

Solutions Sheet 1

1. a. For  $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{GL}_2(\mathbb{R})$  with  $c \neq 0$  and  $z \in \mathbb{C} \setminus \{-\frac{d}{c}\}$  we have

$$\gamma \circ z = \frac{az + b}{cz + d} = \frac{(az + b)(c\bar{z} + d)}{|cz + d|^2} = \frac{ac|z|^2 + adz + bc\bar{z} + bd}{|cz + d|^2}.$$

Taking imaginary parts on both sides we get

$$\text{Im}(\gamma \circ z) = \frac{(ad - bc) \cdot \text{Im}(z)}{|cz + d|^2} = \frac{\det(\gamma) \cdot \text{Im}(z)}{|cz + d|^2}.$$

- b. The image of the complex upper half-plane  $\mathbb{H}$  under the action of  $\gamma$  is  $\mathbb{H}$  if  $\det(\gamma) > 0$ , and it is  $\mathbb{H}^- := \{z \in \mathbb{C} : \text{Im}(z) < 0\}$  if  $\det(\gamma) < 0$ .
- c. It does not define a group action on  $\mathbb{R}$  due to the existence of poles, i.e. if  $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  with  $c \neq 0$  then  $\gamma \circ (-\frac{d}{c}) = \infty \notin \mathbb{R}$ . The action must be defined on  $\mathbb{R} \cup \{\infty\}$  with the usual conventions concerning the value of  $\gamma \circ \infty$  (see Lecture 2).

2. a. We have

$$f\left(\frac{a\tau + b}{c\tau + d}\right) = F\left(\left(\frac{a\tau + b}{c\tau + d}\right)\mathbb{Z} + \mathbb{Z}\right) = (c\tau + d)^k F((a\tau + b)\mathbb{Z} + (c\tau + d)\mathbb{Z}).$$

Since  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(\mathbb{Z})$  we have  $(a\tau + b)\mathbb{Z} + (c\tau + d)\mathbb{Z} = \tau\mathbb{Z} + \mathbb{Z}$  (see Lecture 1), thus

$$f\left(\frac{a\tau + b}{c\tau + d}\right) = (c\tau + d)^k F(\tau\mathbb{Z} + \mathbb{Z}) = (c\tau + d)^k f(\tau).$$

- b. Given  $f : \mathbb{H} \rightarrow \mathbb{C}$  define  $F_f : \mathcal{L} \rightarrow \mathbb{C}$  by

$$F_f(\omega_1\mathbb{Z} + \omega_2\mathbb{Z}) := \omega_2^{-k} f\left(\frac{\omega_1}{\omega_2}\right), \text{ for } \{\omega_1, \omega_2\} \text{ basis of } \mathbb{R}^2 \text{ with } \frac{\omega_2}{\omega_1} \in \mathbb{H}.$$

The function  $F_f$  is well defined since  $\omega'_1\mathbb{Z} + \omega'_2\mathbb{Z} = \omega_1\mathbb{Z} + \omega_2\mathbb{Z}$  with  $\frac{\omega'_1}{\omega'_2} \in \mathbb{H}$  implies

$$\begin{pmatrix} \omega'_1 \\ \omega'_2 \end{pmatrix} = \gamma \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix} \text{ for some matrix } \gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(\mathbb{Z}),$$

hence

$$(\omega'_2)^{-k} f\left(\frac{\omega'_1}{\omega'_2}\right) = (c\omega_1 + d\omega_2)^{-k} f\left(\gamma \circ \frac{\omega_1}{\omega_2}\right) = (c\omega_1 + d\omega_2)^{-k} \left(c\frac{\omega_1}{\omega_2} + d\right)^k f\left(\frac{\omega_1}{\omega_2}\right) = \omega_2^{-k} f\left(\frac{\omega_1}{\omega_2}\right).$$

This proves that  $F_f$  is well defined. Now, for  $\lambda \in \mathbb{C}^\times$  and  $L = \omega_1\mathbb{Z} + \omega_2\mathbb{Z} \in \mathcal{L}$  we have

$$F_f(\lambda L) = F_f(\lambda\omega_1\mathbb{Z} + \lambda\omega_2\mathbb{Z}) = (\lambda\omega_2)^{-k} f\left(\frac{\lambda\omega_1}{\lambda\omega_2}\right) = \lambda^{-k} \omega_2^{-k} f\left(\frac{\omega_1}{\omega_2}\right) = \lambda^{-k} F_f(L).$$

This proves that  $F_f$  satisfies the required transformation property.

We will now show that  $f \mapsto F_f$  is the inverse map of  $F \mapsto f_F$ . Indeed, if  $F = F_f$  then

$$f_F(\tau) = F(\tau\mathbb{Z} + \mathbb{Z}) = 1^{-k} f\left(\frac{\tau}{1}\right) = f(\tau),$$

and if  $f = f_F$  then we have

$$F_f(\omega_1\mathbb{Z} + \omega_2\mathbb{Z}) = \omega_2^{-k} f\left(\frac{\omega_1}{\omega_2}\right) = \omega_2^{-k} F\left(\frac{\omega_1}{\omega_2}\mathbb{Z} + \mathbb{Z}\right) = F(\omega_1\mathbb{Z} + \omega_2\mathbb{Z}).$$

3. a. We observe that hyperbolas (resp. ellipses, parabolas) are mapped to hyperbolas (resp. ellipses, parabolas) under the linear action of  $\mathrm{SL}_2(\mathbb{R})$  on  $\mathbb{R}^2$ . Indeed, this can be proven algebraically by noting that a quadratic curve of the form

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0, \quad (1)$$

can also be written as

$$\begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} A & B/2 \\ B/2 & C \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} D & E \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + F = 0,$$

hence the image of (1) under  $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is the quadratic curve

$$\begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} A' & B'/2 \\ B'/2 & C' \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} D' & E' \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + F = 0,$$

where

$$\begin{pmatrix} A' & B'/2 \\ B'/2 & C' \end{pmatrix} = (\gamma^{-1})^t \begin{pmatrix} A & B/2 \\ B/2 & C \end{pmatrix} \gamma^{-1}, \text{ and } \begin{pmatrix} D' & E' \end{pmatrix} = \begin{pmatrix} D & E \end{pmatrix} \gamma^{-1}.$$

This implies

$$\det \begin{pmatrix} A & B/2 \\ B/2 & C \end{pmatrix} = \det \begin{pmatrix} A' & B'/2 \\ B'/2 & C' \end{pmatrix},$$

hence  $B^2 - 4AC = (B')^2 - 4(A')(C')$ . By the distinction of conics according to the sign of the *discriminant*  $B^2 - 4AC$  we conclude that hyperbolas (resp. ellipses, parabolas) are mapped to hyperbolas (resp. ellipses, parabolas).

Now, let  $\gamma \in \mathrm{SL}_2(\mathbb{R})$  be a matrix different from  $\pm \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ . If  $M \in \mathrm{SL}_2(\mathbb{R})$  then the

invariant sets of  $M\gamma M^{-1}$  are all of the form  $M \circ Y$  where  $Y$  is an invariant set of  $\gamma$ . Thus, it is enough to prove the result for  $M\gamma M^{-1}$ . In what follows we use some results presented in Lecture 2 of the course.

If  $\gamma$  is elliptic, then it is conjugated to a matrix of the form  $\begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}$  with  $\theta \in \mathbb{R}$ .

This acts on  $\mathbb{R}^2$  as a rotation around the origin, hence all circles (which are special cases of ellipses) centered at  $(0, 0)$  are invariant.

If  $\gamma$  is hyperbolic, then it is conjugated to matrix of the form  $\begin{pmatrix} \lambda & 0 \\ 0 & \lambda^{-1} \end{pmatrix}$  with

$\lambda \in \mathbb{R}, \lambda \neq 0, 1, -1$ . This acts on  $\mathbb{R}^2$  leaving invariant each hyperbola of equation  $xy = t$ , with  $t \in \mathbb{R}, t \neq 0$  a parameter.

- b. If  $\gamma$  is parabolic, then it is conjugated to matrix of the form  $\begin{pmatrix} 1 & \lambda \\ 0 & 1 \end{pmatrix}$  with  $\lambda \in \mathbb{R}, \lambda \neq 0$ .

This acts on  $\mathbb{R}^2$  leaving invariant each line of equation  $y = t$ , with  $t \in \mathbb{R}$  a parameter.

4. Put  $\gamma = \begin{pmatrix} 4 & -9 \\ -11 & 25 \end{pmatrix}$ . We follow the algorithm presented in Lecture 3. First we write

$$25 = (-11) \cdot (-2) + 3$$

and compute

$$\gamma T^2 S = \begin{pmatrix} 4 & -1 \\ -11 & 3 \end{pmatrix} S = \begin{pmatrix} -1 & -4 \\ 3 & 11 \end{pmatrix}.$$

Now we write  $11 = 3 \cdot 3 + 2$  and compute

$$\gamma T^2 S T^{-3} S = \begin{pmatrix} -1 & -1 \\ 3 & 2 \end{pmatrix} S = \begin{pmatrix} -1 & 1 \\ 2 & -3 \end{pmatrix}.$$

We write  $-3 = 2 \cdot (-2) + 1$  and compute

$$\gamma T^2 S T^{-3} S T^2 S = \begin{pmatrix} -1 & -1 \\ 2 & 1 \end{pmatrix} S = \begin{pmatrix} -1 & 1 \\ 1 & -2 \end{pmatrix}.$$

Finally, we write  $-2 = 1 \cdot (-2)$  and compute

$$\gamma T^2 S T^{-3} S T^2 S T^2 S = \begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} S = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} = S^2 T^{-1}.$$

We get  $\gamma = S^2 T^{-1} S T^{-2} S T^{-2} S T^3 S T^{-2}$ .

5. a. The group  $\Gamma_\theta$  contains the subgroup

$$\Gamma(2) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{SL}_2(\mathbb{Z}) : \begin{pmatrix} a & b \\ c & d \end{pmatrix} \equiv \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \pmod{2} \right\},$$

which is of index 6 in  $\mathrm{SL}_2(\mathbb{Z})$  since it is the kernel of the reduction mod 2 map to  $\mathrm{SL}_2(\mathbb{Z}/2\mathbb{Z})$ , and the group  $\mathrm{SL}_2(\mathbb{Z}/2\mathbb{Z})$  is the image of the set

$$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} \right\} \subseteq \mathrm{SL}_2(\mathbb{Z}).$$

We have

$$\Gamma_\theta = \Gamma(2) \cup \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \Gamma(2),$$

hence  $[\Gamma_\theta : \Gamma(2)] = 2$ . It follows that  $\Gamma_\theta$  has index 3 in  $\mathrm{SL}_2(\mathbb{Z})$ .

- b. A set of representatives for  $\Gamma_\theta \backslash \mathrm{SL}_2(\mathbb{Z})$  is given by the matrices

$$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, TS = \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \right\}.$$

Hence, letting  $F = \{\tau \in \mathbb{H} : |\tau| \geq 1, |\mathrm{Re}(\tau)| \leq \frac{1}{2}\}$  be the usual fundamental domain for  $\mathrm{SL}_2(\mathbb{Z})$  (see Lecture 3), we get that a fundamental domain for  $\Gamma_\theta$  is

$$F' = F \cup T(F) \cup TS(F).$$

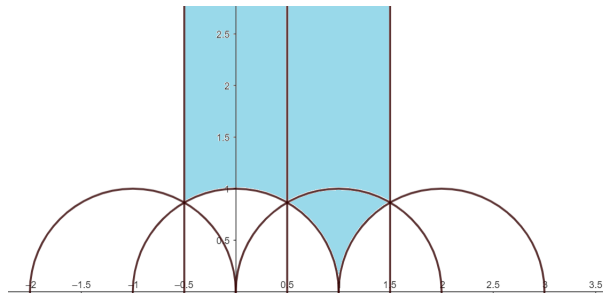


FIGURE 1. Fundamental domain  $F'$

We note that  $F' = F_1 \cup F_2$  where

$$F_1 := \left\{ \tau \in \mathbb{H} : |\tau| \geq 1, -\frac{1}{2} \leq \mathrm{Re}(\tau) \leq 1 \right\}, F_2 := \left\{ \tau \in \mathbb{H} : |\tau - 2| \geq 1, 1 \leq \mathrm{Re}(\tau) \leq \frac{3}{2} \right\}.$$

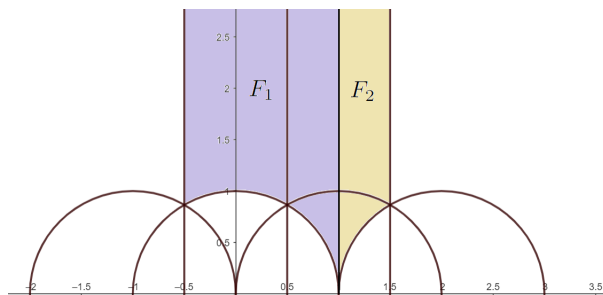
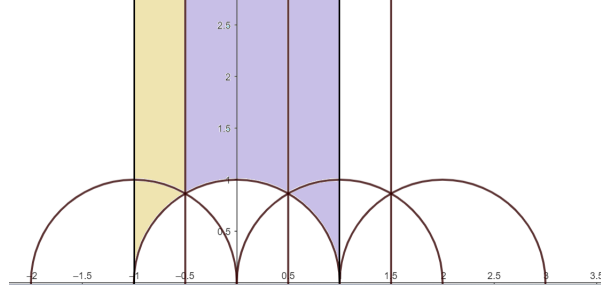


FIGURE 2. Decomposition of  $F'$  into  $F_1$  and  $F_2$

We have

$$F_\theta = F_1 \cup T^{-2}F_2,$$

hence  $F_\theta$  is a fundamental domain for  $\Gamma_\theta$ .

FIGURE 3. Fundamental domain  $F_\theta$ 

- c. We will use that  $F_\theta$  is a fundamental domain for  $\Gamma_\theta$ , hence for every point  $z$  in the interior of  $F_\theta$  we have

$$\gamma_0 \in \Gamma_\theta, \gamma_0 \circ z \in F_\theta \Rightarrow \gamma_0 = \pm \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Let  $\gamma \in \Gamma_\theta$  and choose  $z$  a point in the interior of  $F_\theta$  (e.g.  $z = 2i$ ). Put  $z_0 = \gamma \circ z$ . Choose  $n_1 \in \mathbb{Z}$  so that  $z_1 := T^{2n_1} \circ z_0$  lies in  $R := \{\tau \in \mathbb{H} : |\operatorname{Re}(\tau)| \leq 1\}$ . If  $|z_1| < 1$  then apply  $S$  to  $z_1$  and choose  $n_2 \in \mathbb{Z}$  so that  $z_2 := T^{2n_2} S \circ z_1 \in R$ . Repeat this process as many times as necessary to end up with a point of the form

$$z_k = (T^{2n_k} S \dots T^{2n_3} S T^{2n_2} S T^{2n_1}) \circ z_0$$

in  $F_\theta$ . Note that this process must end after finitely many steps since

$$\operatorname{Im}(z_{t+1}) = \frac{\operatorname{Im}(z_t)}{|z_t|^2}, \text{ for all } t \in \{1, \dots, k-1\} \text{ if } k \geq 1,$$

hence  $\operatorname{Im}(z_0) = \operatorname{Im}(z_1) < \operatorname{Im}(z_2) < \dots$ , but

$$\operatorname{Im}(M \circ z_0) = \frac{\operatorname{Im}(z_0)}{|cz_0 + d|^2}, \text{ if } M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma_\theta,$$

and  $|cz_0 + d| < 1$  gives finitely many possibilities for the integers  $c$  and  $d$ . Since  $z_k$  is in  $F_\theta$  and it is  $\Gamma_\theta$ -equivalent to  $z_0$  we conclude

$$T^{2n_k} S \dots T^{2n_3} S T^{2n_2} S T^{2n_1} \gamma = \pm \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Since  $S^2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ , this implies that  $\gamma$  is in the group generated by  $T^2$  and  $S$ .