

Problem 1

It is enough to show that τ_1 and τ_2 are homotopic, but

$$H_\theta(x_1, x_2, x_3, \dots, x_{n+1}) = (\cos(\theta)x_1, -\sin(\theta)x_2, \sin(\theta)x_1 + \cos(\theta)x_2, x_3, \dots, x_{n+1})$$

is a continuous map on $[-\frac{\pi}{2}, \frac{\pi}{2}] \times \mathbb{S}^n$

Problem 2

Let X, Y be Hausdorff, locally compact spaces and $f: X \rightarrow Y$ continuous.

Then the extended map $\hat{f}: \hat{X} \rightarrow \hat{Y}$ is continuous if and only if f

is proper ($f^{-1}(\text{compact})$ is compact). Rmk: this proves the exercise because any homeomorphism is proper

Proof: \hat{f} is continuous at every point of $\hat{X} \setminus \{\infty\}$ because f is.

Recall that the open neighbourhoods of ∞ are sets of the form $\{\infty\} \cup (X \setminus K)$, where K is compact in X . Therefore, \hat{f} is continuous at ∞ if and only if $f^{-1}(Y \setminus K) \cup \{\infty\} = Y \setminus f^{-1}(K) \cup \{\infty\}$ is an open neighbourhood of ∞ for any $K \subseteq Y$ compact; i.e. iff f is proper.

So for example, $(0, 1) \subset \mathbb{R}$ does not extend to the compactification.

Problem 3:

The stereographic projection is the map

$$\begin{aligned} \mathbb{S}^n \setminus \{(1, 0, \dots, 0)\} &\subseteq \mathbb{R}^{n+1} \xrightarrow{\pi} \mathbb{R}^n \\ (x_0, \dots, x_n) &\longrightarrow \left(\frac{x_1}{1-x_0}, \dots, \frac{x_n}{1-x_0} \right) \end{aligned}$$

with inverse

$$\pi^{-1}(y_1, \dots, y_n) = \left(\frac{\|y\|^2 - 1}{\|y\|^2 + 1}, \frac{2y_1}{\|y\|^2 + 1}, \dots, \frac{2y_n}{\|y\|^2 + 1} \right)$$

And so it extends to the compactifications

$$\mathbb{S}^n \cong \overline{\mathbb{S}^n \setminus \{(1, 0, \dots, 0)\}} \xrightarrow{\tilde{\pi}} \hat{\mathbb{R}}^n$$

Problem 4:

As suggested by the hint, the map

$$\begin{array}{ccc} \mathbb{S}^{2k-1} \times (-\varepsilon, \varepsilon) & \xrightarrow{\phi} & \mathbb{S}^{2k-1} \\ \cap & & \cap \\ \mathbb{C}^k \times (-\varepsilon, \varepsilon) & & \mathbb{C}^k \end{array}$$

given by $\phi(z, t) = e^{it}z$ is a 1-parameter system of neighbourhoods, and the associated vector field is $X(z) = \left. \frac{d}{dt} \phi(z, t) \right|_{t=0} = i \cdot z$.

In real coordinates, $X(x_1, y_1, \dots, x_k, y_k) = (-y_1, x_1, \dots, -y_k, x_k)$.

Problem 5:

a) Let $g = (-id) \circ f$. Then $g: \mathbb{S}^n \rightarrow \mathbb{S}^n$ satisfies $x + g(x) \neq 0$ for all x . If

$$H(t, x) = \frac{tx + (1-t) \cdot g(x)}{\|tx + (1-t) \cdot g(x)\|}$$

then H is well-defined because $x + g(x) \neq 0$, so $id = H(1, \cdot) \sim H(0, \cdot) = g$

So we have shown that $(-id) \circ f \sim id \Rightarrow f \sim (-id) \Rightarrow \deg(f) = (-1)^{n+1}$

b) Using a) in its contrapositive form,

- $\deg(f) = 0 \neq (-1)^{n+1} \Rightarrow \exists x : f(x) = x$.
- $\deg(-f) = 0 \neq (-1)^{n+1} \Rightarrow \exists y : -f(y) = y$.

Problem 6

generator of $H_1(\mathbb{S}^1)$.

Recall that, for a map $\gamma: (\mathbb{S}^1, 1) \rightarrow (X, x_0)$, $\phi([\gamma]) = \gamma_* \overset{\uparrow}{(1)}$, where $\phi: \pi_1(X, x_0) \rightarrow H_1(X)$ is the Hurewicz homomorphism.

On the other hand, if $p: (Y, y_0) \rightarrow (X, x_0)$ is the universal covering, there is a bijection

$$\pi_1(X, x_0) \xrightarrow{\Psi} p^{-1}(x_0)$$

where $\Psi([\gamma]) = \tilde{\gamma}(1)$, where $\tilde{\gamma}: ([0, 1], 0) \rightarrow (Y, y_0)$ fits into a diagram

$$\begin{array}{ccc} [0, 1] & \xrightarrow{\tilde{\gamma}} & Y \\ \downarrow & & \downarrow p \\ \mathbb{S}^1 & \xrightarrow{\gamma} & X \end{array}$$

In our situation, $(X, x_0) = (\mathbb{S}^1, 1)$ and $(Y, y_0) = (\mathbb{R}, 0)$, with $p(x) = e^{2\pi i x}$, and $\gamma(z) = z^k$.

In this case, $\tilde{\gamma}$ can be explicitly computed:

$$\begin{array}{ccc} [0, 1] & \xrightarrow{zk} & \mathbb{R} \\ \downarrow & & \downarrow e^{2\pi i x} \\ \mathbb{S}^1 & \xrightarrow{z \mapsto z^k} & \mathbb{S}^1 \end{array}$$

and so, $\gamma_*(1) = \tilde{\gamma}(1) = k$, so $\deg(\gamma) = k$.

Alternatively, $z \rightarrow z^k$ is a smooth map, 1 is a regular value and the preimage of 1 has cardinality $|k|$, and that at each p mapping to 1, $\varepsilon_p = \text{sign}(k)$

Problem 7

a) As we proven in another exercise, there is a commutative diagram

$$\begin{array}{ccc} H_{n+1}(\Sigma \mathbb{S}^n) & \xrightarrow{\phi} & H_n(\mathbb{S}^n) \\ \downarrow \Sigma f_* & & \downarrow f_* \\ H_{n+1}(\Sigma \mathbb{S}^n) & \xrightarrow{\phi} & H_n(\mathbb{S}^n) \end{array}$$

if x is a generator of $H_n(\mathbb{S}^n)$, $\phi^{-1}(x)$ is a generator of $H_{n+1}(\Sigma\mathbb{S}^n)$, and

$$\Sigma f_* (\phi^{-1}(x)) = \phi^{-1} \circ f_* \circ \phi (\phi^{-1}(x)) = \deg(f) \cdot \phi^{-1}(x)$$

and so Σf_* is "multiplication by $\deg(f)$ ".

b) It follows from part a) and Problem 6.

Problem 8

For $n=1$, let $\gamma: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ be the identity path and let σ be the concatenation of γ and γ^{-1} . As discussed in Problem 6,

$$\sigma_*(1) = \phi([\gamma \circ \gamma^{-1}]) = \phi([\gamma]) - \phi([\gamma]) = 0$$

so σ has degree 0.

Alternatively, one can directly define

$$H_t: [0,1] \rightarrow [0,1]$$

$$s \mapsto \begin{cases} 2st & \text{if } s \leq \frac{1}{2} \\ t(2-2s) & \text{if } s \geq \frac{1}{2} \end{cases}$$

and H_t descends to a homotopy between $H_0: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ (the constant map) and

$H_1: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ (a surjective map), so $\deg(H_1) = 0$.

For higher n just use Problem 7, a) and that, if $f: X \rightarrow Y$ is surjective, so is $\Sigma f: \Sigma X \rightarrow \Sigma Y$.

Problem 9

$GL(n, \mathbb{C})$ is connected: Given $A \in GL(n, \mathbb{C})$, let $z \in \mathbb{C}^*$ be such that the line $\mathbb{R} \cdot z$ does not contain any of the eigenvalues of A . Then

$$\gamma(t) = t \cdot I + (1-t) \cdot z^{-1} \cdot A, \quad t \in [0,1]$$

is a path contained in $GL(n, \mathbb{C})$ because for $t < 1$,

$$\det(\gamma(t)) = \left(\frac{1-t}{z}\right)^n \cdot \det\left(A + z \frac{t}{1-t} I\right)$$

which is non-zero because $z \frac{t}{1-t}$ is not an eigenvalue of A .

$SO(n)$ is connected: $SO(2)$ is homeomorphic to \mathbb{S}^1 . Then argue by induction. If x is any point on the sphere and $\gamma: [0, 1] \rightarrow \mathbb{S}^{n-1}$ is a path between $(1, 0, \dots, 0)$ and x , the Gram-Schmidt algorithm allows one to obtain a path $\tilde{\gamma}: [0, 1] \rightarrow SO(n)$ with $\tilde{\gamma}(0) = \text{Id}$ and $\tilde{\gamma}(t)(1, 0, \dots, 0) = \gamma(t)$. Therefore, we can connect any matrix in $SO(n)$ to one where the first column is $(1, 0, \dots, 0)^t$, but this forces the first row to be $(1, 0, \dots, 0)$ and so the matrix has the form $\left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & A \end{array} \right)$, with $A \in SO(n-1)$, and we can use induction to reach the identity.

$GL(n, \mathbb{R})^+$ is connected: for $n=1$ this is clear. If $n > 1$, any point in $\mathbb{R}^n \setminus \{0\}$ can be connected by a path to $(1, 0, \dots, 0)$. Therefore, there is a path in $GL(n, \mathbb{R})^+$ connecting any matrix to one of the form $\left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & B \end{array} \right)$, where now $B \in GL(n-1, \mathbb{R})^+$. Doing the same construction for B and so on, we see that there is a path in $GL(n, \mathbb{R})^+$ between any matrix and one of the form $\left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & I_1 \end{array} \right)$, but $\{A \in GL(n, \mathbb{R})^+ : A = \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & I_1 \end{array} \right)\}$ is homeomorphic to $\mathbb{R}^{\frac{n(n-1)}{2}}$, which is connected.