

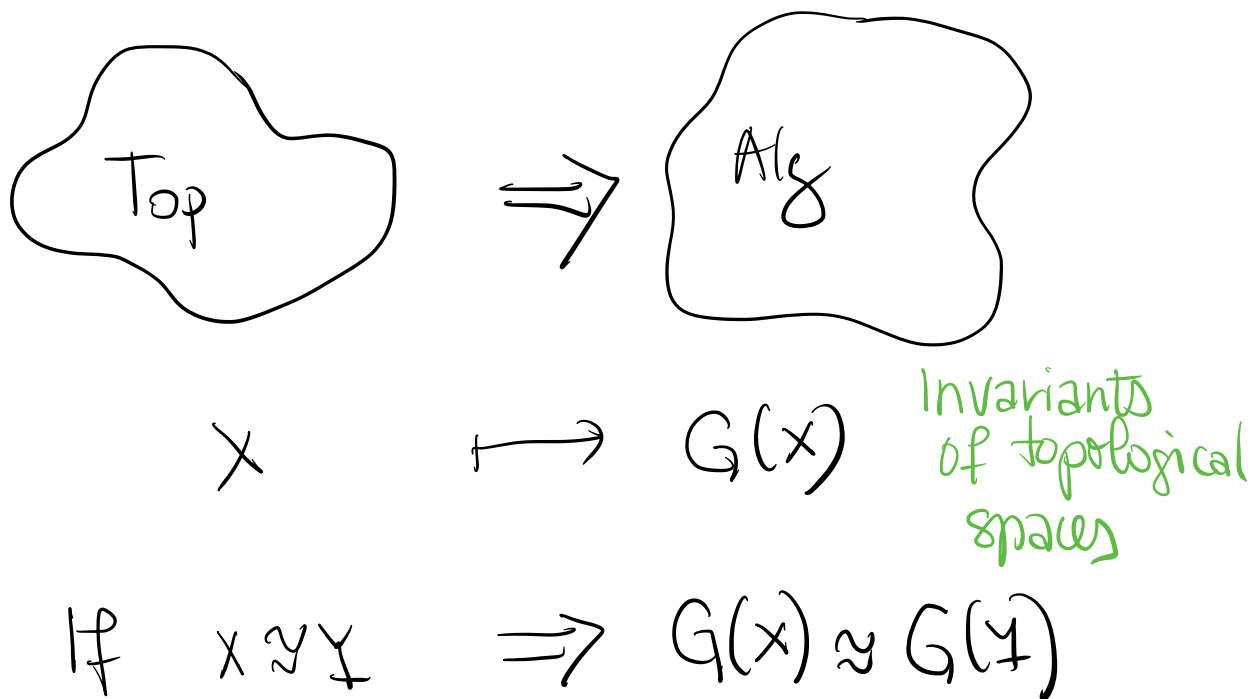
INTRODUCTION

What is topology?

It is a study of topological spaces
up to a homeomorphism (or some
other equivalence)

One way to study topological spaces is
by using ALGEBRA, \rightsquigarrow ALGEBRAIC
TOPOLOGY

How: by assigning algebraic objects to
topological spaces



Examples:

- FUNDAMENTAL GROUP $\pi_1(x, x_0)$
(point-set topology class
at ETH)
- HIGHER HOMOTOPY GROUPS

CONVENTIONS:

- 'space' = 'topological space'
- X topological space, $A \subset X$ with the induced topology (from X) is called a subspace.
- $f: X \rightarrow Y$ 'map' = 'continuous map'
- $A \subset X, B \subset Y, f(x, A) \rightarrow (Y, B)$
means such a map $f: X \rightarrow Y$ s.t.
 $f(A) \subset B$.

QUOTIENT TOPOLOGY

Let X be a topological space,

Y a set, $g: X \rightarrow Y$ surjective (onto).

Define a topology on Y as follows:

$$V \subset Y \text{ open} \iff g^{-1}(V) \subset X \text{ is open.}$$

This is the finest topology that makes g continuous. It is called the

QUOTIENT TOPOLOGY on Y .

Examples:

1) X topological space, \sim an equivalence relation on X . Let $Y = X / \sim$ (the set of all equivalence classes). Then

$g: X \rightarrow Y$ is surjective

$$g(x) = [x]$$

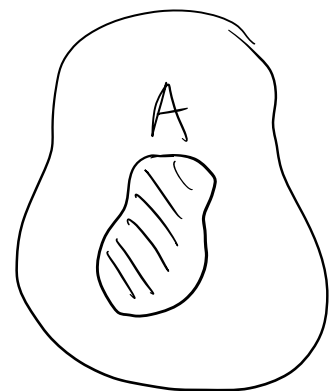
and we can equip Y with the quotient

topology.

2) X = topological space, $A \subset X$ subspace.

We can define an equivalence relation on X as follows:

$$x \sim y \quad \text{if either} \quad \begin{array}{l} x, y \in A \\ x = y \end{array}$$



The equivalence classes are:

$$\{ [x] \}_{x \in X \setminus A}, [A]$$

The quotient space X/A is equipped with the quotient topology.

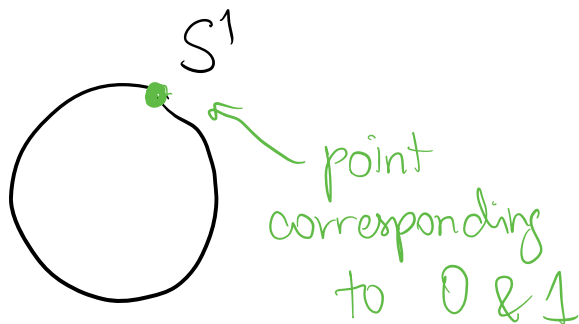
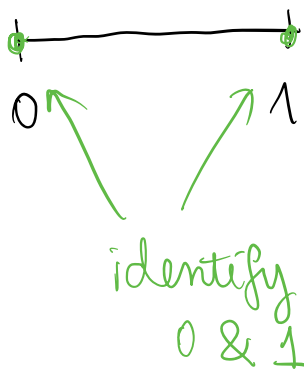
WARNING: This definition is not the same as the group theory definition of G/H , where G is a group & H is a subgroup.

Example: (1) $I = [0, 1]$, $A = \partial I = \{0, 1\}$

Then

$$\frac{I}{A} \approx S^1 \leftarrow \text{circle}$$

↑
homeo.



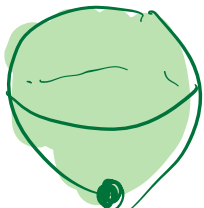
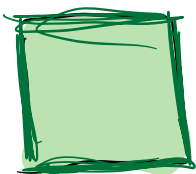
More generally, $\frac{I^n}{\partial I^n} \approx S^n$ \leftarrow n-dimensional sphere

Here $I^n = \underbrace{I \times I \times I \dots \times I}_{n \text{ times}} = \{(x_1, \dots, x_n) \mid x_i \in I\}$

$$\partial I^n = \left\{ (x_1, \dots, x_n) \in I^n \mid \exists j \text{ s.t. } x_j = 0 \text{ or } x_j = 1 \right\}$$

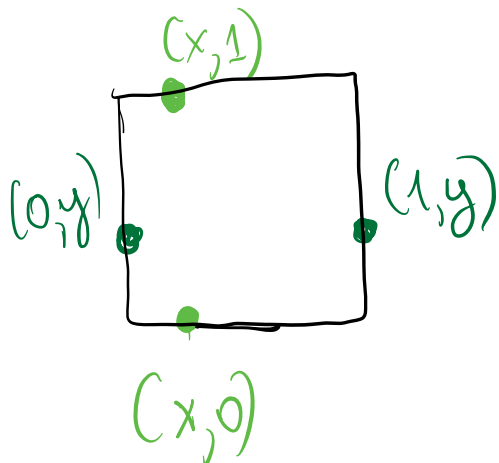
$$S^n = \left\{ (x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} \mid x_1^2 + \dots + x_{n+1}^2 = 1 \right\}$$

n=2



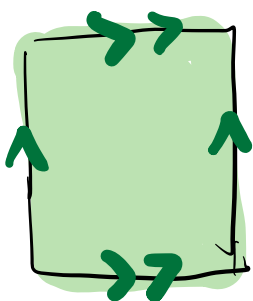
Exercise.

$$(2) \quad X = I \times I$$



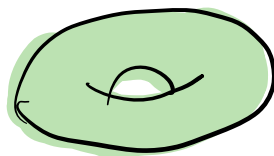
$$(x,0) \sim (x,1) \quad \forall x \in I$$

$$(0,y) \sim (1,y) \quad \forall y \in I$$



$$\frac{I^2}{\sim}$$

2-dimensional
torus (or donut)



HOMOTOPY

Definition

Let X, Y be topological spaces. A **HOMOTOPY** of maps from X to Y is a map

$$F: X \times I \rightarrow Y.$$

Equivalently, F is a continuous 1-parameter

family of maps $f_t: X \rightarrow Y$, where $f_t(x) = F(x, t)$,
 $t \in I$.

Definition

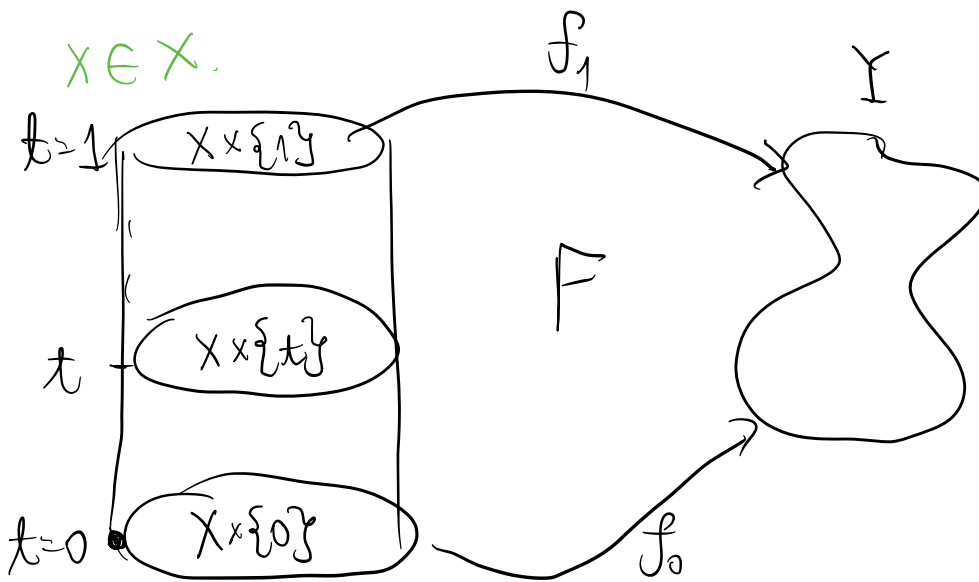
Two maps f_0 and $f_1: X \rightarrow Y$ are

said to be **HOMOTOPIC** if there exists

a homotopy $F: X \times I \rightarrow Y$ such that

$F(x, 0) = f_0(x)$ and $F(x, 1) = f_1(x)$ for

all $x \in X$.



Notation

We write $f_0 \approx f_1$ if f_0 is homotopic
to f_1 .

Example Any two maps $f, g: X \rightarrow \mathbb{R}^2$ are homotopic.

Homotopy (called LINEAR HOMOTOPY) is given by
 $x \mapsto (1-t)f(x) + tg(x)$, $x \in X, t \in I$.

Proposition

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ h \uparrow & & \downarrow k \\ X' & & Y' \end{array}$$

If $f \simeq g$, then
 $f \circ h \simeq g \circ h$ and
 $k \circ f \simeq k \circ g$.

Exercise.

Definition

A map $f: X \rightarrow Y$ is called a **HOMOTOPY EQUIVALENCE** if $g: Y \rightarrow X$ exists s.t.
 $g \circ f \simeq \text{id}_X$ and $f \circ g \simeq \text{id}_Y$.

When such f & g exist, the spaces X & Y are said to be **HOMOTOPY EQUIVALENT** or have the same **HOMOTOPY TYPE**.

Notation: $X \simeq Y$.

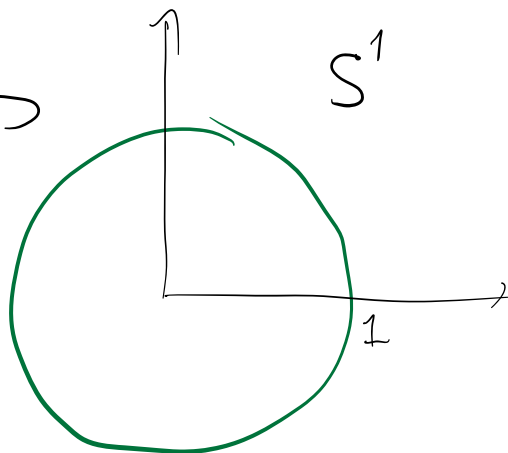
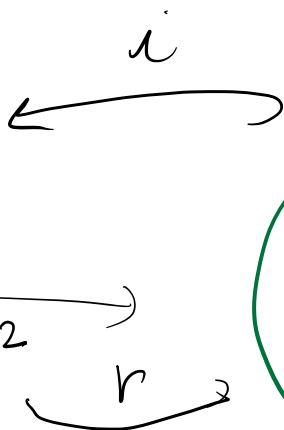
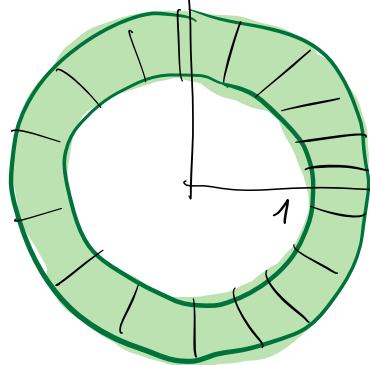
Proposition:

\simeq is an equivalence relation on topological spaces.

Exercise.

Example

A



$$\{(x, y) \mid 1 \leq x^2 + y^2 \leq 4\}$$

$$\{(x, y) \mid x^2 + y^2 = 1\}$$

$$i: S^1 \hookrightarrow A$$

$$(x, y) \mapsto (x, y)$$

$$r: A \rightarrow S^1$$

$$(x, y) \mapsto \frac{(x, y)}{\sqrt{x^2 + y^2}}$$

$r \circ i: S^1 \rightarrow S^1$ is the identity map.

$$i \circ r: A \rightarrow A$$

$$F: A \times I \rightarrow A$$

$$F((x, y), t) = t(x, y) + (1-t) \frac{(x, y)}{\sqrt{x^2 + y^2}}$$

$$F((x, y), 0) = \frac{(x, y)}{\sqrt{x^2 + y^2}} = r(x, y)$$

this map is continuous

$$F((x, y), 1) = (x, y) = \text{id}_A(x, y)$$

So $F: A \times I \rightarrow A$ is a homotopy between $i \circ r$ and id_A .

Therefore, annulus and circle
are homotopy equivalent.

They are not homeomorphic.
(thoughts on how to prove it?)

**THERE EXIST HOMOTOPY EQUIVALENT
SPACES THAT ARE NOT HOMEOMORPHIC.**

Definition

A space X is called **CONTRACTIBLE**

if X is homotopy equivalent to the one-point space.

Proposition

$$\begin{array}{ccc} X & \xrightarrow{c} & \{x_0\} \\ & \nwarrow i & \\ & & \end{array} \quad \begin{array}{l} c \circ i = \text{id} \\ i \circ c \simeq \text{id} \end{array}$$

Let X be a space, $x_0 \in X$. Let $c: X \rightarrow X$
be the constant map $c(x) = x_0 \quad \forall x \in X$.

X is contractible $\Leftrightarrow c \simeq \text{id}_X$.

Proof

(X is contractible $\Leftarrow c \simeq \text{id}_X$)

Let $c: X \rightarrow X$ be such that $c(x) = x_0$.

Let $i: \{x_0\} \rightarrow X$

$r: X \rightarrow \{x_0\}$

Then $r \circ i = \text{id}_{\{x_0\}}$ & $i \circ r \stackrel{\cong}{=} \text{id}_X$.

$\Rightarrow X$ is contractible. $\begin{matrix} \downarrow \\ C \end{matrix}$ $\begin{matrix} \uparrow \\ \text{by assumption} \end{matrix}$

(X is contractible $\Rightarrow C \cong \text{id}_X$)

$C(x) = x_0$ for $x \in X$.

Since X is contractible, there exist i & r

$$f : \{x_0\} \rightarrow X$$

$$f' : X \rightarrow \{x_0\}$$

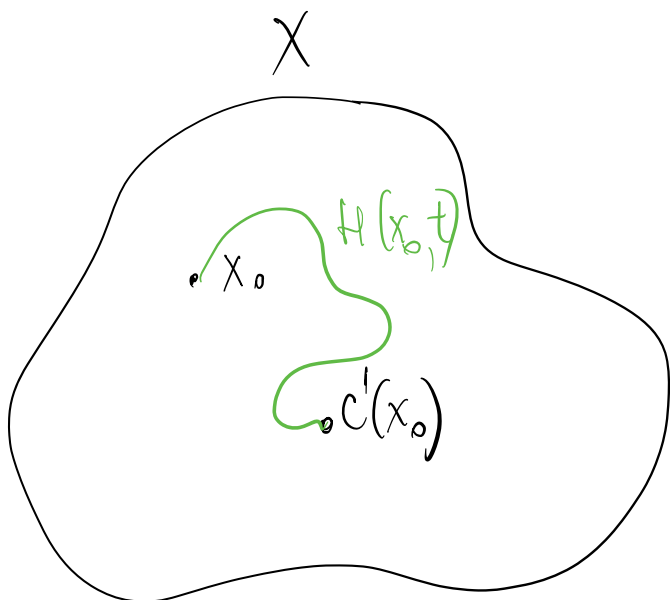
such that

$$f' \circ f = \text{id}_{\{x_0\}}$$

$$f \circ f' \stackrel{\cong}{=} \text{id}_X$$

constant map C'

$$\begin{aligned} C'(x_0) &= f(f'(x_0)) \\ &= f(x_0) \end{aligned}$$



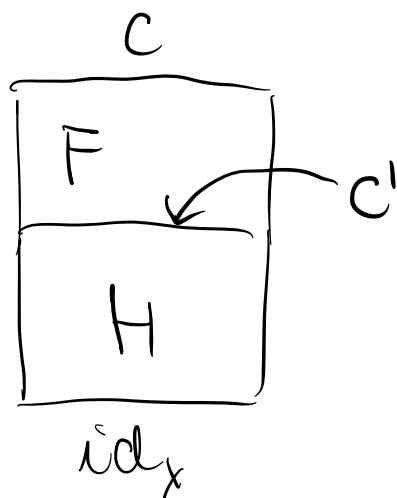
$$H(x_0, 0) = x_0$$

$$H(x_0, 1) = C'(x_0)$$

$H(x_0, t)$ is a path from x_0 to $C'(x_0)$

Homotopy between C' and C is given

by $F(x, t) = H(x_0, t)$ for $t \in [0, 1]$.



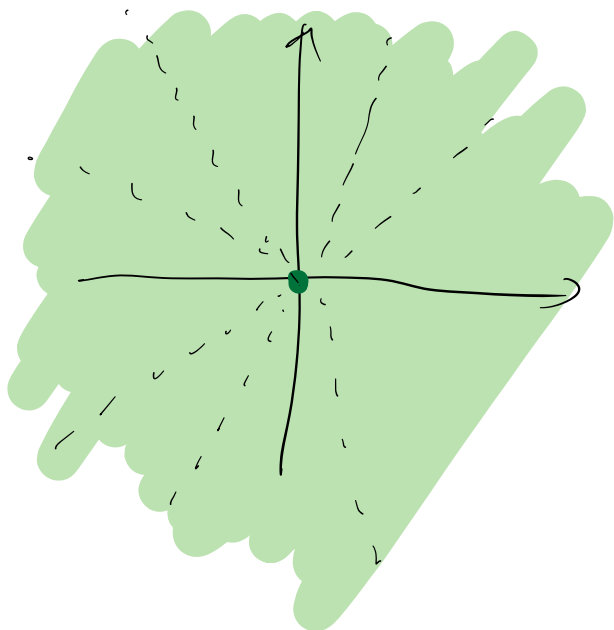
Homotopy between id_x & C is given by

$$H * F = \begin{cases} H(x, 2t) & 0 \leq t \leq \frac{1}{2} \\ H(x_0, 2t-1) & \frac{1}{2} \leq t \leq 1 \end{cases}$$

Concatenation of homotopies

Example

$X = \mathbb{R}^n$ is contractible.



this is a homotopy between id & a constant map

$$F(x, t) = t \cdot x$$

$$F(x, 0) = 0$$

$$F(x, 1) = x = id_{\mathbb{R}^n}(x)$$