

Solutions 2

1. Characterization of convex curves

Let $c \in C^2([0, L], \mathbb{R}^2)$ be a simply C^2 -closed curve parametrized by arc-length. Show that the following two statements are equivalent:

- (i) The curvature κ_{or} of c doesn't change sign, that is, $\kappa_{\text{or}}(t) \geq 0$ for all $t \in [0, L]$ or $\kappa_{\text{or}} \leq 0$ for all $t \in [0, L]$.
- (ii) The curve c is *convex*, that is, the image of c is the boundary of a convex subset $C \subset \mathbb{R}^2$.

*Solution.*¹ We begin by noticing that c is convex if and only if for each $t \in [0, L]$ the curve lies in one of the closed half-planes determined by the tangent line at $c(t)$.

Let $\dot{c} = e_1: [0, L] \rightarrow S^1$ be the tangent indicatrix and let $\theta: [0, L] \rightarrow \mathbb{R}$ be a continuous (hence differentiable, as seen in class) polar angle function for e_1 , that is,

$$e_1(s) = (\cos \theta(s), \sin \theta(s))$$

for all $s \in [0, L]$. Then

$$\dot{e}_1(s) = \theta'(s)(-\sin \theta(s), \cos \theta(s)) = \theta'(s)e_2(s)$$

and using the first Frenet equation we conclude that $\theta' = \kappa_{\text{or}}$, thus

$$\int_0^t \kappa_{\text{or}}(s) ds = \theta(t) - \theta(0).$$

This shows that the condition that κ_{or} doesn't change sign is equivalent to θ being monotonic.

We now prove $(i) \Rightarrow (ii)$. Suppose that κ_{or} doesn't change sign. Without loss of generality we might assume that it's always ≥ 0 and θ is non-decreasing. Assume that c is not convex. Then there exist $t_0 \in [0, L]$ such that points of $c([0, L])$ can be found on both sides of the tangent line T at $c(t_0)$. Denote by $n := \ddot{c}(t_0)/|\ddot{c}(t_0)|$ the normal vector to c at t_0 and define $h: [0, L] \rightarrow \mathbb{R}$ by

$$h(t) := \langle c(t) - c(t_0), n \rangle.$$

The map h measures the distance of $c(t)$ from T . Since $[0, L]$ is compact and c runs on both sides of T , the map h has a maximum at $t_1 \neq t_0$ and a minimum at $t_2 \neq t_0$ with $h'(t_1) = h'(t_2) = 0$.

Therefore $\langle \dot{c}(t_0), n \rangle = \langle \dot{c}(t_1), n \rangle = \langle \dot{c}(t_2), n \rangle = 0$, that is, $\dot{c}(t_0), \dot{c}(t_1), \dot{c}(t_2)$ are parallel (but with the three tangent lines at $c(t_0), c(t_1)$ and $c(t_2)$ pairwise distinct) and so there are $s_1 < s_2 \in \{t_0, t_1, t_2\}$ such that $\dot{c}(s_1) = \dot{c}(s_2)$.

Since θ is non-decreasing this shows that $\theta(s_2) - \theta(s_1) = 2\pi k$ for some $k \in \mathbb{N}_0$. The Theorem of turning tangents, together with the fact that θ is non-decreasing, implies that k is either 0 or 1.

If $k = 0$ then θ is constant on $[s_1, s_2]$, which means that $c([s_1, s_2])$ is a straight line parallel to T ; this contradicts the fact that the three tangent lines are different.

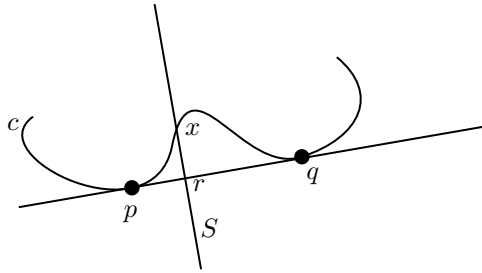
¹The reader is advised: some pictures might be helpful.

If $k = 1$ then θ must be constant on $[0, s_1]$ and on $[s_2, L]$, which implies that c is a straight line from one of the s_i 's and the remaining t_j . Again this is a contradiction.

We now prove $(ii) \Rightarrow (i)$. Suppose that c is convex and that κ_{or} changes sign. Then there are $t_1 < t_2$ in $[0, L]$ with $\theta(t_1) = \theta(t_2)$ and θ not constant on $[t_1, t_2]$. By the Theorem of turning tangents \dot{c} maps surjectively onto S^1 , so there exists $t_3 \in [0, L]$ with $\dot{c}t_1 = -\dot{c}t_3$.

If the tangent lines at $c(t_1)$, $c(t_2)$ and $c(t_3)$ are pairwise distinct, then they are parallel and one of them lies between the other two. This can't be the case since c is convex, thus two of the tangent lines coincide and there are points $p, q \in \{c(t_1), c(t_2), c(t_3)\}$ lying on the same tangent line.

We claim that the arc of c connecting p to q is the straight line segment $\bar{p}q$ from p to q . Suppose that $r \in \bar{p}q$ is not on c and denote by S the straight line perpendicular to $\bar{p}q$ at r .



Since p and q lie on distinct sides of S , by convexity we know that S is nowhere tangent to c . Thus S intersect c in at least two points, say x and y , where x is the nearest point to r . Then the tangent line to c at x has y on one side and at least one of p and q on the other, contradicting convexity.

Hence r doesn't exist, the arc of c connecting p to q is given by $\bar{p}q$ and p, q must be $c(t_1), c(t_2)$. In particular θ is constant on $[t_1, t_2]$, contradiction.

2. Submanifolds

Prove that the following matrix groups are submanifolds of $\mathbb{R}^{n \times n}$:

- (i) $\text{SL}(n, \mathbb{R}) := \{A \in \mathbb{R}^{n \times n} : \det A = 1\}$,
- (ii) $\text{SO}(n, \mathbb{R}) := \{A \in \text{GL}(n, \mathbb{R}) : A^{-1} = A^T, \det A = 1\}$.

Solution. The idea is to write $\text{SL}(n, \mathbb{R})$ and $\text{SO}(n, \mathbb{R})$ as preimages of regular values of smooth maps.

- (i) Consider the smooth map $F: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $A \mapsto \det A$. Notice that F is smooth and $\text{SL}(n, \mathbb{R}) = F^{-1}(1)$ so we want to show that 1 is a regular value for F , that is, $D_A F: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ is surjective for all A in $\text{SL}(n, \mathbb{R})$. Since \mathbb{R} is one dimensional it suffices to show that $D_A F$ is not zero for all $A \in \text{SL}(n, \mathbb{R})$. Indeed

$$\begin{aligned} D_A F(A) &= \left. \frac{d}{dt} \right|_{t=0} F(A + tA) \\ &= \left. \frac{d}{dt} \right|_{t=0} \det(A(1+t)) \\ &= \left. \frac{d}{dt} \right|_{t=0} (1+t)^n \det A \\ &= \left. \frac{d}{dt} \right|_{t=0} (1+t)^n \\ &= n \neq 0. \end{aligned}$$

- (ii) Consider the open subset $W := \{A \in \mathbb{R}^{n \times n} : \det A > 0\} \subset \mathbb{R}^{n \times n}$ and the smooth map $F: W \rightarrow \mathbb{R}^{n(n+1)/2} \cong \text{Symm}(n)$, $A \mapsto AA^T$. Notice that

$$\begin{aligned} F^{-1}(I) &= \{A \in \mathbb{R}^{n \times n} : \det A > 0, AA^T = I\} \\ &= \{A \in \mathbb{R}^{n \times n} : \det A = 1, AA^T = I\} \\ &= \text{SO}(n, \mathbb{R}). \end{aligned}$$

We want to show that I is a regular value of F , that is, $D_A F: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n(n+1)/2}$ is surjective for all A in $\text{SO}(n, \mathbb{R})$. For $B \in \mathbb{R}^{n \times n}$ we compute

$$\begin{aligned} D_A F(B) &= \left. \frac{d}{dt} \right|_{t=0} F(A + tB) \\ &= \left. \frac{d}{dt} \right|_{t=0} (A + tB)(A + tB)^T \\ &= \left. \frac{d}{dt} \right|_{t=0} (A + tB)(A^T + tB^T) \\ &= \left. \frac{d}{dt} \right|_{t=0} AA^T + t(BA^T + AB^T) + t^2 BB^T \\ &= BA^T + AB^T. \end{aligned}$$

Hence given any X in $\mathbb{R}^{n(n+1)/2} \cong \text{Symm}(n)$, set $B := \frac{1}{2}XA$, then

$$D_A F(B) = \frac{1}{2}XAA^T + A\left(\frac{1}{2}XA\right)^T = \frac{1}{2}XAA^T + \frac{1}{2}AA^T X^T = X.$$

This shows that $D_A F$ is surjective for all $A \in F^{-1}(I)$ and $\text{SO}(n, \mathbb{R})$ is a submanifold of $\mathbb{R}^{n \times n}$.

3. Tangent bundle

Let $M \subset \mathbb{R}^n$ be an m -dimensional submanifold. Show that the *tangent bundle*

$$TM := \bigcup_{p \in M} \{p\} \times TM_p$$

is a $2m$ -dimensional submanifold of \mathbb{R}^{2n} .

Solution. $TM \subset \mathbb{R}^{2n}$ is a $2m$ -submanifold of \mathbb{R}^{2n} if and only if for all $(p_0, X_0) \in TM$ there exist open sets $U \subset \mathbb{R}^{2m}$, $V \subset \mathbb{R}^{2n}$, an immersion $f: U \rightarrow \mathbb{R}^{2n}$ such that $(p_0, X_0) \in f(U) = TM \cap V$ and $f: U \rightarrow TM \cap V$ is a homeomorphism.

Let $(p_0, X_0) \in TM$ then there exists a local parametrization: open sets $U_0 \subset \mathbb{R}^m$, $V_0 \subset \mathbb{R}^n$, an immersion $\varphi: U_0 \rightarrow \mathbb{R}^n$ with $p_0 \in \varphi(U_0) = M \cap V_0$ and $\varphi: U_0 \rightarrow M \cap V_0$ is a homeomorphism.

We define a local parametrization of TM at (p_0, X_0) as follows: let $U := U_0 \times \mathbb{R}^m \subset \mathbb{R}^{2m}$, $V := V_0 \times \mathbb{R}^n \subset \mathbb{R}^{2n}$ and $f: U \rightarrow \mathbb{R}^{2n}$ defined by

$$f(x, \xi) = (\varphi(x), D_x \varphi(\xi)).$$

Since φ is smooth, the same holds for f . The derivative of f at (x, ξ) is given by

$$D_{(x, \xi)} f = \begin{pmatrix} D_x \varphi & 0 \\ * & D_x \varphi \end{pmatrix},$$

because $D_\xi(D_x \varphi) = D_x \varphi$ by linearity² of $D_x \varphi$. As φ is an immersion $D_x \varphi$ has rank m , so $D_{x, \xi} f$ has rank $2m$ and we conclude that f is an immersion.

Moreover

$$\begin{aligned} f(U) &= f(U_0 \times \mathbb{R}^m) = \bigcup_{x \in U_0} \{\varphi(x)\} \times D_x \varphi(\mathbb{R}^m) = \bigcup_{p \in \varphi(U_0)} \{p\} \times TM_p \\ &= \bigcup_{p \in M \cap V_0} \{p\} \times TM_p = TM \cap (V_0 \times \mathbb{R}^n) = TM \cap V \end{aligned}$$

and $(p_0, X_0) \in f(U)$.

In order to show that $f: U \rightarrow TM \cap V$ is a homeomorphism, consider $g: TM \cap V \rightarrow U$:

$$g(p, X) := (\varphi^{-1}(p), D_p \varphi^{-1}(X)).$$

The functions φ^{-1} and $D_p \varphi^{-1}$ are continuous and so is g . Moreover

$$\begin{aligned} f \circ g(p, X) &= f(\varphi^{-1}(p), D_p \varphi^{-1}(X)) \\ &= (p, D_{\varphi^{-1}(p)} \varphi D_p \varphi^{-1}(X)) \\ &= (p, D_p(\varphi \circ \varphi^{-1})(X)) \\ &= (p, X), \end{aligned}$$

and similarly

$$g \circ f(x, \xi) = g(\varphi(x), D_x \varphi(\xi)) = (\varphi^{-1} \circ \varphi(x), D_{\varphi(x)} \varphi^{-1} D_x \varphi(\xi)) = (x, \xi).$$

This shows that $f^{-1} = g$ is continuous.

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$$D_\xi(D_x \varphi)(X) = \left. \frac{d}{dt} \right|_{t=0} D_x \varphi(\xi + tX) = \left. \frac{d}{dt} \right|_{t=0} D_x \varphi(\xi) + t D_x \varphi(X) = D_x \varphi(X).$$