

Chapter 2:

random variables

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Outline

- 1) Measurable functions
- 2) Product σ -fields and families of functions
- 3) Independent random variables
- 4) Real-valued random variables
- 5) Integration
- 6) Classical laws
- 7) Integration and independence

1) Measurable functions

Definition Let (E, \mathcal{E}) and (F, \mathcal{F}) be measurable spaces. A function $f: (E, \mathcal{E}) \rightarrow (F, \mathcal{F})$ is measurable if $\forall B \in \mathcal{F}, f^{-1}(B) \in \mathcal{E}$.

Remarks: • Since $(f \circ g)^{-1}(B) = g^{-1}(f^{-1}(B))$, a composition of measurable functions is measurable
• If \mathcal{E}' is a σ -field with $\mathcal{E} \subset \mathcal{E}'$, if $g: (E, \mathcal{E}) \rightarrow (F, \mathcal{F})$ is measurable, then $g: (E, \mathcal{E}') \rightarrow (F, \mathcal{F})$ is measurable

Criterion To check that $f: (E, \mathcal{E}) \rightarrow (F, \mathcal{F})$ is measurable, one often finds a class $\mathcal{B} \subset \mathcal{F}$ such that $\mathcal{F} = \sigma(\mathcal{B})$ and $\forall B \in \mathcal{B}, f^{-1}(B) \in \mathcal{E}$.

Indeed, $\{B \in \mathcal{F} : f^{-1}(B) \in \mathcal{E}\}$ is then a σ -field (exercise) containing \mathcal{B} and thus containing $\sigma(\mathcal{B}) = \mathcal{F}$.

Interpretation in probability. A measurable function $X: (\Omega, \mathcal{A}) \rightarrow (F, \mathcal{F})$ is called a random variable (r.v. in short). Intuitively, this means that $X(\omega)$ is "observable" in the sense one can "observe" whether $X(\omega) \in B$ with $B \in \mathcal{F}$ or not.

Definition Let $f: (E, \mathcal{E}) \rightarrow (F, \mathcal{F})$ be a measurable function and let μ be a measure on (E, \mathcal{E}) . Then, $\forall B \in \mathcal{F}$, $\mu_f(B) = \mu(f^{-1}(B))$ defines a measure on (F, \mathcal{F}) , called the image measure of f by μ .

In probability, if $X: (\Omega, \mathcal{E}) \rightarrow (F, \mathcal{F})$ is a random variable and \mathbb{P} a probability measure on (Ω, \mathcal{E}) , then \mathbb{P}_X , the image measure of \mathbb{P} by X is called the law of X .

By definition, $\forall B \in \mathcal{F}$,

$$\mathbb{P}_X(B) = \mathbb{P}(X^{-1}(B)) = \mathbb{P}(\{\omega \in \Omega; X(\omega) \in B\}) = \mathbb{P}(X \in B)$$

probabilistic notation (avoiding writing " ω ")

Side remark If (E, \mathcal{E}, μ) is a probability space, there exists a random variable with law μ : just take $(\Omega, \mathcal{F}, \mathbb{P}) = (E, \mathcal{E}, \mu)$ and $X: \Omega \rightarrow E$ the identity.
 $x \mapsto x$

END OF LECTURE 4

How can one characterize a probability measure? In other words, is there a "simple" way to check if $\mathbb{P}_X = \mathbb{P}_Y$? (i.e. $\mathbb{P}_X(A) = \mathbb{P}_Y(A) \forall A \in \mathcal{F}$)

If X takes its values in a countable space $(E, \mathcal{P}(E))$, then its law is characterized by the values $\mathbb{P}_X(\{x\}) = \mathbb{P}_X(x) = \mathbb{P}(X=x)$ for $x \in E$, since for $A \subseteq E$, $\mathbb{P}_X(A) = \sum_{x \in A} \mathbb{P}_X(x)$

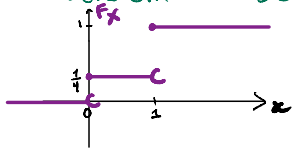
In particular, $\mathbb{P}(X=x) = \mathbb{P}(Y=x) \forall x \in E \Rightarrow \mathbb{P}_X = \mathbb{P}_Y$.

When E is uncountable, this is not true anymore and things can be very complicated!

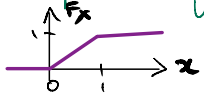
In the case of \mathbb{R} , cumulative distribution functions are useful:

Definition The cumulative distribution function (cdf) of a real-valued r.v. X is the function $F_X: \mathbb{R} \rightarrow [0, 1]$ defined by $F_X(x) = \mathbb{P}(X \leq x) = \mathbb{P}_X((-\infty, x])$ for $x \in \mathbb{R}$.

Example (Bernoulli random variable) If $P(X=0) = \frac{1}{4}$ and $P(X=1) = \frac{3}{4}$,



Example (Uniform distribution) If the law of X is the Lebesgue measure on $[0, 1]$:



(X is said to follow the uniform distribution on $[0, 1]$)

Proposition

- ① Let X be a \mathbb{R} -valued r.v. F_X is non-decreasing, $\lim_{x \rightarrow -\infty} F_X = 0$, $\lim_{x \rightarrow +\infty} F_X = 1$, F_X is right-continuous
- ② If X, Y are two \mathbb{R} -valued r.v. $F_X = F_Y \Leftrightarrow P_X = P_Y$ (cdf's characterize laws)
- ③ [Lebesgue-Stieltjes] If a function $F: \mathbb{R} \rightarrow [0, 1]$ satisfies the condition in ①, then there exists real-valued r.v. with $F = F_X$.

Proof: ①. Since $]-\infty, x] \subset]-\infty, y]$ for $x \leq y$, we get $F_X(x) = P_X(]-\infty, x]) \leq P_X(]-\infty, y]) = F_X(y)$, so F_X is non-decreasing.

• Since $\bigcap_{k=1}^{\infty}]-\infty, -k] =]-\infty, -\infty]$ is decreasing in n , we get $F_X(-\infty) \rightarrow P_X(\bigcap_{k=1}^{\infty}]-\infty, -k]) = P_X(\emptyset) = 0$

Similarly, $\bigcup_{k=1}^{\infty}]-\infty, k] =]-\infty, \infty]$ is increasing in n , so $F_X(\infty) \rightarrow P_X(\bigcup_{k=1}^{\infty}]-\infty, k]) = P_X(\mathbb{R}) = 1$.

• Take $x \in \mathbb{R}$. Since $\bigcap_{k=1}^{\infty}]-\infty, x + \frac{1}{k}]$ is decreasing in n , we get $F_X(x + \frac{1}{n}) \rightarrow P_X(\bigcap_{k=1}^{\infty}]-\infty, x + \frac{1}{k}]) = P_X(]-\infty, x]) = F_X(x)$

② • If $P_X = P_Y$, then $\forall x \in \mathbb{R}$, $P_X(]-\infty, x]) = P_Y(]-\infty, x])$

• If $F_X = F_Y$, then the probability measures P_X and P_Y coincide on $\mathcal{G} = \{]-\infty, x], x \in \mathbb{R} \}$, which is a generating π -system of $\mathcal{B}(\mathbb{R})$

By the result of lecture 3, we conclude that $P_X = P_Y$.

③ Take $\Omega =]0, 1[$, $\mathcal{A} = \mathcal{B}(]0, 1[)$, λ Lebesgue measure on $]0, 1[$. For $w \in]0, 1[$ set $X(w) = \inf \{ t \in \mathbb{R} : F(t) \geq w \}$ (called the right-continuous inverse of F). One checks that X is measurable and that $X(w) \leq x \Leftrightarrow w \leq F(x)$ for $w \in \Omega$ and $x \in \mathbb{R}$. Thus $P(X \leq x) = P(\{w \in \Omega : w \leq F(x)\}) = F(x)$.

∞

Notation If (F, \mathcal{M}) is a measurable space, E a set and $f: E \rightarrow F$ a function, we define $\sigma(f) = \{ f^{-1}(B) : B \in \mathcal{M} \}$ is a σ -field on E called the σ -field generated by f .

More generally, if $(f_i)_{i \in I}$ is a collection of functions with $f_i: E \rightarrow F_i$ and (F_i, \mathcal{A}_i) measurable space we define $\sigma(f_i, i \in I) = \sigma(\{ f_i^{-1}(B_i) : i \in I, B_i \in \mathcal{A}_i \})$, called the σ -field generated by $(f_i)_{i \in I}$.

Remark In general, $\sigma(f_i, i \in I) \neq \bigcap_{i \in I} \sigma(f_i)$: We have $\sigma(f_i, i \in I) = \sigma(\bigcup_{i \in I} \sigma(f_i))$ (see exercise sheet)

Example: If $f: \mathbb{R} \rightarrow \mathbb{R}$, $x \mapsto x^2$, then $\sigma(f) = \{ A \in \mathcal{B}(\mathbb{R}) : A = -A \}$

Interpretation in probability

- $\sigma(X)$ represents the "information" / "observable sets" one has access to by looking at the values of X .
- Similarly, if $(X_i)_{i \in I}$ are r.v., $\sigma(X_i, i \in I)$ represents the "information" given by $(X_i)_{i \in I}$

Proposition ① Let $f: E \rightarrow (F, \mathcal{A})$ be a function. Then $\sigma(f)$ is the smallest σ -field on E for which f is measurable.
 ② Let $f_i: E \rightarrow (F_i, \mathcal{A}_i)$ for $i \in I$ be functions. Then $\sigma(f_i, i \in I)$ is the smallest σ -field on E for which $\forall i \in I$ f_i is measurable.

Proof ①. First $f: (E, \sigma(f)) \rightarrow (F, \mathcal{A})$ is measurable by definition of $\sigma(f)$

• If $\mathcal{B}: (E, \mathcal{E}) \rightarrow (F, \mathcal{A})$ we show that $\sigma(f) \subseteq \mathcal{E}$. To this end, by measurability of f , $\forall B \in \mathcal{A}$, $f^{-1}(B) \in \sigma(f)$, so $\sigma(f) \subseteq \mathcal{E}$ by definition of $\sigma(f)$

② The proof is similar. First, $\forall i \in I$ $f_i: (E, \sigma(f_i, i \in I)) \rightarrow (F_i, \mathcal{A}_i)$ is measurable because for every $B_i \in \mathcal{A}_i$, $f_i^{-1}(B_i) \in \sigma(f_i, i \in I)$ by definition of $\sigma(f_i, i \in I)$

• If $f_i: (E, \mathcal{E}) \rightarrow (F_i, \mathcal{A}_i)$ is measurable $\forall i \in I$ we show that $\sigma(f_i, i \in I) \subseteq \mathcal{E}$. To this end, by measurability of f_i $\forall B_i \in \mathcal{A}_i$: $f_i^{-1}(B_i) \in \mathcal{E}$. Thus \mathcal{E} contains all sets of the form $f_i^{-1}(B_i)$ with $i \in I, B_i \in \mathcal{A}_i$, so it also contains the σ -field they generate, which is precisely $\sigma(f_i, i \in I)$.

If E is a metric space, recall that $\mathcal{B}(E)$ is the Borel σ -algebra, generated by all open sets of E .

Proposition Let E, F be metric spaces and $f: (E, \mathcal{B}(E)) \rightarrow (F, \mathcal{B}(F))$ continuous. Then f is measurable.

Proof: $\forall O \in \mathcal{B}(F)$, if O is open, $f^{-1}(O)$ is open, hence is in $\mathcal{B}(E)$. Since $\mathcal{B}(F) = \sigma(\text{open sets of } F)$, this shows that $f^{-1}(B) \in \mathcal{B}(E)$ for every $B \in \mathcal{B}(F)$.

2) Product σ -fields and families of functions

Product σ -fields are needed when considering pairs, or more generally families, of random variables

Definition (product σ -field) Let $(E_i, \mathcal{E}_i)_{i \in I}$ be measurable spaces. Set $E = \prod_{i \in I} E_i$ and for $i \in I$, let $\pi_i: E \rightarrow E_i$ be the canonical projections.

We let $\bigotimes_{i \in I} \mathcal{E}_i := \sigma(\pi_i, i \in I) = \sigma(\prod_i (B_i) : B_i \in \mathcal{E}_i \text{ for } i \in I)$ be the smallest σ -field on E such that all the projections are measurable. It is called the product σ -field or cylinder σ -field.

Definition (cylinder sets) Sets of the form

$$\pi_{i_1}^{-1}(A_1) \cap \dots \cap \pi_{i_n}^{-1}(A_n)$$

with $i_1, \dots, i_n \in I$, $A_1 \in \mathcal{E}_{i_1}, \dots, A_n \in \mathcal{E}_{i_n}$

are called cylinder sets (they form a generating π -system of the product σ -field)

Examples. In $\mathcal{B}^{[0,1]} = \{f: [0,1] \rightarrow \mathbb{R}\}$, the set

$$\{f: [0,1] \rightarrow \mathbb{R}, -1 < f(\frac{1}{2}) < 1 \text{ and } f(1) > \sqrt{2}\}$$

$$= \pi_{\frac{1}{2}}^{-1}(\text{]}-1, 1[) \cap \pi_1^{-1}(\text{]} \sqrt{2}, \infty[) \text{ is a cylinder set}$$

If $I = \{1, 2, \dots\}$, $E_i = \mathbb{R}$, the product σ -field on $\prod_{i \in I} E_i = \mathbb{R}^{\mathbb{N}}$ is the cylinder σ -field seen in lecture 2

Proposition If $\#I = n$, $\left(\bigotimes_{i=1}^n \mathcal{E}_i = \sigma(A_1 \times \dots \times A_n : A_i \in \mathcal{E}_i \text{ for } 1 \leq i \leq n)\right)$

Proof: Set $\mathcal{E} = \sigma(A_1 \times \dots \times A_n : A_i \in \mathcal{E}_i \text{ for } 1 \leq i \leq n)$

• $\Pi_i : (E, \mathcal{E}) \rightarrow \mathcal{E}_i$ is measurable because

$$\Pi_i^{-1}(B_i) = E_1 \times \dots \times E_{i-1} \times B_i \times E_{i+1} \times \dots \times E_n \in \mathcal{E}$$

• if Π_i is measurable $\forall i$, then $A_1 \times \dots \times A_n = \Pi_1^{-1}(A_1) \cap \dots \cap \Pi_n^{-1}(A_n)$

Hence \mathcal{E} is the smallest σ -algebra s.t. $\forall i, \Pi_i$ is measurable

END OF LECTURE 5

WARNING: It is not true in general that $\bigotimes_{i \in I} \mathcal{E}_i = \sigma(\prod_{i \in I} A_i : A_i \in \mathcal{E}_i)$ (it is true when I is countable, but not in general)

Remark If \mathcal{B}_i is a generating π -system of \mathcal{E}_i , then

$\{A_1 \times \dots \times A_n : A_i \in \mathcal{B}_i\}$ is a generating π -system of $\mathcal{E}_1 \otimes \dots \otimes \mathcal{E}_n$

Definition • If \mathbb{P}_i is a probability measure on (E_i, \mathcal{E}_i) , the product probability measure $\bigotimes_{i \in I} \mathbb{P}_i$ is the unique probability measure on $(\prod_{i \in I} E_i, \bigotimes_{i \in I} \mathcal{E}_i)$ such that $\bigotimes_{i \in I} \mathbb{P}_i(\prod_{i \in I} \Pi_i^{-1}(A_i)) = \prod_{i \in I} \mathbb{P}_i(A_i)$ for all cylinder sets.

• When $\#I = n$, $\mathbb{P}_1 \otimes \dots \otimes \mathbb{P}_n$ is the unique probability measure on $(E_1 \times \dots \times E_n, \mathcal{E}_1 \otimes \dots \otimes \mathcal{E}_n)$

such that $\mathbb{P}_1 \otimes \dots \otimes \mathbb{P}_n(A_1 \times \dots \times A_n) = \mathbb{P}_1(A_1) \mathbb{P}_2(A_2) \dots \mathbb{P}_n(A_n)$ for $A_i \in \mathcal{E}_i$.

(Uniqueness comes from the fact that 2 probability measures that coincide on a generating π -system are equal
existence is admitted: it involves additional tools from measure theory)

The definition extends to σ -finite measures such as the Lebesgue measure (μ is σ -finite on E if one can write $E = \bigcup_{n \geq 1} E_n$ with $\mu(E_n) < \infty$).

Example The Lebesgue measure on \mathbb{R}^n is the product $\lambda \otimes \dots \otimes \lambda$ with λ the Lebesgue measure on \mathbb{R} .

Remark When one considers a family of random variables, their law is a probability measure on a product space. For example, $\mathbb{P}(XY \leq 1) = \mathbb{P}_{(X,Y)}(\{(x,y) \in \mathbb{R}^2 : xy \leq 1\}) = \mathbb{P}_{XY}([-\infty, 1])$.

More generally, if (X_1, \dots, X_n) is a random variable with values in (E_1, \dots, E_n) its law $\mathbb{P}_{(X_1, \dots, X_n)}$ is characterized by $\mathbb{P}_{(X_1, \dots, X_n)}(A_1 \times \dots \times A_n) = \mathbb{P}((X_1, \dots, X_n) \in A_1 \times \dots \times A_n)$

$$= \mathbb{P}(X_1 \in A_1, \dots, X_n \in A_n) \quad (6)$$

Proposition ① Let $(E_i, \mathcal{E}_i)_{i \in I}$ be a family of measurable spaces.

A function $f: (E, \mathcal{E}) \rightarrow (\prod_{i \in I} E_i, \otimes_{i \in I} \mathcal{E}_i)$ is measurable iff $\forall i \in I$ $\pi_i \circ f$ is measurable (i.e. writing $f = (f_i)_{i \in I}$ f is measurable iff $\forall i \in I$; f_i is measurable)

② If $f, g: (R, \mathcal{B}(R)) \rightarrow (R, \mathcal{B}(R))$ are measurable, $f+g, f \times g, \min(f, g), \max(f, g)$ are measurable

Then, if $(X_i)_{i \in I}$ is a collection of random variables, one may view $(X_i)_{i \in I}$ as ONE random variable

Proof: ① \Rightarrow If f is measurable, $\forall i \in I$ $\pi_i \circ f$ is a composition of measurable functions, so it is measurable.

\Leftarrow Since $\otimes_{i \in I} \mathcal{E}_i = \sigma(\pi_i^{-1}(B_i) : B_i \in \mathcal{E}_i, i \in I)$, it suffices to check that $f^{-1}(\pi_i^{-1}(B_i)) \in \mathcal{E}$ for every $i \in I$ and $B_i \in \mathcal{E}_i$.

But $f^{-1}(\pi_i^{-1}(B_i)) = (\pi_i \circ f)^{-1}(B_i) \in \mathcal{E}_i$ because $\pi_i \circ f$ is measurable

② By ①, $(R, \mathcal{B}(R)) \rightarrow (R^2, \mathcal{B}(R) \otimes \mathcal{B}(R))$ is measurable.
 $x \mapsto (f(x), g(x))$

But $(R^2, \mathcal{B}(R^2)) \rightarrow R$ is continuous, hence measurable
 $(u, v) \mapsto u+v$

Since $\mathcal{B}(R^2) = \mathcal{B}(R) \otimes \mathcal{B}(R)$ (see exercise sheet), we conclude by composition that $f+g$ is measurable. The reasoning is the same for the other functions

3) Independent random variables

For a function $X: \Omega \rightarrow (E, \mathcal{E})$ recall that $\sigma(X) = \{X^{-1}(A) : A \in \mathcal{E}\}$

Definition (II of a finite number of random variables)

Random variables X_1, \dots, X_n are independent (notation: \perp) if the σ -fields $\sigma(X_1), \dots, \sigma(X_n)$ are independent.

Remark By the definition of independence, if $X_i: (\Omega, \mathcal{F}) \rightarrow (E_i, \mathcal{E}_i)$ are random variables, X_1, \dots, X_n are $\perp \Leftrightarrow \forall A_i \in \mathcal{E}_1, \dots, A_n \in \mathcal{E}_n, \mathbb{P}(X_1^{-1}(A_1) \cap \dots \cap X_n^{-1}(A_n)) = \mathbb{P}(X_1^{-1}(A_1)) \dots \mathbb{P}(X_n^{-1}(A_n))$
 $\Leftrightarrow \forall A_i \in \mathcal{E}_1, \dots, A_n \in \mathcal{E}_n \mathbb{P}(X_1 \in A_1, \dots, X_n \in A_n) = \mathbb{P}(X_1 \in A_1) \dots \mathbb{P}(X_n \in A_n)$
 $\Leftrightarrow \forall A_i \in \mathcal{E}_1, \dots, A_n \in \mathcal{E}_n \mathbb{P}_{(X_1, \dots, X_n)}(A_1 \times \dots \times A_n) = \mathbb{P}_{X_1}(A_1) \dots \mathbb{P}_{X_n}(A_n)$
 $\Leftrightarrow \mathbb{P}_{(X_1, \dots, X_n)} = \mathbb{P}_{X_1} \otimes \dots \otimes \mathbb{P}_{X_n}$ (*)

The last \Leftrightarrow comes from the fact that two probability measures are equal iff they are equal on a generating π -system.

Remark To show that X_1, \dots, X_n are \perp one very often shows that

$$\mathbb{P}(X_1 \in A_1, \dots, X_n \in A_n) = \mathbb{P}(X_1 \in A_1) \dots \mathbb{P}(X_n \in A_n) \quad (**)$$

for every $A_i \in \mathcal{B}_i, \dots, A_n \in \mathcal{B}_n$ with \mathcal{B}_i a generating π -system of \mathcal{E}_i with $\Omega \in \mathcal{B}_i$ (thanks to the property seen at the end of Chapter 1)

Proposition

(1) If X_1, \dots, X_n are \mathbb{Z} -valued r.v., they are \perp iff $\forall i_1, \dots, i_n \in \mathbb{Z}, \mathbb{P}(X_1 = i_1, \dots, X_n = i_n) = \mathbb{P}(X_1 = i_1) \dots \mathbb{P}(X_n = i_n)$

(2) If X_1, \dots, X_n are \mathbb{R} -valued r.v., they are \perp iff $\forall x_1, \dots, x_n \in \mathbb{R}, \mathbb{P}(X_1 \leq x_1, \dots, X_n \leq x_n) = \mathbb{P}(X_1 \leq x_1) \dots \mathbb{P}(X_n \leq x_n)$

Proof: (1) Take $\{\mathbb{Z}\} \cup \{\{i\} : i \in \mathbb{Z}\}$, generating π -system of \mathbb{Z} . To see that (**) holds with $A_i = \mathbb{Z}$, just sum over all $i_k \in \mathbb{Z}$ (for example, for $n=3, \mathbb{P}(X_1 = i_1, X_2 = i_2) = \sum_{i_3 \in \mathbb{Z}} \mathbb{P}(X_1 = i_1, X_2 = i_2, X_3 = i_3)$)
 (2) Take $\{\mathbb{R}\} \cup \{\} -\infty, x\} : x \in \mathbb{R}\}$, generating π -system of \mathbb{R} . To see that (**) holds with $A_i = \mathbb{R}$, just make $x_k \rightarrow \infty$.

Definition Let $X = (X_1, \dots, X_n)$ be a random variable in $E_1 \times \dots \times E_n$. The law \mathbb{P}_{X_i} of X_i is called a marginal law. The law of (X_1, \dots, X_n) is called the joint law.

Remark Since $\mathbb{P}_{(X_1, \dots, X_n)}(E_1 \times \dots \times E_{i-1} \times A_i \times E_{i+1} \times \dots \times E_n) = \mathbb{P}_{X_i}(A_i)$, the marginal laws are determined by the joint law $\mathbb{P}_{(X_1, \dots, X_n)}$. The converse is false in general, but it is true for independent random variables by (**)

Lemma (Composition principle) Let $(X_i)_{1 \leq i \leq n}$ be random variables with $X_i: \Omega \rightarrow E_i$.
 Let $f_i: E_i \rightarrow F_i$ be measurable. Assume that $(X_i)_{1 \leq i \leq n}$ are \perp .
 Then $(f_i(X_i))_{1 \leq i \leq n}$ are \perp .

Proof: This follows from the fact that $\sigma(f_i(X_i)) \subset \sigma(X_i)$.
 Indeed, take $A \in \sigma(f_i(X_i))$. Then $\exists B \in E_i$ with $A = (f_i \circ X_i)^{-1}(B) = X_i^{-1}(f_i^{-1}(B))$.
 Since f_i is measurable, $f_i^{-1}(B) \in E_i$, so $A \in \sigma(X_i)$.

Definition (independence for any family of random variables)

If $(X_i)_{i \in I}$ are random variables, they are independent (notation: \perp)
 if $\forall J \subset I$, $\text{Card}(J) < +\infty$, $(X_j)_{j \in J}$ are independent.

Let us give two useful results involving infinite families (countable for the first one, uncountable for the second one).

Lemma Let $(X_i)_{i \geq 1}$ be \perp . Fix $p \geq 1$. Set
 $\mathcal{B}_1 = \sigma(X_1, \dots, X_p)$ and $\mathcal{B}_2 = \sigma(X_k : k \geq p+1)$
 Then $\mathcal{B}_1 \perp \mathcal{B}_2$.

Proof: We apply the previous proposition of lecture 4 with
 $\mathcal{b}_1 = \sigma(X_1, \dots, X_p)$ and $\mathcal{b}_2 = \bigcup_{k=p+1}^{\infty} \sigma(X_k)$

Indeed, $\sigma(\mathcal{b}_1) = \mathcal{B}_1$, $\sigma(\mathcal{b}_2) = \mathcal{B}_2$ (exercise sheet) \mathcal{b}_1 and \mathcal{b}_2 are π -systems such
 that $\forall A \in \mathcal{b}_1, \forall B \in \mathcal{b}_2, P(A \cap B) = P(A)P(B)$

Indeed, we have $\sigma(X_1, \dots, X_p) \perp \sigma(X_{p+1}, \dots, X_k)$ by the coalition principle for
 independent σ -fields.

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END OF LECTURE 6

Remark The coalition principle for \perp σ -fields shows that if $(X_i)_{1 \leq i \leq n}$ are \perp r.v. $(X_{i_1}, \dots, X_{i_2}), (X_{i_1+1}, \dots, X_{i_2}), \dots, (X_{i_r+1}, \dots, X_n)$ are \perp .
The previous proposition covers a case of an infinite family

Lemma The two random variables $(X_i)_{i \in I}$ and $(Y_j)_{j \in J}$ with values in $\prod_{i \in I} E_i$ and $\prod_{j \in J} F_j$ are independent if and only $\forall i_1, \dots, i_k \in I \quad \forall j_1, \dots, j_\ell \in J$,
 $(X_{i_1}, \dots, X_{i_k}) \perp (Y_{j_1}, \dots, Y_{j_\ell})$

Proof \Rightarrow This follows from the composition principle with the functions
 $f: (x_i)_{i \in I} \mapsto (x_{i_1}, \dots, x_{i_k})$ and $g: (y_j)_{j \in J} \mapsto (y_{j_1}, \dots, y_{j_\ell})$

\Leftarrow We apply the previous proposition with
 $\beta_1 = \bigcup_{\substack{k \geq 1 \\ i_1, \dots, i_k \in I}} \sigma(X_{i_1}, \dots, X_{i_k})$ and $\beta_2 = \bigcup_{\substack{\ell \geq 1 \\ j_1, \dots, j_\ell \in J}} \sigma(Y_{j_1}, \dots, Y_{j_\ell})$,

which are π -systems containing Ω such that $\sigma(\beta_1) = \sigma((X_i)_{i \in I})$, $\sigma(\beta_2) = \sigma((Y_j)_{j \in J})$
and $\forall A \in \beta_1, \forall B \in \beta_2, P(A \cap B) = P(A)P(B)$

We now introduce the notion of tail σ -field.

Definition If $(X_i)_{i \geq 1}$ are random variables, we set $\mathcal{B}_n = \sigma(X_k : k \geq n)$ and
 $\mathcal{B}_\infty = \bigcap_{n \geq 1} \mathcal{B}_n$, called the tail σ -field of $(X_i)_{i \geq 1}$

Intuitively \mathcal{B}_∞ corresponds to the events which do not change if we change the values of a finite number of X_i 's.

Example If $(X_i)_{i \geq 1}$ are real-valued, set $S_n = X_1 + \dots + X_n$. Then
 $\left\{ \limsup_{n \rightarrow \infty} S_n = +\infty \right\} \in \mathcal{B}_\infty$

Indeed, for every $k \geq 1$, this event belongs to $\left\{ \limsup_{n \geq k} (X_k + X_{k+1} + \dots + X_n) = +\infty \right\} \in \mathcal{B}_k$

Theorem (Kolmogorov 0-1 law) Assume that $(X_i)_{i \geq 1}$ are independent
then $\forall B \in \mathcal{B}_\infty, P(B) = 0$ or $P(B) = 1$

Proof: Set $\mathcal{D}_n = \sigma(X_1, \dots, X_n)$. Then $\mathcal{D}_n \perp\!\!\!\perp \mathcal{B}_{n+1}$, hence $\mathcal{D}_n \perp\!\!\!\perp \mathcal{B}_\infty$
 since $\mathcal{B}_\infty \subset \mathcal{B}_{n+1}$

Therefore $\forall A \in \bigcup_{n=1}^{\infty} \mathcal{D}_n$, $\forall B \in \mathcal{B}_\infty$, $P(A \cap B) = P(A)P(B)$

But $\bigcup_{n=1}^{\infty} \mathcal{D}_n$ is a π -system and $\sigma(\bigcup_{n=1}^{\infty} \mathcal{D}_n) = \sigma((X_n)_{n \geq 1})$

Hence $\forall A \in \sigma(X_n: n \geq 1)$, $\forall B \in \mathcal{B}_\infty$, $P(A \cap B) = P(A)P(B)$

Hence $\forall A \in \mathcal{B}_\infty$, $\forall B \in \mathcal{B}_\infty$, $P(A \cap B) = P(A)P(B)$.

Taking $A=B$, we get $P(B) = P(B)^2$, then $P(B) = 0$ or 1 .

4) Real-valued random variables

Recall that if $(x_n)_{n \geq 1}$ is a sequence in \mathbb{R} , we write

$$\limsup_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \sup_{k \geq n} x_k \in \bar{\mathbb{R}} = \mathbb{R} \cup \{\pm \infty\}$$

$$\liminf_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \inf_{k \geq n} x_k \in \bar{\mathbb{R}}$$

Proposition Let $f_n: (E, \mathcal{E}) \rightarrow (\bar{\mathbb{R}}, \mathcal{B}(\bar{\mathbb{R}}))$ be measurable functions.
 Then $\sup_n f_n$, $\inf_n f_n$, $\limsup_n f_n$, $\liminf_n f_n$ are measurable.
 (We equip $\bar{\mathbb{R}}$ with the distance $d(x, y) = |\operatorname{Arctan} x - \operatorname{Arctan} y|$)

Proof: We show it for $f = \sup_n f_n$ (it is similar for the other functions). It is enough to show that

$$\forall a \in \mathbb{R}, f^{-1}([-\infty, a]) \in \mathcal{E}.$$

$$\text{But } f^{-1}([-\infty, a]) = \bigcap_{n \geq 1} f_n^{-1}([-\infty, a]) \in \mathcal{E}.$$

Take home message: any "reasonable" operation on measurable functions gives a measurable function

Definition A simple function $f: (E, \mathcal{E}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ is a measurable function taking a finite number of values. Equivalently, f can be written in the form $f(x) = \sum_{i=1}^n a_i \mathbb{1}_{x \in A_i}$ ($A_i \subset E, a_i \in \mathbb{R}$)

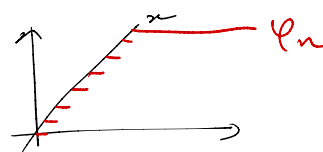
Remark By taking intersections, a simple function can be written uniquely in the form $f(x) = \sum_{i=1}^n b_i \mathbb{1}_{x \in B_i}$ with $b_1 < b_2 < \dots < b_n$ and $(B_i)_{1 \leq i \leq n}$ disjoint.

Theorem Let $f: E \rightarrow \mathbb{R}^+$ be a measurable function. There exists a sequence (f_n) of simple functions s.t. $0 \leq f_n \uparrow f$, that is $\forall x \in E$, the sequence $(f_n(x))_{n \geq 1}$ is increasing with limit $f(x)$.

In practice, this result is useful to show a result on general measurable functions by first showing it for simple functions and then by passing to the limit.

Proof: Step 1: We approximate $\mathbb{R}_+ \rightarrow \mathbb{R}_+$
 $x \mapsto x$

We just set $\varphi_n(x) = \min(2^{-n} \lfloor 2^n x \rfloor, n)$



Step 2: Take $f_n = \varphi_n \circ f$.

Important application: Doob-Dynkin Lemma

Let $f: (E, \mathcal{E}) \rightarrow (F, \mathcal{F})$ and $g: (E, \sigma(f)) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ be measurable functions. Then we can write

$g = h \circ f$ with $h: (F, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ a measurable function

Proof: To simplify, assume $g \geq 0$ (otherwise just write $g = g^+ - g^-$ with $g^+ = \max(g, 0) \geq 0$ and $g^- = \max(-g, 0) \geq 0$)

Step 1: Assume that $g = \mathbb{1}_A$ with $A \in \sigma(g)$. Then $A = f^{-1}(B)$ with $B \in \mathbb{R}$.

Setting $h = \mathbb{1}_B$, we have $g(x) = h(f(x))$ because $f(x) \in B \Leftrightarrow x \in f^{-1}(B)$.

Step 2: By linearity, the result holds when g is a simple function.

Now let g_n be $\sigma(g)$ -measurable simple functions s.t. $0 \leq g_n \uparrow g$ where $g_n = h_n \circ f$ with $h_n: (F, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ measurable

Then set $h(y) = \begin{cases} \sup_{n \geq 1} h_n(y) & \text{if this quantity is finite} \\ 0 & \text{otherwise} \end{cases}$

Then for $x \in E$ $\sup_{n \geq 1} h_n(f(x)) = \sup_{n \geq 1} g_n(x) = g(x)$, which implies $g(x) = h(f(x))$.

Remark A simple adaptation of the proof shows that the result is true when g is \mathbb{R}^n -valued (but it is false in full generality: see exercise sheet)

Remark In probability, this result is often used to say that $\sigma(X)$ measurable functions are functions of X .

5) Integration

END OF LECTURE 7

The notion of expectation is defined in probability using integration with respect to a measure in measure theory. Since it plays a crucial role, let us recall the setting.

We start with ≥ 0 functions

Let (E, \mathcal{E}, μ) be a measured space.

a) Definition of the Lebesgue integral

Definition If $f: E \rightarrow [0, +\infty]$ is a simple function, $f = \sum_{i=1}^n a_i \mathbb{1}_{A_i}$ with $a_i \in (\mathbb{R}_+ \cup \{+\infty\})$ and $A_i \in \mathcal{E}$, we define $\int f d\mu = \sum_{i=1}^n a_i \mu(A_i)$ [with the convention $0 \times \infty = 0$]

Remark

- we sometimes write $\int_E f d\mu$, $\int f(x) \mu(dx)$, $\int f(x) d\mu(x)$
- if $f = \sum_{i=1}^m b_i \mathbb{1}_{B_i}$, $\sum_{i=1}^m b_i \mu(B_i) = \sum_{i=1}^n a_i \mu(A_i)$ (the definition of $\int f d\mu$ does not depend on the choice of the representative of f)

Elementary properties Let $f, g \geq 0$ be simple functions

1) If $a, b \geq 0$, $\int (af + bg) d\mu = a \int f d\mu + b \int g d\mu$

2) If $f \leq g$, $\int f d\mu \leq \int g d\mu$

In particular, $\int f d\mu = \sup_{\substack{h \text{ simple} \\ h \leq f}} \int h d\mu$

Definition Let $f: E \rightarrow [0, \infty]$ be measurable. We set

$$\int f d\mu = \sup \left\{ \int h d\mu : 0 \leq h \leq f, h \text{ simple} \right\} \in \mathbb{R}_+ \cup \{\infty\}$$

In probability, if $X: \Omega \rightarrow \mathbb{R}_+$ is a random variable, we define

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega)$$

In particular, if $A \in \mathcal{E}$, $\mathbb{E}[\mathbb{1}_A] = \int_{\Omega} \mathbb{1}_A(\omega) \mathbb{P}(d\omega) = \mathbb{P}(A)$.

Proposition ① If $0 \leq f \leq g \leq +\infty$, $\int f d\mu \leq \int g d\mu$

② If $f \geq 0$ and $\mu(\{x \in E: f(x) > 0\}) = 0$, then $\int f d\mu = 0$.

Proof: ① Ok by definition

② Let h be a simple function such that $0 \leq h \leq f$.

Since $h(x) > 0 \Rightarrow f(x) > 0$, we have $\mu(\{x \in E: h(x) > 0\}) = 0$.

Hence $\int h d\mu = 0$ by definition of the integral of a ≥ 0 simple function

So $\int f d\mu = 0$ by definition of the integral of a ≥ 0 function

b) Monotone convergence

Theorem (monotone convergence)

Let $(f_n: E \rightarrow [0, +\infty])_{n \geq 1}$ be a non-decreasing sequence of functions

(i.e. $\forall x \in E, \forall n \geq 1, f_{n+1}(x) \geq f_n(x)$). Set $f(x) = \lim_{n \rightarrow \infty}^{\uparrow} f_n(x)$

Then $\int f d\mu = \lim_{n \rightarrow \infty}^{\uparrow} \int f_n d\mu \in [0, \infty]$

means that the sequence is increasing

Probabilistic version: If $(X_n)_{n \geq 0}$ is a non-decreasing sequence of random variables, $\mathbb{E}[\lim_{n \rightarrow \infty} X_n] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n]$

Here $\lim_{n \rightarrow \infty} X_n$ is the random variable $\omega \mapsto \lim_{n \rightarrow \infty} X_n(\omega)$

Proof ① Since $f \geq f_n$, we have $\int f d\mu \geq \int f_n d\mu$. Hence $\int f d\mu \geq \lim_{n \rightarrow \infty} \int f_n d\mu$
(the limit exists since $(\int f_n d\mu)_{n \geq 1}$ is increasing)

② For the other inequality, take h simple, $h \leq f$
The goal is to connect h to f_n .

Idea 1: Set $E_n = \{x \in E : h(x) \leq f_n(x)\}$

problem: it can be empty for every $n \geq 1$.

Idea 2: introduce a new parameter $a > 1$ to "get some space": set

$$E_n = \{x : h(x) \leq a f_n(x)\}.$$

Since $h(x) \leq a f(x) \forall x \in E$, we have $\bigcup_{n \geq 1} E_n = E$, and $f_n \geq \frac{1}{a} \mathbb{1}_{E_n} h$.

$$\text{Hence } \int f_n d\mu \geq \int \frac{1}{a} \mathbb{1}_{E_n} h d\mu = \frac{1}{a} \sum_{i=1}^k b_i \mu(B_i \cap E_n) \text{ if } h = \sum_{i=1}^k b_i \mathbb{1}_{B_i}$$

But $B_i \cap E_n \uparrow B_i$

$$\text{Hence } \lim_{n \rightarrow \infty} \mu(B_i \cap E_n) = \mu(B_i)$$

$$\text{Therefore } \liminf_{n \rightarrow \infty} \int f_n d\mu \geq \frac{1}{a} \sum_{i=1}^k b_i \mu(B_i) = \frac{1}{a} \int h d\mu$$

Take $a \rightarrow 1$: $\liminf_{n \rightarrow \infty} \int f_n d\mu \geq \int h d\mu$.

Taking the sup over h simple, we get $\lim_{n \rightarrow \infty} \int f_n d\mu \geq \int f d\mu$

Corollary ① If $f, g \geq 0$ and $a, b \geq 0$, $\int (af + bg) d\mu = a \int f d\mu + b \int g d\mu$

$$\text{② If } f_k \geq 0, \int (\sum_k f_k) d\mu = \sum_k \int f_k d\mu$$

Probabilistic version:
• for $X, Y \geq 0$ r.v. $\mathbb{E}[aX + bY] = a\mathbb{E}[X] + b\mathbb{E}[Y]$
• for $X_k \geq 0$ r.v., $\mathbb{E}[\sum_k X_k] = \sum_k \mathbb{E}[X_k]$

Proof: ① Let f_n, g_n be simple ≥ 0 functions such that $f_n \uparrow f, g_n \uparrow g$ (cf 4) for existence). Then by monotone convergence:

$$\begin{aligned} \int (af + bg) d\mu &= \lim \uparrow \int (af_n + bg_n) d\mu \\ &= \lim \uparrow (a \int f_n d\mu + b \int g_n d\mu) \\ &= a \int f d\mu + b \int g d\mu \end{aligned}$$

② Set $F_n = \sum_{k=1}^n f_k, F = \sum_{k=1}^{\infty} f_k$. Then $F_n \uparrow F$, so

$$\int F_n d\mu \rightarrow \int F d\mu$$

But $\int F_n d\mu = \sum_{k=1}^n \int f_k d\mu \xrightarrow{n \rightarrow \infty} \sum_{k=1}^{\infty} \int f_k d\mu$

Examples. For $a \in E$, the Dirac measure at a is defined by $\delta_a(A) = \begin{cases} 0 & \text{if } a \notin A \\ 1 & \text{if } a \in A \end{cases}$ for every $A \in \mathcal{E}$. Then $\forall f: E \rightarrow \mathbb{R}_+$ measurable,

$$\int_E f(x) \delta_a(dx) = f(a).$$

Indeed, this is true for simple functions and we conclude by monotone convergence

• If $\#$ is the counting measure on \mathbb{N} , then $\forall f: \mathbb{N} \rightarrow \mathbb{R}_+$,

$$\int_{\mathbb{N}} f(x) \#(dx) = \sum_{i=0}^{\infty} f(i)$$

Indeed, this is true for simple functions and we conclude by monotone convergence

c) Fatou's lemma

Theorem (Fatou's lemma) Let (f_n) be a sequence of ≥ 0 measurable functions. Then

$$\int \liminf_{n \rightarrow \infty} f_n d\mu \leq \liminf_{n \rightarrow \infty} \int f_n d\mu$$

Probabilistic setting: If $(X_n)_{n \geq 1}$ are ≥ 0 r.v., $\mathbb{E}[\liminf_{n \rightarrow \infty} X_n] \leq \liminf_{n \rightarrow \infty} \mathbb{E}[X_n]$

Proof: By definition, $\liminf_{n \rightarrow \infty} f_n = \lim_{k \rightarrow \infty} \inf_{n \geq k} f_n$, so by monotone convergence

$$\int \liminf_{n \rightarrow \infty} f_n d\mu = \lim_{k \rightarrow \infty} \int \inf_{n \geq k} f_n d\mu. \text{ But for every integer } p \geq k, \inf_{n \geq k} f_n \leq f_p,$$

which implies $\int \inf_{n \geq k} f_n d\mu \leq \int f_p d\mu$. By taking the increasing limit as $k \uparrow \infty$, we get the result

d) Markov's inequality

We say that a property is true almost everywhere (a.e.) if the set of $x \in E$ for which it is not true is negligible, i.e. has 0 measure (in probability: almost-surely/a.s.)

Proposition Let $f \geq 0$

- ① $\forall a > 0, \mu(\{x: f(x) \geq a\}) \leq \frac{1}{a} \int f d\mu$
- ② $\int f d\mu < \infty \Rightarrow f < \infty$ a.e.
- ③ $\int f d\mu = 0 \Rightarrow f = 0$ a.e.
- ④ $\exists f, g \geq 0, f = g$ a.e. $\Rightarrow \int f d\mu = \int g d\mu$

Probabilistic setting for $X, Y \geq 0$ r.v.

- ① $\forall a > 0, \mathbb{P}(X \geq a) \leq \frac{1}{a} \mathbb{E}[X]$ (Markov's inequality)
- ② $\mathbb{E}[X] < \infty \Rightarrow X < \infty$ a.s.
- ③ $\mathbb{E}[X] = 0 \Rightarrow X = 0$ a.s.
- ④ $X = Y$ a.s. $\Rightarrow \mathbb{E}[X] = \mathbb{E}[Y]$

Proof ① Set $E_a = \{x : f(x) \geq a\}$. Then $f \geq a \mathbb{1}_{E_a}$.

Hence $\int f d\mu \geq \int a \mathbb{1}_{E_a} d\mu = a \mu(E_a)$

② Set $A_n = \{f \geq n\}$ (i.e. $A_n = \{x : f(x) \geq n\}$)

and $A_\infty = \{f = \infty\}$.

Then $\mu(A_\infty) = \mu(\bigcap_{n \geq 1} A_n) = \lim_{n \rightarrow \infty} \mu(A_n) \stackrel{①}{\leq} \lim_{n \rightarrow \infty} \frac{1}{n} \int f d\mu = 0$.

③ (\Leftarrow) Already seen

(\Rightarrow) Set $B_n = \{f \geq \frac{1}{n}\}$. Then $\mu(B_n) \leq n \int f d\mu = 0$.

Hence $\mu(\{f > 0\}) = \mu(\bigcup_{n=1}^{\infty} B_n) \leq \sum_{n=1}^{\infty} \mu(B_n) = 0$.

④ Write $\int \max(f, g) d\mu = \int \min(f, g) d\mu + \int (\underbrace{\max(f, g) - \min(f, g)}_{=0 \text{ a.e.}}) d\mu = \int \min(f, g) d\mu$.

But $\min(f, g) \leq f, g \leq \max(f, g)$

Hence $\int \min(f, g) d\mu = \int f d\mu = \int g d\mu = \int \max(f, g) d\mu$

e) Fubini's Theorem

Recall that μ is σ -finite if one can write $E = \bigcup_{n=1}^{\infty} A_n$ with $(A_n)_{n \geq 1}$ countable sequence of events with $\mu(E_n) < \infty \forall n \geq 1$.

Informally, Fubini's theorem states that if $f: \mathbb{R}^n \rightarrow \mathbb{R}_+$ is measurable, μ_1, \dots, μ_n are σ -finite, then the integral $\int \dots \int f(x_1, \dots, x_n) \mu_1(dx_1) \dots \mu_n(dx_n)$ can be computed by integrating in any order.

In probability, this means that one can exchange $E[\cdot]$ and $\int dx$ for ≥ 0 r.v.

We state the theorem for $n=2$

Theorem (Fubini-Tonelli) Let μ, ν be σ -finite measures on (E, \mathcal{E}) and (F, \mathcal{F}) . We equip $E \times F$ with

the product σ -field $\mathcal{E} \otimes \mathcal{F}$. Let $f: E \times F \rightarrow \mathbb{R}_+$ be measurable.

(1) $x \mapsto \int f(x, y) \nu(dy)$ and $y \mapsto \int f(x, y) \mu(dx)$ are measurable

(2) We have $\int_{E \times F} f d\mu \otimes \nu = \int_E \left(\int_F f(x, y) \nu(dy) \right) \mu(dx) = \int_F \left(\int_E f(x, y) \mu(dx) \right) \nu(dy)$.

We do not give the proof here: it involves additional inputs from measure theory

§) Integrating real-valued random variables

If $f: E \rightarrow \mathbb{R}$ is real valued, when $\int |f| d\mu < \infty$, we say that f is μ -integrable and write $f \in L^1(E, \mathcal{E}, \mu)$.
More generally for $p > 0$, when $\int |f|^p d\mu < \infty$ we write $f \in L^p(E, \mathcal{E}, \mu)$.

Definition When $\int |f| d\mu < \infty$, write $f = f_+ - f_-$ with $f_+ = \max(f, 0) \geq 0$ and $f_- = \max(-f, 0) \geq 0$ and define $\int f d\mu = \int f_+ d\mu - \int f_- d\mu$.

As for ≥ 0 functions one checks that for f, g μ -integrable:

- $\int |f+g| d\mu \leq \int |f| d\mu + \int |g| d\mu$ (triangular inequality)
- $f \leq g$ μ almost everywhere implies $\int f d\mu \leq \int g d\mu$
- $f = g$ μ almost everywhere implies $\int f d\mu = \int g d\mu$.

Probabilistic setting $X: \Omega \rightarrow \mathbb{R}$ is integrable (in $L^1(\mathcal{X}, \mathcal{A}, \mathbb{P})$) if $\mathbb{E}[|X|] < \infty$.

When $\mathbb{E}[|X|^p] < \infty$ we write $X \in L^p(\mathcal{X}, \mathcal{A}, \mathbb{P})$

(observe that if X is bounded, i.e. $|X| \leq C$ for a fixed (deterministic) C , then $\mathbb{E}[|X|^p] \leq C^p$ so $X \in L^p$)

For real-valued functions, we have the following very important result.

Theorem (dominated convergence) Let (f_n) be a sequence of integrable real-valued measurable functions. Assume

① $\exists f: E \rightarrow \mathbb{R}$ measurable such that $f_n(x) \xrightarrow{n \rightarrow \infty} f(x)$ holds for μ -almost all x

② $\exists g: E \rightarrow \mathbb{R}_+$ measurable such that $\int g d\mu < \infty$ and $\forall n \geq 1, |f_n(x)| \leq g(x)$ for μ -almost all x [domination condition]

Then $\int |f_n - f| d\mu \xrightarrow{n \rightarrow \infty} 0$ and $\int f_n d\mu \rightarrow \int f d\mu$

Probabilistic setting Let X_n be real-valued r.v. Assume that:

① $\exists X$ r.v. such that $X_n \xrightarrow{n \rightarrow \infty} X$ almost surely

② $\exists Z \geq 0$ r.v. such that $\mathbb{E}[Z] < \infty$ and $\forall n \geq 1, |X_n| \leq Z$ almost surely

Then $\mathbb{E}[|X_n - X|] \xrightarrow{n \rightarrow \infty} 0$, $\mathbb{E}[X_n] \xrightarrow{n \rightarrow \infty} \mathbb{E}[X]$

Remark In the domination condition, it is crucial that the dominating function must NOT depend on n .

Proof: By (1) and (2), $|f| \leq g$ μ almost everywhere, so $\int |f| d\mu \leq \int g d\mu < \infty$, which shows that f is integrable.

Next, the idea is to consider $h_n = 2g - |f - f_n|$.

Observe that $h_n \geq 0$ μ -almost everywhere, so that $h_n = h_n \mathbb{1}_{h_n > 0}$ μ almost everywhere.

By Fatou's lemma: $\int \liminf_{n \rightarrow \infty} (h_n \mathbb{1}_{h_n > 0}) d\mu \leq \liminf_{n \rightarrow \infty} \int h_n \mathbb{1}_{h_n > 0} d\mu = \liminf_{n \rightarrow \infty} \int h_n d\mu$
 $\int 2g d\mu$.

Thus $2 \int g d\mu \leq 2 \int g - \limsup_{n \rightarrow \infty} \int |f - f_n| d\mu$, which implies $\int |f - f_n| d\mu \rightarrow 0$.

The second convergence follows from $|\int f d\mu - \int f_n d\mu| \leq \int |f - f_n| d\mu$.

The extension of Fubini-Tonelli to real-valued functions is the following

Theorem (Fubini-Lebesgue) Let μ, ν be σ -finite measures on (E, \mathcal{E}) and (F, \mathcal{F}) . We equip $E \times F$ with the product σ -field $\mathcal{E} \otimes \mathcal{F}$. Let $f: E \times F \rightarrow \mathbb{R}$ be $\mu \otimes \nu$ integrable. Then

- ① for μ -almost every x , $y \mapsto f(x, y)$ is ν -integrable and for ν -almost every y , $x \mapsto f(x, y)$ is μ -integrable
- ② The functions $x \mapsto \int f(x, y) \nu(dy)$ and $y \mapsto \int f(x, y) \mu(dx)$ are well defined, except maybe on sets with 0 measure, and are respectively μ and ν integrable.
- ③ We have $\int_{E \times F} f d\mu \otimes \nu = \int_E \left(\int_F f(x, y) \nu(dy) \right) \mu(dx) = \int_F \left(\int_E f(x, y) \mu(dx) \right) \nu(dy)$

In practice, one first checks if $|f|$ is $\mu \otimes \nu$ integrable using Fubini-Tonelli, and then one can interchange the order of integration.

Application If X is an integrable real-valued r.v. and $(A_i)_{i \geq 1}$ are events such that $\Omega = \bigcup_{i \geq 1} A_i$ and $A_i \cap A_j = \emptyset$ for $i \neq j$, then

$$\mathbb{E}[X] = \sum_{i=1}^{\infty} \mathbb{E}[X \mathbb{1}_{A_i}]$$

Indeed, $\sum_{i=1}^{\infty} \mathbb{E}[X \mathbb{1}_{A_i}] = \mathbb{E}[X (\sum_{i=1}^{\infty} \mathbb{1}_{A_i})]$

$\mathbb{1}$ because $\forall \omega \in \Omega$ there is only one $i \geq 1$ such that $\omega \in A_i$

This is useful when one has to treat several different cases.

It can be seen as a functional version of the law of total probability, which is:

$$P(A) = \sum_{i=1}^{\infty} P(A \cap A_i) \quad (\text{which comes from the fact that } A = \bigcup_{i=1}^{\infty} A \cap A_i)$$

Example: If Y is a \mathbb{Z} -valued r.v. and $X \geq 0$, $E[X] = \sum_{i \in \mathbb{Z}} E[X \mathbb{1}_{Y=i}]$

6) Classical laws

a) Discrete laws

- uniform law: If E is a finite set with n elements, X follows the uniform distribution on E if $P(X=z) = \frac{1}{n}$ for all $z \in E$
- Bernoulli law of parameter $p \in (0,1)$: it's the law of a r.v. X in $\{0,1\}$ with $P(X=1)=p$ $P(X=0)=1-p$
Interpretation: result of a rigged coin giving heads with probability p
- Binomial law $B(n,p)$ ($n \geq 1, p \in (0,1)$): it's the law of a r.v. in $\{1, \dots, n\}$ with $P(X=k) = \binom{n}{k} p^k (1-p)^{n-k}$
Interpretation: number of heads when tossing n times the previous coin
- Geometric law of parameter $p \in (0,1)$: It's the law of a r.v. in $\{0,1,2,\dots\}$ with $P(X=k) = p(1-p)^{k-1}$ $k \geq 1$.
Interpretation: number of trials before the first heads with the previous coin
- Poisson law of parameter $\lambda > 0$: it's the law of a r.v. in \mathbb{N} with $P(X=k) = \frac{\lambda^k}{k!} e^{-\lambda}$, $k \geq 0$
Interpretation: law of rare events (this will be seen later)

b) Continuous laws

END OF LECTURE 8

this involves the notion of density

Definition Let $p: \mathbb{R} \rightarrow \mathbb{R}_+$ be a measurable function such that $\int_{\mathbb{R}} p(x) dx = 1$

For $A \in \mathcal{B}(\mathbb{R})$, the formula $\mu(A) = \int_A p(x) dx = \int \mathbb{1}_A(x) p(x) dx$ defines a probability measure on \mathbb{R}

A r.v. X having this as law is called a r.v. with density p . Its cdf is $P(X \leq x) = \int_{-\infty}^x p(t) dt$.

⚠ a density is not uniquely defined: it is defined up to a 0 Lebesgue measure set (if $p=q$ almost everywhere, X has density p and q ⚠)

One can check that for every $f: \mathbb{R} \rightarrow \mathbb{R}_+$ measurable $\mathbb{E}[f(X)] = \int_{\mathbb{R}} f(x) p(x) dx$ (*)

Indeed, if f is the form $f = \mathbb{1}_A$ with $A \in \mathcal{B}(\mathbb{R})$, we have

$$\mathbb{E}[\mathbb{1}_A(X)] = \int_{\mathbb{R}} \mathbb{1}_A(x) p(x) dx = \mathbb{P}(\{\omega \in \Omega: X(\omega) \in A\}) = \mathbb{P}_X(A)$$

(definition of the integral of a simple function)

Also $\int_{\mathbb{R}} \mathbb{1}_A(x) p(x) dx = \int_A p(x) dx = \mathbb{P}_X(A)$ by definition.

By linearity, (*) holds for f simple. Then take $0 \leq f_n \uparrow f$ with f_n simple.

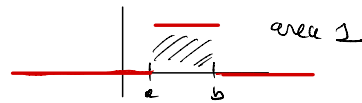
Then $\mathbb{E}[f_n(X)] = \int_{\mathbb{R}} f_n(x) p(x) dx$ by monotone convergence theorem.

$$\downarrow \quad \quad \quad \downarrow$$

$$\mathbb{E}[f(X)] \quad \quad \quad \int_{\mathbb{R}} f(x) p(x) dx$$

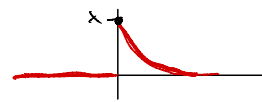
• Uniform law on $[a, b]$ ($a < b$):

$$p(x) = \frac{1}{b-a} \mathbb{1}_{[a,b]}(x)$$



• Exponential law of parameter $\lambda > 0$

$$p(x) = \lambda e^{-\lambda x} \mathbb{1}_{x \geq 0}$$

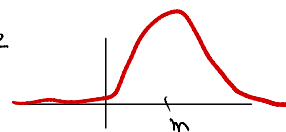


Then $\mathbb{E}[X] = \int_0^{\infty} \lambda x e^{-\lambda x} dx = \frac{1}{\lambda}$

It satisfies $\mathbb{P}(X > a+b) = \mathbb{P}(X > a) \mathbb{P}(X > b)$ (memoryless property)

• Gaussian law $N(m, \sigma^2)$ ($m \in \mathbb{R}, \sigma^2 > 0$)

One checks that $\mathbb{E}[X] = m$, $\sigma^2 = \mathbb{E}[(X-m)^2]$ $p(x) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-m)^2}{2\sigma^2}}$



Remark If X has density p , its CDF $F(x) = \int_{-\infty}^x p(u) du$ is continuous. Indeed, take a sequence $x_n \rightarrow x$.

Then $F(x_n) = \int_{\mathbb{R}} \frac{p(u) \mathbb{1}_{]-\infty, x_n]}(u) du}{f_n(u)}$

• For fixed $u \neq x$, $f_n(u) \rightarrow p(u) \mathbb{1}_{]-\infty, x]}(u)$ since $\{x\}$ has 0 Lebesgue measure, this convergence holds for almost all u

• $|f_n(u)| \leq p(u)$, which is an integrable function which does not depend on n

Then $F(x_n) \rightarrow \int_{\mathbb{R}} p(u) \mathbb{1}_{]-\infty, x]}(u) du = F(x)$

⚠ The converse is false in general: CDF continuous $\not\Rightarrow$ density

What is true is CDF of X continuous $\Leftrightarrow \forall x \in \mathbb{R}, \mathbb{P}(X=x) = 0$

Remark If $F: \mathbb{R} \rightarrow [0,1]$ is non-decreasing, $\lim_{x \rightarrow -\infty} F = 0$, $\lim_{x \rightarrow \infty} F = 1$, continuous AND piece-wise C^1 , that is $\exists -\infty = a_0 < a_1 < \dots < a_n = \infty$ such that F is C^1 on (a_i, a_{i+1}) for every $0 \leq i < n$, then F is the CDF of a r.v with density $p(x) = \begin{cases} F'(x) & \text{for } x \in (a_i, a_{i+1}) \\ 0 & \text{otherwise} \end{cases}$

Indeed, for every $x \in \mathbb{R}$ we then have $F(x) = \int_{-\infty}^x p(t) dt$

In particular, if the cdf of X is continuous and piece-wise C^1 , then X has a density (given by the a.s. derivative of its cdf)

Remark One similarly defines random variables with density on \mathbb{R}^n : if $p: \mathbb{R}^n \rightarrow \mathbb{R}_+$ is a measurable function with $\int_{\mathbb{R}^n} p(x_1, \dots, x_n) dx_1 \dots dx_n < \infty$, $X = (X_1, \dots, X_n)$ has density p if $\forall A \in \mathcal{B}(\mathbb{R}^n)$,

$$P(X \in A) = \int_A p(x_1, \dots, x_n) dx_1 \dots dx_n.$$

Then $\forall 1 \leq i \leq n$ X_i has a density p_i in \mathbb{R} obtained by integrating p with respect to the other variables:

$$p_i(x) = \int_{\mathbb{R}^{n-1}} p(x_1, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n) dx_1 \dots dx_{i-1} dx_{i+1} \dots dx_n.$$

7) Integration and independence

the following result is very useful

Theorem (transfer theorem) Let $X: \Omega \rightarrow E$ be a random variable, $f: E \rightarrow \mathbb{R}_+$ a measurable function. Then $\mathbb{E}[f(X)] = \int_E f(x) P_X(dx)$

Proof: Step 1: Take $f = \mathbb{1}_A$ with $A \in E$. Then $\mathbb{E}[\mathbb{1}_{X \in A}] = P(X \in A)$, and

$$\int_E \mathbb{1}_A(x) P_X(dx) = P_X(A) = P(X \in A)$$

Step 2: By linearity, the result is true for any ≥ 0 simple function.

We then take a sequence (f_n) of simple functions such that $0 \leq f_n \leq f$ and $f_n \uparrow f$, and conclude by monotone convergence:

$$\mathbb{E}[f_n(X)] = \int_E f_n(x) P_X(dx) \xrightarrow{n \rightarrow \infty} \int_E f(x) P_X(dx)$$

$$\int_{\Omega} f_n(X(\omega)) P(d\omega) \xrightarrow{n \rightarrow \infty} \int_{\Omega} f(X(\omega)) P(d\omega) = \mathbb{E}[f(X)].$$

$$\text{Hence } \mathbb{E}[f(X)] = \int_E f(x) P_X(dx)$$

Remark If X has density p , we have seen that for $f: \mathbb{R} \rightarrow \mathbb{R}_+$ measurable, $\mathbb{E}[f(X)] = \int_{\mathbb{R}} f(x) p(x) dx$.

It is also $\int_{\mathbb{R}} f(x) P_X(dx)$ by the transfer theorem. For this reason we write $P_X(dx) = p(x) dx$

Remark The transfer theorem is also valid for $f: E \rightarrow \mathbb{R}$ (not necessarily ≥ 0) bounded (write $f = f^+ - f^-$ with $f^+, f^- \geq 0$) and more generally for $f: E \rightarrow \mathbb{R}$ such that $\mathbb{E}[|f(X)|] < \infty$.

Application: Let U be uniform on $[0, 1]$. Find the law of U^2

Take $f: [0, 1] \rightarrow \mathbb{R}_+$ measurable. Then by the transfer theorem

$$\mathbb{E}[f(U^2)] = \int_{\mathbb{R}} f(u^2) \mathbb{P}_U(du) = \int_0^1 f(u^2) du \stackrel{[u^2=x]}{=} \int_0^1 f(x) \frac{1}{2\sqrt{x}} dx$$

But we know that $\mathbb{E}[f(U^2)] = \int_{\mathbb{R}} f(x) \mathbb{P}_{U^2}(dx)$

We conclude that $\boxed{\mathbb{P}_{U^2}(dx) = \mathbb{1}_{[0,1]}(x) \frac{1}{2\sqrt{x}} dx}$

Indeed, if $\int_E f(x) \mu(dx) = \int_E f(x) \nu(dx)$ for every $f: E \rightarrow \mathbb{R}_+$ measurable, then $\mu = \nu$ (just take $f = \mathbb{1}_A$).

This is the dummy function method.

Application If X has density p , then $\mathbb{E}[|X|] = \int_0^\infty |x| \mathbb{P}_X(dx) = \int_0^\infty |x| p(x) dx$

Example If X has density $\frac{\alpha+1}{x^{\alpha+2}} \mathbb{1}_{[1, \infty[}$, then for $p > 0$ $\mathbb{E}[X^p] < \infty \Leftrightarrow p > \alpha + 1$.

Indeed, by the transfer theorem, $\mathbb{E}[X^p] = \int_0^\infty x^p \mathbb{P}_X(dx) = \int_1^\infty \frac{\alpha+1}{x^{p+\alpha+2}} dx$ which is finite iff $p - \alpha > 1$.

Corollary If $X: \Omega \rightarrow E$ and $Y: \Omega \rightarrow E$ are two random variables with same law, then $\mathbb{E}[f(X)] = \mathbb{E}[f(Y)] \quad \forall f: E \rightarrow \mathbb{R}_+$ measurable

proof: $\mathbb{E}[f(X)] = \int_E f(x) \mathbb{P}_X(dx) = \int_E f(x) \mathbb{P}_Y(dx) = \mathbb{E}[f(Y)]$

Example if $X: \Omega \rightarrow \mathbb{R}_+$ and $Y: \Omega \rightarrow \mathbb{R}_+$ have the same law, then $\mathbb{E}[X^p] = \mathbb{E}[Y^p] \quad \forall p > 0$.

END OF LECTURE 9

Theorem If X_1, \dots, X_n are \mathbb{R} real-valued random variables with X_i having density p_i , then (X_1, \dots, X_n) has density $p_1(x_1) \dots p_n(x_n)$

Proof: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}_+$ be measurable. We use the dummy function method.

By 4, $\mathcal{B}_{(X_1, \dots, X_n)} = \mathcal{B}_{X_1} \otimes \dots \otimes \mathcal{B}_{X_n}$. Thus

$$\begin{aligned} \mathbb{E}[f(X_1, \dots, X_n)] &\stackrel{\text{transfer theorem}}{=} \int_{\mathbb{R}^n} f(x_1, \dots, x_n) \mathcal{P}_{(X_1, \dots, X_n)}(dx_1 \dots dx_n) = \int_{\mathbb{R}^n} f(x_1, \dots, x_n) \mathcal{P}_{X_1}(dx_1) \otimes \dots \otimes \mathcal{P}_{X_n}(dx_n) \\ &= \int_{\mathbb{R}^n} f(x_1, \dots, x_n) \underbrace{p_1(x_1) \dots p_n(x_n)}_{\text{law of } (X_1, \dots, X_n)} dx_1 \dots dx_n \end{aligned}$$

! In general, if X_1, \dots, X_n have densities in \mathbb{R} , (X_1, \dots, X_n) does not have a density in \mathbb{R}^n (if X has a density, one can check that (X, X) does not have a density in \mathbb{R}^2).

Theorem Let X, Y be \mathbb{R} r.v. in \mathbb{R} with densities. Then $X+Y$ has a density

Proof let p, q be densities of X, Y . We use the dummy function method. Let $f: \mathbb{R} \rightarrow \mathbb{R}_+$ be measurable.

$$\mathbb{E}[f(X+Y)] = \int_{\mathbb{R}^2} f(x+y) p(x) q(y) dx dy = \int_{\mathbb{R}} q(y) \left(\int_{\mathbb{R}} f(x+y) p(x) dx \right) dy$$

To compute $\int_{\mathbb{R}} f(x+y) p(x) dx$ (for fixed y) we use the change of variables $z = x+y$:

$$\int_{\mathbb{R}} f(x+y) p(x) dx = \int_{\mathbb{R}} f(z) p(z-y) dz, \text{ so } \mathbb{E}[f(X+Y)] = \int_{\mathbb{R}} q(y) \left(\int_{\mathbb{R}} f(z) p(z-y) dz \right) dy$$

and using Fubini-Tonelli this is $\int_{\mathbb{R}} f(z) \left(\int_{\mathbb{R}} p(z-y) q(y) dy \right) dz$

We conclude that $X+Y$ has a density, given by $z \mapsto \int_{\mathbb{R}} p(z-y) q(y) dy$ (called the convolution of X and Y)

Application Let (X, Y) be a r.v. with density in \mathbb{R}^2 . Then $\mathbb{P}(X=Y) = 0$

Proof Let p be a density of (X, Y) . Using the transfer theorem, write

$$\mathbb{P}(X=Y) = \mathbb{E}[\mathbb{1}_{X=Y}] = \int_{\mathbb{R}^2} \mathbb{1}_{x=y} p(x, y) dx dy$$

$$= \int_{\mathbb{R}} \left(\int_{\mathbb{R}} \mathbb{1}_{x=y} p(x, y) dx \right) dy$$

But for fixed $y \in \mathbb{R}$, $x \mapsto \mathbb{1}_{x=y} p(x, y)$ is $= 0$ if $x \neq y$.

Thus $x \mapsto \int_{x=y} f(x,y)$ is almost everywhere equal to 0. Thus $\int \int_{x=y} f(x,y) dx dy = 0$.

Thus $P(X=Y) = \int_{\mathbb{R}} 0 dy = 0$



Application If X has a density, (X,X) does not have a density (since $P(X=X)=1$)

Corollary If X, Y are \perp r.v with densities, then $P(X=Y) = 0$
Indeed, by what we have seen (X,Y) has then a density in \mathbb{R}^2 .

Theorem The following assertions are equivalent:

① X_1, \dots, X_n are \perp

② $\forall f_i: E \rightarrow \mathbb{R}_+$ measurable, $\mathbb{E}[f_1(X_1) \dots f_n(X_n)] = \prod_{k=1}^n \mathbb{E}[f_k(X_k)]$.

Proof: For ① \Rightarrow ②, we use the fact that $X_1, \dots, X_n \perp \Rightarrow P_{(X_1, \dots, X_n)} = P_{X_1} \otimes \dots \otimes P_{X_n}$. By the transfer theorem

$$\begin{aligned} \mathbb{E}[f_1(X_1) \dots f_n(X_n)] &= \int f_1(x_1) \dots f_n(x_n) P_{(X_1, \dots, X_n)}(dx_1, \dots, dx_n) \\ &= \int f_1(x_1) \dots f_n(x_n) P_{X_1} \otimes \dots \otimes P_{X_n}(dx_1, \dots, dx_n) \\ &\stackrel{[Fubini]}{=} \prod_{k=1}^n \int f_k(x_k) P_{X_k}(dx_k) \\ &= \prod_{k=1}^n \mathbb{E}[f_k(X_k)] \end{aligned}$$

For ② \Rightarrow ① just take $f_{i,j} = \mathbb{1}_{A_i}$ for A_i measurable to get

$$P(X_1 \in A_1, \dots, X_n \in A_n) = P(X_1 \in A_1) \dots P(X_n \in A_n)$$



In practice, to show that $X \perp Y$, one often computes $\mathbb{E}[f(x)g(y)]$ to obtain something of the form $(\int f(x)\mu(dx))(\int g(y)\nu(dy)$.

Corollary if (X_1, \dots, X_n) has a density of a product form $g_1(x_1) \dots g_n(x_n)$ then X_1, \dots, X_n are \perp

This readily follows from ② \Rightarrow ① in the previous Theorem

Remark If the functions f_i are real valued, the equality $\mathbb{E}\left[\prod_{i=1}^n f_i(X_i)\right] \stackrel{(\ast)}{=} \prod_{i=1}^n \mathbb{E}[f_i(X_i)]$ is true under the integrability condition $\mathbb{E}[|f_i(X_i)|] < \infty$ for every $1 \leq i \leq n$.

In particular, if X_1, \dots, X_n are \perp integrable r.v., then $X_1 \cdot X_2 \cdot \dots \cdot X_n$ is integrable and $\mathbb{E}\left[\prod_{i=1}^n X_i\right] = \prod_{i=1}^n \mathbb{E}[X_i]$.

WARNING in general this is false without the \perp condition (take $n=2$, $X_1 = X_2$ with $\mathbb{E}[X_1] = 0$)

Application ① Let X be a real-valued in L^2 . Then $X \in L^1$ and we define the variance of X by $\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2] = \mathbb{E}[X^2] - \mathbb{E}[X]^2 \geq 0$

② [Cauchy-Schwarz] let X be in L^2 then $\mathbb{E}[|X|]^2 \leq \mathbb{E}[X^2]$

③ Let $(X_i)_{1 \leq i \leq n}$ be independent real-valued L^2 -random variables. Then

$$\text{Var}(X_1 + \dots + X_n) = \text{Var}(X_1) + \dots + \text{Var}(X_n)$$

Informally, the variance of a random variable measures its "dispersion" from its mean.

Proof ① Write $\mathbb{E}[|X|] = \mathbb{E}[|X| \mathbb{1}_{|X| \leq 1}] + \mathbb{E}[|X| \mathbb{1}_{|X| > 1}]$
 $\leq \mathbb{E}[\mathbb{1} \cdot \mathbb{1}_{|X| \leq 1}] + \mathbb{E}[X^2 \mathbb{1}_{|X| > 1}]$
 $\leq 1 + \mathbb{E}[X^2] < \infty$.

To prove the formula for $\text{Var}(X)$, write using linearity of expectation:

$$\begin{aligned} \mathbb{E}[(X - \mathbb{E}[X])^2] &= \mathbb{E}[X^2 - 2X\mathbb{E}[X] + \mathbb{E}[X]^2] \\ &= \mathbb{E}[X^2] - 2\mathbb{E}[X]\mathbb{E}[X] + \mathbb{E}[X]^2 = \mathbb{E}[X^2] - \mathbb{E}[X]^2 \end{aligned}$$

② This follows from $0 \leq \text{Var}(|X|) = \mathbb{E}[|X|^2] - \mathbb{E}[|X|]^2 = \mathbb{E}[X^2] - \mathbb{E}[|X|]^2$

③ It suffices to establish the result for $n=2$ (the general case follows by induction using the fact that $X_1 \perp X_2 + \dots + X_n$).

$$\begin{aligned} \text{Write } \text{Var}(X_1 + X_2) &= \mathbb{E}[(X_1 + X_2)^2] - (\mathbb{E}[X_1 + X_2])^2 \\ &= \mathbb{E}[X_1^2] + 2\mathbb{E}[X_1 X_2] + \mathbb{E}[X_2^2] - (\mathbb{E}[X_1]^2 + 2\mathbb{E}[X_1]\mathbb{E}[X_2] + \mathbb{E}[X_2]^2) \end{aligned}$$

But $\mathbb{E}[X_1 X_2] = \mathbb{E}[X_1]\mathbb{E}[X_2]$ by \perp .

$$\begin{aligned} \text{Thus } \text{Var}(X_1 + X_2) &= (\mathbb{E}[X_1^2] - \mathbb{E}[X_1]^2) + (\mathbb{E}[X_2^2] - \mathbb{E}[X_2]^2) \\ &= \text{Var}(X_1) + \text{Var}(X_2) \end{aligned}$$



Application If X is a $B(n, p)$ random variable, then $X \stackrel{\text{law}}{=} Y_1 + \dots + Y_n$ with $(Y_i)_{1 \leq i \leq n}$ independent Bernoulli(p) random variables, so $\text{Var}(X) = \text{Var}(Y_1 + \dots + Y_n) = \text{Var}(Y_1) + \dots + \text{Var}(Y_n) = p(1-p) + \dots + p(1-p) = n p(1-p)$.

Remarks. We have $\text{Var}(aX+b) = a^2 \text{Var}(X)$

- ③ above is false in general without \perp (take $n=2$ $X_1=X_2$)