

§2 Holomorphic Functions

§2-1 Definitions, basic properties

This is a central notion for the rest of the class.

Let $\Omega \subset \mathbb{C}$ an open set

$f: \Omega \rightarrow \mathbb{C}$ a complex valued function on Ω .

Defn: f is called holomorphic at $z_0 \in \Omega$

$$\lim_{\substack{z \rightarrow z_0 \\ z \neq z_0}} \frac{f(z) - f(z_0)}{z - z_0} = \lim_{\substack{h \rightarrow 0 \\ h \neq 0}} \frac{f(z_0 + h) - f(z_0)}{h} \text{ exists}$$

Here $h \in \mathbb{C}$, $z_0 + h \in \Omega$, (so that the quotient is well defined)

If the limit exists, we denote it with $f'(z_0)$.

It is called the derivative of f at z_0 .

f is called holomorphic on Ω if it is holomorphic $\forall z_0 \in \Omega$.

If f is holomorphic on all of \mathbb{C} , then it is called entire.

Remark Regular or complex differentiable are other words used for holomorphic.

Example 2.1 let $f: \mathbb{C} \rightarrow \mathbb{C}$, $f(z) = z^2$

Then f is entire. Since

$$\lim_{h \rightarrow 0} \frac{f(z_0+h) - f(z_0)}{h} = \lim_{h \rightarrow 0} \frac{(z_0+h)^2 - z_0^2}{h} = \lim_{h \rightarrow 0} \frac{2z_0h + h^2}{h} = 2z_0 + h = 2z_0$$

Hence $f'(z) = 2z \quad \forall z \in \mathbb{C}$.

As in real variables, we have

Prop 2.2. ① let $\mathcal{H}(\Omega) = \{ f: \Omega \rightarrow \mathbb{C} \mid f \text{ is hol. on } \Omega \}$

then $\mathcal{H}(\Omega)$ is a \mathbb{C} -vector space

More precisely

if $f, g \in \mathcal{H}(\Omega)$ then $\alpha f + \beta g \in \mathcal{H}(\Omega)$ for every $\alpha, \beta \in \mathbb{C}$.

$$(\alpha f + \beta g)' = \alpha f' + \beta g'$$

($0: \Omega \rightarrow \mathbb{C}$, $0(z) = 0$ is the 0. element)

② $f, g \in \mathcal{H}(\Omega) \Rightarrow fg \in \mathcal{H}(\Omega)$

$$\text{and } (fg)' = f'g + fg'$$

③ if $g(z_0) \neq 0$ then f/g is hol. at z_0 and

$$(f/g)' = \frac{f'g - fg'}{g^2}$$

if $g(z) \in \mathcal{H}(\Omega)$ and $g(z) \neq 0 \quad \forall z \in \Omega$ then $f/g \in \mathcal{H}(\Omega)$.

④ If $f: \Omega \rightarrow U$, $g: U \rightarrow \mathbb{C}$ are holom, then $g \circ f: \Omega \rightarrow \mathbb{C}$ is hol and

$$(g \circ f)'(z) = g'(f(z)) \cdot f'(z) \quad \forall z \in \Omega$$

Proofs Very similar to the case of real variables. Here I will just give the proof of ④.

Let $z_0 \in \Omega$, $f(z_0) = w_0 \in U$

Consider $F: \Omega \rightarrow \mathbb{C}$, $G: U \rightarrow \mathbb{C}$ defined by

$$F(z) = \begin{cases} \frac{f(z) - f(z_0)}{z - z_0} & \text{if } z \neq z_0 \\ f'(z_0) & \text{if } z = z_0 \end{cases}$$

$$G(w) = \begin{cases} \frac{g(w) - g(w_0)}{w - w_0} & \text{if } w \neq w_0 \\ g'(w_0) & \text{if } w = w_0 \end{cases}$$

Since $\lim_{z \rightarrow z_0} F(z) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} = f'(z_0) = F(z_0)$

we have F is continuous at z_0 .

Similarly G is cont. at w_0 . Hence

$G \circ f$ is continuous at z_0 . (Since f is diff at z_0 , F is continuous at z_0 .)

For $z \in \Omega, z \neq z_0$ we have

$$\frac{(g \circ f)(z) - (g \circ f)(z_0)}{z - z_0} = \frac{g(f(z)) - g(f(z_0))}{z - z_0}$$

using $w_0 = f(z_0)$

$$= \begin{cases} \frac{g(f(z)) - g(w_0)}{f(z) - w_0} \cdot \frac{f(z) - f(z_0)}{z - z_0} & \text{if } f(z) \neq w_0 \\ 0 & \text{if } f(z) = w_0 \end{cases}$$

$$= G(f(z)) F(z)$$

(Note if $f(z) = w_0$ then $F(z) = \frac{w_0 - f(z_0)}{z - z_0} = 0$)

Hence $\lim_{z \rightarrow z_0} \frac{(g \circ f)(z) - (g \circ f)(z_0)}{z - z_0} = \lim_{z \rightarrow z_0} G(f(z)) F(z)$

$$= G(f(z_0)) \cdot F(z_0) \quad (\text{since } G \circ f, F \text{ are cont. at } z_0)$$

$$= G(w_0) F(z_0)$$

$$= g'(w_0) \cdot f'(z_0)$$

$$= g'(f(z_0)) \cdot f'(z_0) \quad \text{as wanted}$$

□

Rmk 2.3 Note if $f: \Omega \rightarrow \mathbb{C}$
 is diff. at $z_0 \in \Omega$ then
 \exists a complex number $c \in \mathbb{C}$ s.t.

$$f(z) = f(z_0) + c(z - z_0) + E(z, z_0)$$

with $E: \Omega \rightarrow \mathbb{C}$ satisfying

$$\lim_{z \rightarrow z_0} \left| \frac{E(z, z_0)}{z - z_0} \right| = 0.$$

Here $c = f'(z_0)$.

Example 2.4 Example 2.1, Prop 2.2

applied repeatedly show that any
 polynomial $p(z) \in \mathbb{C}[x]$ is differentiable

For $p(z) = z^n$ we have

$$p'(z_0) = \lim_{z \rightarrow z_0} \frac{z^n - z_0^n}{z - z_0} = \lim_{z \rightarrow z_0} \frac{(z - z_0)(z^{n-1} + z^{n-2}z_0 + \dots + z_0^{n-1})}{z - z_0}$$

$$= \lim_{z \rightarrow z_0} z^{n-1} + z^{n-2}z_0 + \dots + z_0^{n-1} = n z_0^{n-1}$$

② Important non-example

let $f(z) = \bar{z}$. Then

$$\frac{f(z_0+h) - f(z_0)}{h} = \frac{\overline{z_0+h} - \bar{z}_0}{h} = \frac{1}{5/5}$$

For $h = t, t \in \mathbb{R}$ this limit is 1

For $h = it, t \in \mathbb{R}$ the limit is -1

Hence $\lim_{h \rightarrow 0} \frac{f(z_0+h) - f(z_0)}{h}$ doesn't exist

for any $z_0 \in \mathbb{C}$. And $f(z) = \bar{z}$ is not holomorphic.

Note that $f(z) = \bar{z}$ as a function of from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ is given by

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(x, y) \mapsto (x, -y) \text{ hence it is}$$

a linear function and is differentiable

$$\text{with } J_{F(x_0, y_0)} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Recall A function $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is

differentiable

$$(x, y) \mapsto (u(x, y), v(x, y))$$

at a point $P_0 = (x_0, y_0)$ if \exists linear map

$$J: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ s.t.}$$

$$\lim_{\substack{P \rightarrow P_0 \\ P \neq P_0}} \left(\frac{F(P) - F(P_0) - J(P - P_0)}{\|P - P_0\|} \right) = 0.$$

$P \rightarrow P_0$
 $P \neq P_0$

equivalently

$$F(P) - F(P_0) = J(P_0)(P - P_0) + \psi(P - P_0) |P - P_0|$$

with $|\psi(P - P_0)| \rightarrow 0$ as $P \rightarrow P_0$

The linear map $J: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is unique and called the differential of F at P_0 .

In the standard basis of \mathbb{R}^2 , J is represented by the Jacobian Matrix of F

$$J = J_F(x, y) = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix}$$

Recall We can view \mathbb{C} as a 1-dim'l vector space over \mathbb{C} with basis $\{1\}$ or as a 2-dimensional real v-space with basis $\{1, i\}$.

And a map $T: \mathbb{C} \rightarrow \mathbb{C}$ is \mathbb{C} -linear

$$\text{if } Tz = \lambda z \text{ for some } \lambda \in \mathbb{C}$$

On the other hand $T: \mathbb{C} \rightarrow \mathbb{C}$ is \mathbb{R} -linear

$$\text{if } T(z) = T(x + yi) = T(1)x + T(i)y = \lambda z + \mu \bar{z}$$

$$\text{with } \left. \begin{aligned} \lambda &= \frac{1}{2} (T(1) - i T(i)) \\ \mu &= \frac{1}{2} (T(1) + i T(i)) \end{aligned} \right\}$$

$$\text{Using } \begin{aligned} x &= \frac{z + \bar{z}}{2} \\ y &= \frac{z - \bar{z}}{2i} \end{aligned}$$

$$y = \frac{z - \bar{z}}{2i}$$

Hence every \mathbb{C} -linear map $T: \mathbb{C} \rightarrow \mathbb{C}$ is \mathbb{R} -linear.

But an \mathbb{R} -linear map $T: \mathbb{C} \rightarrow \mathbb{C}$ is \mathbb{C} -linear only if $\mu = 0$ i.e. $T(i) = iT(1)$.

$$\text{If } T(1) = a + bi \quad \text{and} \quad T(i) = c + di \\ T(i) = iT(1) \Rightarrow b = -c \quad \text{and} \quad a = d.$$

If we identify \mathbb{C} with \mathbb{R}^2 with $z = x + iy \leftrightarrow \begin{pmatrix} x \\ y \end{pmatrix}$
 + Since every \mathbb{R} -linear map $\mathbb{R}^2 \rightarrow \mathbb{R}^2$
 is given by a 2×2 real matrix $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \underbrace{\begin{pmatrix} a & b \\ c & d \end{pmatrix}}_A \begin{pmatrix} x \\ y \end{pmatrix}$

Such a map is also \mathbb{C} -linear if A is of the form $A = \begin{pmatrix} a & -c \\ c & a \end{pmatrix}$

Prmk.: Note that in Example $f(z) = \bar{z}$ as a map from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$, it is differentiable with Jacobian equal to $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, which is not a matrix of the above form!

Our next goal is to see how this linear algebra fact about \mathbb{R} -linear versus \mathbb{C} -linear maps is reflected in the case of a complex function $f: \mathbb{C} \rightarrow \mathbb{C}$ and its differentiability.

§ 2.2 Cauchy - Riemann Equations

Holomorphicity vs real differentiability

let $f: \mathbb{C} \rightarrow \mathbb{C}$ be holomorphic at z_0

If $f(x+iy) = u + iv$, we can also view f

as a map from \mathbb{R}^2 to \mathbb{R}^2 ; $\tilde{f}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$(x, y) \mapsto (u(x, y), v(x, y))$$

$$\bullet \quad f'(z_0) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} \text{ exists}$$

independent of how $z \rightarrow z_0$.

In particular we can have z tend to z_0 along the line $z = x + iy_0$ by letting $x \rightarrow x_0$

$$f'(z_0) = \lim_{x \rightarrow x_0} \frac{f(x + iy_0) - f(x_0 + iy_0)}{x - x_0}$$

$$= \lim_{x \rightarrow x_0} \frac{f(x, y_0) - f(x_0, y_0)}{x - x_0}$$

$$= \lim_{x \rightarrow x_0} \frac{u(x, y_0) - u(x_0, y_0)}{x - x_0} + i \lim_{x \rightarrow x_0} \frac{v(x, y_0) - v(x_0, y_0)}{x - x_0}$$

$$= u_x(x_0, y_0) + i v_x(x_0, y_0)$$

Hence we conclude that the usual partial derivatives $u_x(z_0)$, $v_x(z_0)$ and hence the partial derivative $f_x(z_0) = u_x(x_0) + i v_x(x_0)$ exist

and $f'(z_0) = u_x(z_0) + i v_x(z_0) = f_x(z_0)$ (A)

On the other hand approaching $z_0 = x_0 + iy_0$ along $z = x_0 + iy$ with $y \rightarrow y_0$ gives

$$f'(z_0) = \lim_{y \rightarrow y_0} \frac{f(x_0 + iy) - f(x_0 + iy_0)}{i(y - y_0)}$$

$$= \lim_{y \rightarrow y_0} \frac{v(x_0, y) - v(x_0, y_0)}{y - y_0} = i \lim_{y \rightarrow y_0} \frac{u(x_0, y) - u(x_0, y_0)}{y - y_0}$$

$$= v_y(z_0) - i u_y(z_0)$$

We obtain that the partial derivatives $f_y(z_0) = u_y(z_0) + i v_y(z_0)$ also exists and

$$f'(z_0) = v_y(z_0) - i u_y(z_0) = -i f_y(z_0) \tag{B}$$

(A) and (B) gives

$$\begin{cases} u_x(z_0) = v_y(z_0) \\ u_y(z_0) = -v_x(z_0) \end{cases}$$

Cauchy Riemann equations (CR)

If we introduce two differential operators

$$\frac{\partial}{\partial z} := \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right)$$

$$\frac{\partial}{\partial \bar{z}} := \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right)$$