

In this lecture we cover chapters 5 & 6 of the book "The geometry of the group of symplectic diffeomorphisms" by L. Polterovich.

Chapter 5: linearisation of Hofer's Geometry

GOAL: Interpret Hofer's metric as distance between a point and a linear subspace.

5.1. Space of periodic Hamiltonians

$\mathcal{F} := \{F: M \times \mathbb{R} \rightarrow \mathbb{R} \text{ smooth normalized Hamiltonians with } F(x, t) = F(x, t+1)\}$

Lemma 1: A flow $\{f_t\}_{t \in \mathbb{R}}$ generated by some $F \in \mathcal{F} \Leftrightarrow f_{t+1} = f_t f_1 \quad \forall t \in \mathbb{R}$

Proof of Lemma 1: Let $\frac{d}{dt} f_t = X_t f_t$

" \Rightarrow ": If $F_t = F_{t+1}$, consider the initial value problem $\begin{cases} \frac{d}{dt} \varphi_t = X_t \varphi_t \\ \varphi_0 = f_1 \end{cases}$

Then $\frac{d}{dt} (f_{t+1}) = X_{t+1} (f_{t+1}) = X_t (f_{t+1}) \quad , \quad f_{0+1} = f_1$

$\frac{d}{dt} (f_t f_1) = X_t (f_t) f_1 = X_t (f_t f_1) \quad , \quad f_{0+1} = 1 f_1 = f_1$

But since the solution to the ODE is unique we get $f_{t+1} = f_t f_1$

" \Leftarrow ": $\frac{d}{dt} (f_{t+1}) = X_{t+1} (f_{t+1})$

$\frac{d}{dt} (f_t f_1) = X_t (f_t) f_1 = X_t (f_t f_1) \Rightarrow X_{t+1} = X_t$, hence $F_t = F_{t+1}$

Remark: Take any flow $\{g_t\}_{t \in \mathbb{R}}$ with $g_1 = \phi$
 Let $\alpha: [0, 1] \rightarrow [0, 1]$ with $\alpha \equiv 0$ near 0, $\alpha \equiv 1$ near 1
 Consider new flow $f_t = g_{\alpha(t)} \quad t \in [0, 1]$, extend by $f_{t+1} = f_t f_1$
 By Lemma 1, $\{f_t\}_{t \in \mathbb{R}}$ is generated by some function in \mathcal{F}

We define a norm on \mathcal{F} by $\|F\| = \max_t \|F_t\| = \max_t (\max_x F(x, t) - \min_x F(x, t))$

Notation: $F \in \mathcal{F} \rightsquigarrow$ Hamiltonian flow $\{f_t\}_{t \in \mathbb{R}} \rightsquigarrow \phi_F := f_1$

Let $\mathcal{X} = \{F \in \mathcal{F} : \phi_F = 1\} \subset \mathcal{F}$. \mathcal{X} generates Hamiltonian loops.

Theorem 1: $\forall F \in \mathcal{F} : \rho(1, \phi_F) = \inf_{H \in \mathcal{X}} \|F - H\| = \text{dist}(F, \mathcal{X})$

For the proof of this theorem we need the following lemma:

Lemma 2: $\forall \phi \in \text{Ham}(M)$ we have $\rho(1, \phi) = \inf \{ \|F\| : F \in \mathcal{F} \text{ s.t. } \phi = \phi_F \} =: \varepsilon(1, \phi)$

Proof of Thm 1 using Lemma 2:

For $F \in \mathcal{F}$ let $\{f_t\}_{t \in \mathbb{R}}$ its Hamiltonian flow

Let $\{g_t\}_{t \in \mathbb{R}}$ be another flow generated by $G \in \mathcal{F}$ with $g_1 = \phi_F$

(1) Decompose $g_t = h_t \circ f_t$ and H the normalized Hamiltonian of $\{h_t\}_{t \in \mathbb{R}}$

By Lemma 1: $H \in \mathcal{F}$ and $\{h_t\}_{t \in \mathbb{R}}$ is a loop

$$\boxed{g_0 = f_0 = 1, g_1 = f_1 = \phi_F \Rightarrow h_0 = h_1 = 1}$$

(2) Also \forall loop $\{h_t\}_{t \in \mathbb{R}}$, then $\{h_t f_t\}_{t \in \mathbb{R}}$ is generated by some function in \mathcal{F} using Lemma 1.

$$\boxed{g_t := h_t f_t, \text{ then } g_{t+1} = h_{t+1} f_{t+1} = h_t \underbrace{h_1}_{=1} f_t f_1 = (h_t f_t)(h_1 f_1) = g_t g_1}$$

Now in any case: $G(x, t) = H(x, t) + F(h_t^{-1} x, t)$

Then $H'(x, t) = -H(h_t x, t)$ generates the loop $\{h_t^{-1}\}_{t \in \mathbb{R}}$, hence $H' \in \mathcal{F}$

Therefore $\|G\| = \|F - H'\|$.

By (1), (2) every G corresponds to a unique H' and vice versa, hence we conclude by Lemma 2. □

Proof of Lemma 2:

Clearly $\mathcal{L}(1, \phi) \geq \mathcal{L}(1, \phi)$.

For $\varepsilon > 0$, let $\{f_t\}_{t \in [0, 1]}$ Hamiltonian flow with $f_0 = 1, f_1 = \phi$ & $\int_0^1 \|F_t\| dt \leq \mathcal{L}(1, \phi) + \varepsilon$

W.l.o.g let $F \in \mathcal{F}$ (by the first remark above) and $(*) \|F_t\| > 0 \forall t \in [0, 1]$

Let $\mathcal{C} = \{C^1\text{-smooth, orientation preserving diffeos of } S^1 = \mathbb{R}/\mathbb{Z} \text{ fixing } 0\}$

For $\alpha \in \mathcal{C}$, the path $\{f_t(\alpha)\}_{t \in \mathbb{R}}$ generated by $F^\alpha(x, t) = \alpha'(t) F(x, \alpha(t))$

Consider $b(t) = \frac{\int_0^1 \|F_s\| ds}{\int_0^1 \|F_t\| ds}$, let $\alpha := b^{-1}$.

$$\|F^\alpha\| = \max_t \alpha'(t) \|F_{\alpha(t)}\| = \max_t \left(\frac{\|F_t\|}{b'(t)} \right) = \int_0^1 \|F_s\| ds \leq \mathcal{L}(1, \phi) + \varepsilon$$

Approximating α by a smooth diffeo from \mathcal{C} , we get $\tilde{F} \in \mathcal{F}$ generating $\phi \pm 1$.

$$\|\tilde{F}\| \leq \mathcal{L}(1, \phi) + 2\varepsilon$$

□

Justification for (*):

Prop 1: $\{h_t\}_{t \in \mathbb{R}}$ flow generated by F , then \exists arbitrary small (in C^∞ -sense) loop $\{h_t\}_{t \in \mathbb{R}} \simeq 1$.
 $\{h_t^{-1}\}_{t \in \mathbb{R}}$ is regular, i.e. $\exists x \in M \simeq 1$. $-H(h_t x, t) + F(h_t x, t) \neq 0$

Proof: Let $y \in M$, $E := T_y^* M$. Take $2n$ - smooth closed curves $d_1, \dots, d_{2n} \simeq 1$.

(i) $\{d_1(t), \dots, d_{2n}(t)\}$ is a basis $\forall t$ and (ii) $\int_0^1 d_j(t) dt = 0 \quad \forall j$

Let $u_1, v_1, \dots, u_n, v_n$ be a basis of E take

$$\begin{aligned} d_{2j+1}(t) &= u_j \cos(2\pi t) + v_j \sin(2\pi t) \\ d_{2j+2}(t) &= -u_j \sin(2\pi t) + v_j \cos(2\pi t) \end{aligned}$$

Claim: For functions $G^{(1)}, \dots, G^{(2n)} \in \mathcal{F}$ with $\int G^{(j)}(x, t) dt = 0$ & $d_y G^{(j)} = d_j(t)$ there is a corresponding $2n$ -dim variation $\{h_t(\epsilon)\}$ for ϵ in a small neighborhood of 0 in \mathbb{R}^{2n} of the constant loop $h_t(0) = 1 \simeq 1$. $\frac{\partial}{\partial \epsilon_j} \Big|_{\epsilon=0} H(x, t, \epsilon) = G^{(j)}(x, t)$ for $H(x, t, \epsilon)$ the Hamiltonian of the variation.

Consider $\Phi: S^1 \times \mathbb{R}^{2n} \rightarrow E, (t, \epsilon) \mapsto d_y(F_t - H_t(\epsilon))$

Since $\frac{\partial}{\partial \epsilon_j} \Big|_{\epsilon=0} \Phi(t, \epsilon) = d_j(t)$, Φ is a submersion in some neighborhood U of $\epsilon = 0$

Let $\Psi = \Phi|_{S^1 \times U}$, Ψ is a submersion, $\Psi^{-1}(\{0\})$ is a 1 -dim submanifold of $S^1 \times U$, hence its projection to U is nowhere dense

$\Rightarrow \exists$ arbitrary small $\epsilon \in \mathbb{R}^{2n} \simeq 1$. $d_y(F_t - H_t(\epsilon)) \neq 0$ which proves the Proposition. \square

Construction in the claim:

First take the 1-dimensional case

Take $G \in \mathcal{F} \simeq 1$. $\int_0^1 G(x, t) dt = 0 \quad \forall x \in M$

Then let $h_t(\epsilon) \in \text{Ham}(M, \Omega)$ be the t -time ϵ map of the Hamiltonian flow generated by the time-independent Hamiltonian $\int G(x, s) ds$

Then for the corresponding Hamiltonian $H(x, t, \epsilon)$ we have $\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} H(x, t, \epsilon) = G(x, t)$

Then for function $G^{(1)}, \dots, G^{(2n)} \in \mathcal{F}$ with $\int_0^1 G^{(j)}(x, t) dt = 0$, one can construct for every j a 1-dim variation $h_t^{(j)}(\epsilon)$ as above.

Then $h_t(\epsilon_1, \dots, \epsilon_{2n}) = h_t^{(1)}(\epsilon_1) \circ h_t^{(2)}(\epsilon_2) \circ \dots \circ h_t^{(2n)}(\epsilon_{2n})$ is a $2n$ -dim variation of the constant loop with

$$\frac{\partial}{\partial \epsilon_j} \Big|_{\epsilon=0} H(x, t, \epsilon) = G^{(j)}(x, t)$$

Paths in Homotopy class

For $F \in \mathcal{F}$, $\{f_t\}_{t \in \mathbb{R}}$ the corresponding Hamiltonian. Consider

$$L(F) = \inf \{ \text{length}(\{g_t\}_t) : \{g_t\}_{t \in [0,1]} \text{ Ham. path with } g_0 = 1, g_1 = \phi_F, \{g_t\}_t \simeq \{f_t\}_t \}$$

where $\text{length}(\{g_t\}_t) = \int_0^1 \|G_s\| ds$

Remark: $L(F)$ can be identified with $\tilde{d}(\tilde{1}, \tilde{\phi}_F)$ the distance on the universal cover of $\text{Ham}(M, \Omega)$.

Let $\mathcal{H}_c \subset \mathcal{H}$ be the set of Hamiltonians that generate contractible loops or \mathcal{H}_c is the path connected component of \mathcal{H} containing 0.

Theorem 2: $\forall F \in \mathcal{F} : L(F) = \inf_{H \in \mathcal{H}_c} \|F - H\|$

The proof of this theorem proceeds in the same way, just note that:

- Time reparametrizations & Regularisation doesn't change the homotopy class of a path with fixed end points. Hence it suffices to prove that

$$L(F) = \inf \{ \|G\| : G \in \mathcal{F} \text{ with } \phi_G = \phi_F \text{ with Ham. flow of } G \text{ homotopic to } \{f_t\}_t \}$$

- $g_t = h_t \circ f_t$ & g_t is homotopic to $f_t \Rightarrow h_t$ is contractible

Chapter 6: Lagrangian intersections

6.1 Exact Lagrangian isotopies

(V^{2n}, ω) symplectic manifold, N^n closed manifold.

Let $\Phi: N \times [0, 1] \rightarrow V$ be a Lagrangian isotopy, i.e. $\{\Phi_t = \Phi(\cdot, t)\}_{t \in [0, 1]}$ is a smooth family of Lagrangian embeddings.

$$\Phi^* \omega = \alpha_s \lrcorner ds \quad \text{for } \{\alpha_s\}_s \text{ a family of 1-forms on } N \text{ since } \Phi^* \omega|_{N \times \{t_0\}} \equiv 0$$

Also $d\Phi^* \omega = d\alpha_s \lrcorner ds \equiv 0 \Rightarrow \alpha_s$ is closed $\forall s$

Def: Φ is exact if α_s is exact $\forall s$

Let $\{h_{t,s}\}_{t \in S^1, s \in [0, 1]}$ be a smooth family of Hamiltonian loops of (M, Ω) generated by $H(x, t, s)$
 $L \subset M$ a closed Lagrangian submanifold. Then

$$\Phi: L \times S^1 \times [0, 1] \rightarrow M \times T^*S^1 \text{ is the corresponding family of Lagrangian suspensions} \\ (x, t, s) \mapsto (h_{t,s}(x), -H(h_{t,s}(x), t, s))$$

Theorem 3: Φ is exact.

Proof: Write $\Phi^*(\Omega + dt \lrcorner dt) = \alpha_s \lrcorner ds$
Hence we need to check that α_s is exact

As in Chapter 3.1. E one can find that for $x \in L, \xi \in T_x L$:

$$\alpha_s(\xi) = \Omega((h_{t,s})_* \xi, \frac{\partial h_{t,s}}{\partial s}(x)) ; \alpha_s\left(\frac{\partial}{\partial t}\right) = \frac{\partial H}{\partial s}(h_{t,s}(x), t, s)$$

Elements in $H_1(L \times S^1, \mathbb{Z})$ are generated by elements of the form $C = \beta \times \{0\}, D = \gamma \times S^1$
(Algebraic K nneth Formula) for β a cycle on $L, \gamma \in L$

Hence we need to prove that for all 1-cycles their integral vanishes

For cycles like C above we have that since $h_{0,s} = 1$ that α_s vanishes on all tangent vectors to $L \times \{s=0\}$

$$\text{Also } \int_D \alpha_s = \int_0^1 \frac{\partial H}{\partial s}(h_{t,s}(\gamma), t, s) dt \stackrel{(*)}{=} 0$$

For $(*)$ one proves that $\frac{\partial}{\partial s} H(h_{t,s}(x), t, s)$ is the derivative of a periodic function w.r.t. t .

□

┌ see Prop 6.1C in the book for the proof of $(*)$ ─┘

6.2 Lagrangian Intersections

Def: A Lagrangian submanifold $N \subset V$ has the Lagrangian intersection property (LIP) if $N \cap \Phi(N) \neq \emptyset \quad \forall \Phi \in \text{Ham}(M, \omega) \iff e(N) = +\infty$

Example: Gromov's Theorem

- If $\pi_2(V, N) = 0$ & V has "nice" behaviour at infinity, then N has this property.
- If $\pi_2(V, N) \neq 0$, take e.g. $V = S^2$, N a small enough circle, then N can be displaced.

Def: A closed Lagrangian submanifold L of (M, Ω) has the stable Lagrangian intersection property if $L \times \{r=0\}$ has the LIP in $(M \times T^*S^1, \Omega + dr \lrcorner dt)$

Examples:

- Lagrangian torus in the cotangent bundle $T^*\mathbb{T}^n$ with standard symmetric structure (by Gromov's Theorem)
- equator of S^2

6.3 Application to Hamiltonian Loops

(M, Ω) , $L \subset M$ closed Lagrangian submanifold that has the LIP
 $\{g_t\}_{t \in S^1}$ loop of Hamiltonian diffeos generated by $G \in \mathcal{H}$
 s.t. $g_t(L) = L \quad \forall t \in S^1$; $G(x, t) = 0 \quad \forall x \in L, t \in S^1$

Theorem 4: $\{h_t\}_{t \in S^1}$ loop of Ham. diffeomorphisms homotopic to $\{g_t\}_{t \in S^1}$ with Hamiltonian $H \in \mathcal{H}$.
 Then $\exists (x, t) \in L \times S^1$ s.t. $H(x, t) = 0$

Proof: By applying twice the Lagrangian suspension construction, we obtain two Lagrangian submanifolds N_G & N_H of $M \times T^*S^1$

Then $N_G = L \times \{r=0\}$ and N_H is isotopic to N_G by Thm 3 & the isotopy is exact

The stable LIP yields $N_H \cap N_G \neq \emptyset$, let $(x, 0, t) \in N_H \cap N_G$

Since it lies in N_H : $x = h_t y$ & $0 = -H(h_t y, t)$ for some $y \in L$ □

Cor: If $L \subset M$ has the stable LIP, then $\forall H \in \mathcal{H}_c$ there is a $x \in L, t \in S^1$ s.t. $H(x, t) = 0$

Remarks:

- Statement in the Corollary is not true if the (stable) LIP is not assumed
- Theorem 4 allows us to give non-trivial lower bounds for Hofer's distance.