R}$
 $g \in C^1$ so that $f = \nabla g$.

Suppose $\gamma: [a, b] \rightarrow X$

$$\int_{\gamma} f ds = \int_{\gamma} \nabla g ds$$

$$= \int_a^b \nabla g(\gamma(t)) \cdot \gamma'(t) dt$$

By chain rule

$$\frac{d}{dt}(g \circ \gamma) = \nabla g(\gamma(t)) \cdot \gamma'(t)$$

$$\begin{aligned} \int_{\gamma} f ds &= \int_{\gamma} \nabla g ds \\ &= \int_a^b \left(\frac{d}{dt}(g \circ \gamma) \right) dt \end{aligned}$$

$$= (g \circ \gamma)(b) - (g \circ \gamma)(a)$$

$$= g(\gamma(b)) - g(\gamma(a))$$

Rk Integral of f only depends
on the end points of γ
and of course on g .

Defn A differentiable function $g: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$ so that $\nabla g = f$ is called a potential for f

Rk ① $n=1$ a potential is simply a primitive.

② If $f: \mathbb{R} \rightarrow \mathbb{R}$ and

continuous, then

$$g(x) := \int_a^x f(t) dt$$

is a primitive of f

$$\text{i.e. } g'(*)=f(x).$$

So for $f: \mathbb{R} \rightarrow \mathbb{R}$ continuous, primitive always exists.

Question for $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$

Is there always a g such that $\nabla g = f$?

Answer : NO /

Ex. : $f(x,y) = (2xy^2, 2x)$

Suppose there is a g s.t $\nabla g = (2xy^2, 2x)$

$$\frac{\partial g}{\partial x} = 2xy^2$$

$$\frac{\partial g}{\partial y} = 2x$$

↓

$$g(x,y) = x^2y^2 + h(y)$$

$$\frac{\partial g}{\partial y} = 2x^2y + h'(y)$$

$$= 2x$$

Has no soln.

Hence no such g exists.

$$\text{Ex: } f(x,y) = (2xy^2, 2yx^2)$$

Is there a $g = 1/2 \rightarrow 1/2$
so that

$$\frac{\partial g}{\partial x} = 2xy^2$$

$$\frac{\partial g}{\partial y} = 2yx^2$$

↓

$$g(x,y) = x^2y^2 + h(y)$$

$$\frac{\partial g}{\partial y} = 2yx^2 + h'(y)$$

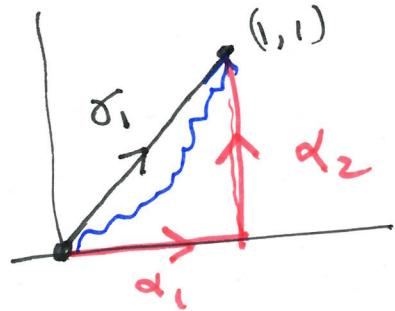
$$= 2yx^2$$

$$\Rightarrow h'(y) = 0 \Rightarrow h = \text{const.}$$

$$g(x,y) = x^2y^2 + C$$

$$\text{then } \nabla g = f$$

$$\underline{\text{Ex}}: f = (2xy^2, 2yx^2)$$



$$\alpha_1: [0,1] \rightarrow \mathbb{R}^2 \\ t \rightarrow (t,t)$$

$$\alpha_1: [0,1] \rightarrow \mathbb{R}^2 \\ t \rightarrow (t,0)$$

$$\alpha_2: [0,1] \rightarrow \mathbb{R}^2 \\ t \rightarrow (0,t)$$

$$\int_C f \cdot ds = 1 = \int_{\alpha_1 + \alpha_2} f \cdot ds = 1$$

The integral is indep.
of the path from $(0,0)$
to $(1,1)$

Defn Let $X \subset \mathbb{R}^n$ $f: X \rightarrow \mathbb{R}^n$

be a continuous vector
field. If for any $x_1, x_2 \in X$
the line integral

$\int_C f \cdot ds$ of a curve in X
from x_1 to x_2

is independent of the curve
then f is called conservative

How do we decide if
a vector field is
conservative?

Defn. let $X \subset \mathbb{R}^n$ open

X is path connected

If for every pair of points in

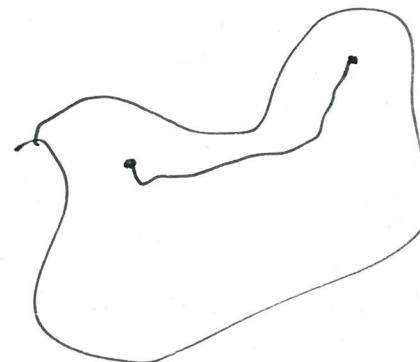
$x, y \in X$, \exists a path

$\gamma: [0, 1] \rightarrow X$ with

$$\gamma(0) = x$$

$$\gamma(1) = y$$

$$\gamma([0, 1]) \subset X$$



path
connected



not
path
connected.

Thm: f continuous

v. field on an open
path connected set $X \subset \mathbb{R}^n$.
Then FAE .

① f is the gradient
of a function $g: X \rightarrow \mathbb{R}$
 $f = \nabla g$

- 2) The line integral
of f is independent
of the path
between the 2 points
- 3) The line integral of
 f along closed paths
are zero.

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