Proposition

N is an equivalence relation on the set of all maps $X \rightarrow Y$. Proof • REFLEXIVE

> H(x,t) = f(x) $\forall x \in X,$ $t \in [0,1]$

H is a homotopy between $f & f = f \circ f$.

· SYMMETRIC

f vg $H: x x z \rightarrow Y \Rightarrow$ H(x, 0) = f(x) H(x, 1) = g(x)RANSITIVE

F~g&g~h.

 $F(x,t) = H^{-1}(x)$ is a homotopy from g to F so gru f

F*H is the homotopy => f~h from f to h. NOTATION

X, I spaces. Let
$$[X, Y] = \text{set of homotopy}$$

 $X \to Y$

For poirs we write [(x, A), (I, B)].

FUNDAMENTAL GROUP



we have that

$$\mathcal{T}_{\Lambda}(X, X) = \left[(S^{1}, x), (X, X_{o}) \right]$$

$$f_{base point}$$
or S¹

Review Exercise: Prove that T_n(x,xo) is a group. HIGHER HOMOTOPY GROUPS $\underset{(x',x')}{\coprod} = \left[(I_{u'}) \geq I_{u'} \right]$ Since $\mathbb{I}_{AT}^{n} \approx S^{n}$, $\mathbb{T}_{n}(x, x_{o}) = \left[\left(S^{n} + \right) (X, x_{o}) \right]$. OPERATION $f_{Q}: \mathbb{I}^{n} \rightarrow X$ $h \ge 2$ $f + g(t_{n}, .., t_{n}) = \begin{cases} f(t_{1}, .., t_{n-1}, 2t_{n}) & o \leq t_{n} \leq \frac{1}{2} \\ g(t_{1}, .., t_{n-1}, 2t_{n-1}) & d \leq t_{n} \leq \frac{1}{2} \\ g(t_{1}, .., t_{n-1}, 2t_{n-1}) & d \leq t_{n} \leq \frac{1}{2} \end{cases}$ Visually





of In with the region outside mapping to the basepoint, Once this is done, we slide them part each other (so they remain disjoint) and interchange their positions. To finish the homotopy, we enlarge them back to their original size. Further properties of t: • ASSOCIATIVE · IDENTITI ELEMENT $CONST: I^n \rightarrow \{x_o\}$ · INVERSE $-f(t_{1},..,t_{n})$ $=f(t_{1},..,1-t_{n})$ Equipped with this operation Tr(X,xo) is an abelian group.

Examples $(\mathcal{T}, \mathcal{T}_n(S^{\kappa}) = 0 \quad \forall n < \kappa$ $(3) \mathcal{T}_{3}(S^{2}) \cong \mathbb{Z}$ $(2) \prod_{n \in \mathbb{Z}} (S^{n}) \cong \mathbb{Z}$ T((st) for general h7k is unknown.

Brawback; homotopy groups are very hard to compute in general. Alternative. HOMOLOGY GROUPS the most important homology theory in algebraic topology and the one we will be studying almost exclusively, is Called SINGULAR HOMOLOGY. But since the technical apparatus of singular homology is somewhat complicated, we will start with simplicial homology. We will define it for A-complexes (Hatcher), which are a slight generalitation of simplicial complexes. DELTA COMPLEXES Definition the STANDARD n-dimensional SIMPLEY (or n-simplex) is the topological space $\Delta^n = \mathcal{E}(t_0, t_1, t_n) \in \mathbb{R}^{n+1} \geq t_1 = 1, t_2 \geq 0 \neq \mathcal{E}_1$ Example. Δ^n is a point V_0



An n-simplex is the smallest convex set min Euclidean space RM containing nt1 points Vo, V1, ..., Vn that do not lie mi a hyperplane of dimension les than m(or equivalently, such points that the difference vectors Y-Vo,..., Vn-Vo are linearly independent). the points Vi are called VERTICES of the simplex and the simplex

itself is denoted by [Vo,..., Vh]. Example The vertices of the standard n-simplex are the unit vectors along the coordinate axes.

ORDERING OF THE VERTICES IS IMPORTANT as it determines the

Orientation of the Simplex.

 $[V^{\circ}, V]$



 $\left[V_{0}, V_{1}, V_{2}\right]$

 $\left[V_{0},V_{1},V_{2},V_{3}\right]$

the ordering also determines a canonical linear homomorphism from the standard m-simplex & onto any other simplex IVo, ..., Vh]; preserving the order of

Ventices, hamely;

$$(t_{0}, ..., t_{n}) \mapsto \sum_{i=0}^{n} t_{i} V_{i}$$

 $t_{i} \text{ ore called barycentric coordinates}}$
of $Z t_{i}V_{i} m$
 $[V_{0}, ..., V_{n}]$

Definition
If we delete one of the Mrs vertices
of an m-simplex
$$[V_{0},...,V_{h}]$$
, then
the remaining in vertices span an
 $(n-1)$ simplex, called a FACE of
 $[V_{0},...,V_{n}]$. It is ordered according to
the order in $[V_{0},...,V_{n}]$.