Reminder:

Consider a ring extension $A \subset B$.

Definition 1.1.1:

- (a) An element $b \in B$ is called *integral over* A if there exists a monic $f \in A[X]$ with f(b) = 0.
- (b) The ring B is called *integral over* A if every $b \in B$ is integral over A.
- (c) The integral closure of A in B is the set $\tilde{A} := \{b \in B \mid b \text{ integral over } A\}$.

Proposition 1.1.4:

- (b) The subset \tilde{A} is a subring of B that contains A.
- (c) The subring \tilde{A} is its own integral closure in B.

Normalization 1.3

From now on we assume that A is an integral domain with quotient field K.

Definition 1.3.1: (a) The integral closure of A in K is called the *normalization of A*.

(b) The ring A is called *normal* if this normalization is A.

Proposition 1.3.2: (a) The normalization of A is normal.



1.4 Localization

Definition 1.4.1: A subset $S \subset A \setminus \{0\}$ is called *multiplicative* if it contains 1 and is closed under multiplication.

Definition-Proposition 1.4.2: For any multiplicative subset $S \subset A$ the subset

$$S^{-1}A := \left\{ \frac{a}{s} \mid a \in A, \ s \in S \right\}$$

is a subring of K that contains A and is called the *localization of* A with respect to S.

$$P_{\underline{n}\underline{f}} = \frac{\pi}{1} \in S^{2}A, \quad 1 = \frac{1}{1} \in S^{2}A, \quad \frac{\pi}{5} : \frac{\pi}{$$

Example 1.4.3: For every prime ideal $\mathfrak{p} \subset A$ the subset $A \setminus \mathfrak{p}$ is multiplicative. The ring $A_{\mathfrak{p}} := (A \setminus \mathfrak{p})^{-1}A$ is called the *localization of A at* \mathfrak{p} .

Proposition 1.4.4: For every multiplicative subset $S \subset A$ we have: (a) $S^{-1}\widetilde{A} = \widetilde{S^{-1}A}$

(b) If A is normal, then so is
$$S^{-1}A$$
.
[M_{1} (b) If A is normal, then so is $S^{-1}A$.
[M_{2} (c) $H = 0$ $H = 0$ $H = 0$
 $H = 0$ $H = 0$ $H = 0$
 $H = 0$ $H = 0$ $H = 0$
 $H = 0$ $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$ $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 $H = 0$
 H

$$Tdu \quad \varepsilon \in \left[\vec{S}^{T} \vec{A} \right]^{n}, \quad vik \quad \varepsilon^{T} + u_{1} c^{-1} + \dots = 0 \quad vik \quad u_{i} \in \vec{S}^{T} \vec{A}.$$

$$Uin \quad u_{i} = \frac{\pi i}{S} \quad vik \quad \alpha_{i} \in A, \quad s \in S.$$

$$\exists \quad \left[S \in \vec{J}^{T} + \quad S \quad u_{1} \left[S \in \vec{J}^{T-1} + \dots + \vec{S}^{T} \quad u_{n} = 0 \right] \\ \exists \quad \left[S \in \vec{J}^{T} + \quad \alpha_{1} \left[S \in \vec{J}^{T-1} + \dots + \vec{S}^{T-1} \quad \alpha_{n} = 0 \right] \\ \exists \quad S \in \vec{C} \quad \vec{A} \quad \exists \quad \varepsilon = \frac{S c}{S} \in \vec{S}^{T} \quad \vec{A}.$$

1.5 Field extensions

In the following we consider a normal integral domain A with quotient field K, and an algebraic field extension L/K, and let B be the integral closure of A in L.

Proposition 1.5.1: For any homomorphism $\sigma: L \to M$ of field extensions of K, an element $x \in L$ is integral over A if and only if $\sigma(x)$ is integral over A.





Proposition 1.5.3: We have $(A \setminus \{0\})^{-1}B = L$.

 $\frac{\operatorname{Pm}_{i}}{\operatorname{Wie}} \quad \forall y \in L \quad \operatorname{chine} \ X_{1,\dots,7} \quad X_{n} \in K \quad \operatorname{with} \quad y^{n} + X_{1} \quad y^{n-1} + x_{n} = 0.$ $\operatorname{Wie} \quad \operatorname{cah} \quad X_{i} = \frac{\pi_{i}}{5} \quad \operatorname{wik} \quad \alpha_{i} \in A, \quad S \in A \setminus \{0\}.$ $= \int_{0}^{\infty} \left(\sum_{i=1}^{n} \int_{0}^{\infty} \left(\sum_{i=1}^{n$

 $\Rightarrow (5\gamma)^{n} + 5x_{1}(5\gamma)^{n-1} + 5x_{n} = 0$ $\Rightarrow 5\gamma \in B \Rightarrow \gamma = \frac{5\gamma}{5} \in [A \cdot \{0\}]^{n} B. \qquad \frac{5\gamma}{4} = 0$

1.6 Norm and Trace

Assume that L/K is finite separable. Let \overline{K} be an algebraic closure of K.

Definition 1.6.1: For any $x \in L$ we consider the K-linear map $T_x: L \to L, u \mapsto ux$.

- (a) The norm of x for L/K is the element $\operatorname{Nm}_{L/K}(x) := \det(T_x) \in K$.
- (b) The trace of x for L/K is the element $\operatorname{Tr}_{L/K}(x) := \operatorname{tr}(T_x) \in K$.

Proposition 1.6.2: (a) For any $x, y \in L$ we have $\operatorname{Nm}_{L/K}(xy) = \operatorname{Nm}_{L/K}(x) \cdot \operatorname{Nm}_{L/K}(y)$. (b) The map $\operatorname{Nm}_{L/K}$ induces a homomorphism $L^{\times} \to K^{\times}$.

(c) The map $\operatorname{Tr}_{L/K}: L \to K$ is K-linear. $\operatorname{I'}_{\underline{x_{\gamma}}}: (A) \quad T_{\underline{x_{\gamma}}} = T_{\underline{x}} \circ T_{\underline{y}} \implies det(T_{\underline{x_{\gamma}}}) = det(T_{\underline{x}}). det(T_{\underline{y}}).$ (b) $\underline{x} \neq 0 \implies T_{\underline{x}}$ Size time $\implies det(T_{\underline{x}}) \neq 0.$ (c) $T_{\underline{x} \neq \underline{y}} = T_{\underline{x}} + T_{\underline{y}} \implies der(T_{\underline{x} \neq \underline{y}}) = der(T_{\underline{x}}) + der(T_{\underline{y}})$ $\forall a \in K: T_{a\underline{x}} = a \cdot T_{\underline{x}} \implies der(T_{a\underline{x}}) = a. de(T_{\underline{x}}).$ **Proposition 1.6.3:** For any $x \in L$ we have

$$\operatorname{Nm}_{L/K}(x) = \prod_{\sigma \in \operatorname{Hom}_{K}(L,\overline{K})} \sigma(x) \quad \text{and} \quad \operatorname{Tr}_{L/K}(x) = \sum_{\sigma \in \operatorname{Hom}_{K}(L,\overline{K})} \sigma(x).$$

$$f_{\operatorname{Inf}} : \quad \operatorname{Viz} \quad \mathsf{K}' := \mathsf{K}(\mathsf{k}) = \operatorname{vin}_{*} \operatorname{fe} \quad \mathsf{r}(\mathsf{X}) = \prod_{\sigma \in \operatorname{Hom}_{K}(K,\overline{K})} (\mathsf{X} - \mathfrak{c}(\mathsf{k}))$$

$$[\sqcup_{/\mathsf{K}'}] = d = \operatorname{Juv}_{*} \operatorname{fe}. \quad \mathsf{g} \; \mathsf{T}_{\mathsf{X}} \quad \mathsf{i} \quad \prod_{\sigma \in \operatorname{Hom}_{K}(K',\overline{K})} (\mathsf{X} - \mathfrak{c}(\mathsf{k})) \stackrel{d}{=} \prod_{\sigma \in \operatorname{Hom}_{K}(L,\overline{K})} \mathsf{fe} \quad \mathsf{fe} \quad$$

•

Proposition 1.6.5: For any two finite separable field extensions M/L/K we have:

(a)
$$\operatorname{Nm}_{L/K} \circ \operatorname{Nm}_{M/L} = \operatorname{Nm}_{M/K}$$
.
(b) $\operatorname{Tr}_{L/K} \circ \operatorname{Tr}_{M/L} = \operatorname{Tr}_{M/K}$.
 $\operatorname{Tr}_{L/K} \circ \operatorname{Tr}_{M/L} = \operatorname{Tr}_{M/K}$.
 $\operatorname{Tr}_{L/K} \circ \operatorname{Tr}_{M/L} = \operatorname{Tr}_{M/K}$.
 $\operatorname{Tr}_{K} \circ \operatorname{Tr}_{M/L} = \operatorname{Tr}_{M/K}$.
 $\operatorname{Tr}_{K} \circ \operatorname{Tr}_{K} \circ \operatorname{Tr}_$

_

Discriminant 1.7

Proposition 1.7.1: The map

$$L \times L \longrightarrow K, \quad (x, y) \mapsto \operatorname{Tr}_{L/K} \bigotimes \langle \times \gamma \rangle.$$

is a non-degenerate symmetric K-bilinear form.

$$\underbrace{I_{K}}_{i} = 1.6.4 = \exists x \in L, T_{L/K}(x) \neq 0 := i \Rightarrow f(x, 1) i \Rightarrow \dots a.$$

$$\underbrace{I_{K}}_{i} = \underbrace{I_{K}}_{i} = \underbrace{I$$

Definition 1.7.3: The *discriminant* of any ordered basis (b_1, \ldots, b_n) of L over K is the determinant of det (T) ER. the associated Gram matrix

$$\operatorname{disc}(b_1,\ldots,b_n) := \operatorname{det}\left(\operatorname{Tr}_{L/K}(b_i b_j)\right)_{i,j=1,\ldots,n} = \operatorname{det}(T)^2 \in K.$$

Proposition 1.7.4: If L = K(b) and n = [L/K], then $disc(1, b, ..., b^{n-1})$ is the discriminant of the minimal polynomial of b over K.

Proposition 1.7.5: (a) We have $\operatorname{disc}(b_1, \ldots, b_n) \in K^{\times}$.

(b) If
$$b_1, \ldots, b_n \in B$$
, then $\operatorname{disc}(b_1, \ldots, b_n) \in A \setminus \{0\}$ and

$$\begin{bmatrix} C & 1 \\ \overline{\operatorname{disc}(b_1, \ldots, b_n)} \cdot (Ab_1 + \ldots + Ab_n). \end{bmatrix}$$

$$P_{--f} : [A] \quad \begin{bmatrix} T_{-} \bigcup_{l \in \mathbb{Z}} (b_i \cdot b_j) \end{bmatrix}_{i,j} \quad i_i \text{ instable}, \text{ because } T_{-} \bigcup_{k \in \mathbb{Z}} A = Ai_k \in [\dots A_{k^-}] \quad i_k = A_{i_k} = A_{i_k} = [\dots A_{k^-}] \quad i_k = A_{i_k} = A_{i_k$$

$$= \underbrace{\chi_{i}}_{X_{i}} = \underbrace{\left(\sum_{x_{i}}^{n} \right)}_{X_{i}} = \underbrace{\left(\sum_{x_$$