

## Exercise Sheet 3

### 1. Differentiability

Let  $M \subset \mathbb{R}^n$  be an  $m$ -dimensional submanifold,  $F: M \rightarrow \mathbb{R}^k$  a map and  $p \in M$ . Show that the following statements are equivalent.

- (i)  $F$  is differentiable in  $p$  (as defined in the lecture).
- (ii) There exist an open neighborhood  $V$  of  $p$  in  $\mathbb{R}^n$  and a map  $\bar{F}: V \rightarrow \mathbb{R}^k$  differentiable in  $p$  with

$$\bar{F}|_{V \cap M} = F|_{V \cap M}.$$

### 2. Orientability

- (i) Let  $W \subset \mathbb{R}^n$  be an open set,  $f: W \rightarrow \mathbb{R}$  a  $C^1$ -map and  $y \in \mathbb{R}$  a regular value of  $f$ . Prove that  $M := f^{-1}(\{y\})$  is an orientable submanifold.
- (ii) Prove that the submanifolds  $\text{SL}(n, \mathbb{R})$  and  $\text{SO}(n, \mathbb{R})$  are orientable.

### 3. Angle-preserving parametrization

Let  $U \subset \mathbb{R}^m$  be an open set and  $f: U \rightarrow \mathbb{R}^n$  an immersion. The map  $f$  is called *angle-preserving* if for all  $x \in U$  and  $\xi, \eta \in TU_x$  the angles between  $\xi, \eta$  and  $df_x(\xi), df_x(\eta)$  coincide. Here the angles are meant with respect to the standard scalar products on  $\mathbb{R}^m$  and  $\mathbb{R}^n$ , respectively.

- (i) Show that  $f$  is angle-preserving if and only if  $g_{ij} = \lambda^2 \delta_{ij}$ , where  $g_{ij}$  is the matrix of the first fundamental form of  $f$ ,  $\delta_{ij}$  is the Kronecker delta and  $\lambda: U \rightarrow \mathbb{R}$  is a differentiable function.
- (ii) Find an angle-preserving parametrization of the 2-sphere without North and South Pole,  $S^2 \setminus \{N, S\} \subset \mathbb{R}^3$ , of the form

$$f(x, y) = \left( \sqrt{1 - h^2(y)} \cos(x), \sqrt{1 - h^2(y)} \sin(x), h(y) \right),$$

where  $h: \mathbb{R} \rightarrow \mathbb{R}$  is an odd function.