

17.9.24

①

§ 0. Introduction

Our goal this semester is to study functions $f: \mathbb{C} \rightarrow \mathbb{C}$ defined on the complex plane \mathbb{C} , or on an open subset of \mathbb{C} .

We will see that the study of complex function theory is not simply the study of functions on \mathbb{R}^2 .

We will see that many ways the theory of functions of one real variable is more complicated than the theory of functions of a complex variable.

To give an idea of what I mean

let's try to compare and contrast:

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① It is not too difficult to write down a function of a real variable that is n times differentiable but not infinitely differentiable.

$$f(x) := \begin{cases} x^2 \sin(1/x^2) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$$

The derivative of f exists for every x including $x=0$. $f'(0) = 0$. Hence f is differentiable but its derivative is not continuous. Hence not differentiable twice.

By integrating f as many times as you like you can get a function h which is differentiable that many times but not infinitely differentiable.

In contrast: We'll see that if $f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable once then it is differentiable only many times.

② There are functions $f: \mathbb{R} \rightarrow \mathbb{R}$ that are only many times differentiable whose Taylor series does not represent f i.e. f is not analytic.

e.g. $f(x) = \begin{cases} \exp(-\frac{1}{x^2}) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$

Then f is ∞ 'ly differentiable. Unfortunately at $x=0$ all derivatives are zero. Hence its Taylor series is identically zero and cannot represent f .

In contrast: If $f: \mathbb{C} \rightarrow \mathbb{C}$ is a function of a complex variable which is differentiable then f is analytic, i.e. it can be represented by a power series.
(differentiable = analytic)

③ There are plenty of C^∞ functions of a real variable that are bounded
e.g. $\sin x, \cos x$

In contrast: We'll see that if $f: \mathbb{C} \rightarrow \mathbb{C}$ is differentiable and bounded then it is constant (Liouville's Thm)

④ For two functions of a real variable f, g f and g can agree on an open set without being equal

In contrast if $f, g: \mathbb{C} \rightarrow \mathbb{C}$ are 2 differentiable functions which coincides on an arbitrarily small disc (or even on a convergent sequence (2n)) then $f = g$
(Analytic continuation principle)

Remark

The power of complex function theory comes from this "robustness" or rigidity. It is a subject in some sense "analysis", geometry, algebra come together.

This, we will see, allows one to prove theorems that a priori has nothing to do with complex numbers.

Ex ① The Integral.

$$\int_0^{\infty} \cos(t^2) dt = \int_0^{\infty} \sin(t^2) dt = \sqrt{\frac{2\pi}{4}}$$

② Let $\pi(x) = \#\{p \text{ prime} \mid p \leq x\}$

then $\pi(x) \sim \frac{x}{\log x}$ Prime Number Theorem

$$\left(\lim_{x \rightarrow \infty} \pi(x) / (x / \log x) = 1 \right)$$

③ if $f \in \mathbb{C}[X]$ a non-zero poly.

⑤

Then f has a zero in \mathbb{C} .

(Fund. thm of Algebra)

④ let $r_4(n) = \# \{ (m_1, m_2, m_3, m_4) \in \mathbb{Z}^4 \mid m_1^2 + m_2^2 + m_3^2 + m_4^2 = n \}$

$$\text{Then } r_4(n) = 8 \sum_{\substack{d \mid n \\ 4 \nmid d}} d$$

In particular $r_4(n) \geq 1 \quad \forall n.$

Before we start with the defn of differentiability of a complex variable function, we quickly recall the defns and basic properties of complex numbers as well as some basic notions of topology and analysis

§ 1. Complex numbers and complex plane

P. (Review)

$$\mathbb{C} := \{x + iy \mid x, y \in \mathbb{R}, i^2 = -1\}$$

$$\mathbb{R} \hookrightarrow \mathbb{C}, \quad \mathbb{R} \subset \mathbb{C}$$

$$r \mapsto r + i \cdot 0$$

For $z = x + iy \in \mathbb{C}$ we define

Real part of $z := x = \operatorname{Re}(z)$

Imaginary part of $z := y = \operatorname{Im}(z)$

Complex conjugate of $z := \boxed{x - iy = \bar{z}}$

• $\operatorname{Re}(z) = \frac{z + \bar{z}}{2}$

• $\operatorname{Im}(z) = \frac{z - \bar{z}}{2i}$

• $z \in \mathbb{R} \Leftrightarrow z = \bar{z}$

$z \in i\mathbb{R} \Leftrightarrow z = -\bar{z}$ (purely imaginary)

- Complex numbers can also be represented as ordered pairs of real numbers in \mathbb{R}^2
 $z = (x, y)$ where we have $z = w$
 with $w = (u, v)$ if and only if $x = u$ and $y = v$

Addition in \mathbb{C} : if $z = x + iy$, $w = u + iv$

$$z + w = (x + u) + i(y + v)$$

as pairs $z + w = (x + u, y + v)$

⑦

Multiplication in \mathbb{C} $z \cdot w = (x + iy)(u + iv)$
 (using $i^2 = -1$) $= xu + i(xv + yu) + i^2 vy$
 $= (xu - vy) + i(xv + yu)$

as pairs in \mathbb{R}^2 : $(x, y) \cdot (u, v) := (xu - vy, xv + yu)$

Note $i = (0, 1)$, and $(0, 1) \cdot (0, 1) = (-1, 0) = -1$

\mathbb{R}^2 , together with these 2 operations $+$, \cdot becomes a field i.e.

$(\mathbb{R}^2, +, \cdot)$ satisfies ① $(\mathbb{R}^2, +)$ is a comm-group with additive identity $0 := (0, 0)$

② $(\mathbb{R}^2 \setminus \{0, 0\}, \cdot)$ is a comm group with mult. identity $1 := (1, 0)$

③ $z_1(z_2 + z_3) = z_1 z_2 + z_1 z_3$
 $= (z_2 + z_3)z_1$

Additive inverse of $z = (x, y)$: $-z = (-x, -y)$

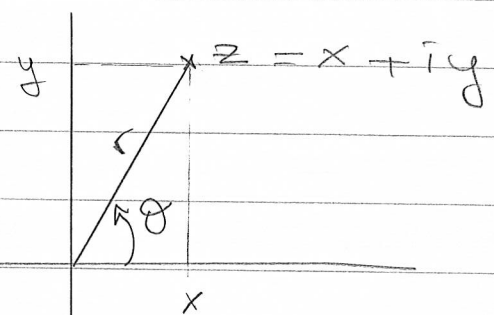
Mul. inverse of z ; $0 \neq z = (x, y) \Rightarrow z^{-1} = \frac{\bar{z}}{|z|^2}$

$$= \left(\frac{x}{x^2 + y^2}, \frac{-y}{x^2 + y^2} \right)$$

Here $|z| := \sqrt{z \bar{z}} = \sqrt{x^2 + y^2}$ is called

the norm, or modulus or abs. value of z

We also have the polar coordinate representation of complex numbers



$$z = r(\cos\theta + i\sin\theta) = re^{i\theta}$$

$$x = r\cos\theta$$

$$y = r\sin\theta$$

where $r \geq 0$, $\theta \in \mathbb{R}$
with $r = |z|$

The polar representation is not unique unless $z \neq 0$ and we restrict $\theta \in (-\pi, \pi]$ (or any other interval of length 2π).

θ is called the argument of z which is defined uniquely up to a multiple of 2π and is denoted by $\arg z$

$$\arg z = \{ \theta \in \mathbb{R} \mid z = |z|e^{i\theta} \}$$

The argument of z chosen in the interval $(-\pi, \pi]$ is called the principal argument and denoted by Arg z

$$\text{Arg}(i) = \frac{\pi}{2} \quad \text{Arg}(-c) = \pi \quad c \in \mathbb{R}$$

Remark - No assignment of argument is made to $0 \in \mathbb{C}$.

For $z = x + iy \neq 0$ we have

$$\text{Arg } z = \begin{cases} \arcsin(y/|z|) & \text{if } x \geq 0 \\ \pi - \arcsin(y/|z|) & \text{if } x < 0 \text{ and } y \geq 0 \\ -\pi - \arcsin(y/|z|) & \text{if } x < 0 \text{ and } y < 0 \end{cases}$$

Here for $t \in [-1, 1]$, $\arcsin t$ is the unique number $u \in [-\pi/2, \pi/2]$ s.t. $\sin u = t$

Observe that $\arg(z^{-1}) = -\arg z$

$$\arg(zw) = \arg z + \arg w$$

But it is not always the case that

$$\text{Arg}(z^{-1}) = -\text{Arg } z \quad \text{or}$$

$$\text{Arg}(zw) = \text{Arg } z + \text{Arg } w.$$

for example $\arg(-\frac{1}{2}) = \pi \neq -\arg(-2) = -\pi$

$$\text{and } \pi = \text{Arg}(-1) = \text{Arg}((-i)(-i))$$

$$\neq \text{Arg}(-i) + \text{Arg}(-i) = -\frac{\pi}{2} + -\frac{\pi}{2} = -\pi$$

Recall: $|z| = 0 \Leftrightarrow z = 0 \quad \forall z \in \mathbb{C}$

$$\bullet |z_1 - z_2| \leq |z_1 + z_2| \leq |z_1| + |z_2| \quad \forall z_1, z_2 \in \mathbb{C}$$

$$\bullet |z_1 z_2| = |z_1| |z_2| \quad \forall z_1, z_2 \in \mathbb{C}$$

$$\bullet |\bar{z}| = |z|$$

$$\bullet |\text{Re}(z)| \leq |z|, \quad |\text{Im}(z)| \leq |z| \quad \forall z \in \mathbb{C}$$

$$\bullet \text{if } z = r e^{i\theta}, \quad w = s e^{i\beta} \quad \text{then } zw = r s e^{i(\theta + \beta)}$$

Representation of \mathbb{C} as 2×2 matrices.

for $z = a + ib$, let $Z = \begin{pmatrix} a & -b \\ b & a \end{pmatrix}$

$w = c + di$, let $W = \begin{pmatrix} c & -d \\ d & c \end{pmatrix}$

then $ZW = \begin{pmatrix} a & -b \\ b & a \end{pmatrix} \begin{pmatrix} c & -d \\ d & c \end{pmatrix} = \begin{pmatrix} ac - bd & -(bc + ad) \\ bc + ad & ac - bd \end{pmatrix}$

On the other hand

$zw = ac - bd + i(bc + ad)$

Hence the multiplication in \mathbb{C} corresponds to multiplication of corresponding matrices in $M_2(\mathbb{R})$

We can represent any $z \in \mathbb{C}$ with the matrix

$$Z = \begin{pmatrix} \operatorname{Re} z & -\operatorname{Im} z \\ \operatorname{Im} z & \operatorname{Re} z \end{pmatrix} \\ = (\operatorname{Re} z) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + (\operatorname{Im} z) \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$i \in \mathbb{C}$ corresponds to $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ and $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}^2 = -\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

In polar form $z = re^{i\theta}$, the corresponding matrix is $Z = r \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} r & 0 \\ 0 & r \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

Next we recall some definitions that we need from Topology and Analysis

We will denote the open disc of radius r centered at z by $D_r(z)$ or $D(z, r)$

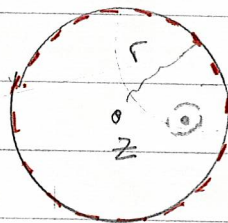
$$D_r(z) := \{w \in \mathbb{C} \mid |w - z| < r\}$$

$\overline{D}_r(z) := \{w \in \mathbb{C} \mid |w - z| \leq r\}$ is the closed disc.

The boundary of $D_r(z)$ is the circle!

$$C_r(z) = \overline{D}_r(z) \setminus D_r(z)$$

$$= \{w \in \mathbb{C} \mid |z - w| = r\}$$



• A subset $U \subset \mathbb{C}$ is open if $\forall z \in U, \exists r > 0$ such that $D_r(z) \subset U$

e.g. $\emptyset, \mathbb{C}, D_r(z), \mathbb{H} = \{z \in \mathbb{C} \mid \text{Im } z > 0\}$

• A subset $U \subset \mathbb{C}$ is called closed if $\mathbb{C} \setminus U$ is open.

U is closed $(\Leftrightarrow) \forall$ sequence $(z_n) \in U$, if $z_n \rightarrow z$ then $z \in U$

e.g. $\emptyset, \mathbb{C}, \overline{D}_r(z), C_r(z), \mathbb{R}$

• A subset $K \subset \mathbb{C}$ is called compact if it is closed and bounded (i.e. $\exists M$ s.t. $|z| < M \forall z \in K$).

(ii) • $K \subset \mathbb{C}$ is compact \Leftrightarrow every sequence $\{(z_n)\} \subset K$ has a subsequence that converges to a point in K

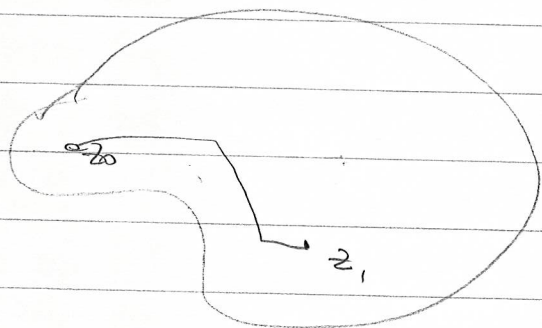
e.g. \emptyset , $\overline{D}_r(z)$, $C_r(z)$, $[a, b] \times [c, d]$

An subset A of \mathbb{C} is called disconnected if \exists open sets U and V such that

(i) $U \cap V = \emptyset$ (ii) $A \cap U \neq \emptyset$, $A \cap V \neq \emptyset$ and
(iii) $A \subset U \cup V$.

A subset A is called connected if it is not disconnected.
A connected open set $\emptyset \neq U \subset \mathbb{C}$ is called a region or a domain.

• Any pair of distinct points z_0, z_1 in an open connected set $A \subset \mathbb{C}$ can be connected by a polygonal path lying in A .



e.g. \emptyset , \mathbb{C} , $D_r(z)$, $\overline{D}_r(z)$, $C_r(z)$, \mathbb{R} are connected

\mathbb{Z} , \mathbb{D} , $\mathbb{R} \cup D_1(2i)$ are disconnected.

Rmk In general metric spaces path connected \Rightarrow connected
but connected $\not\Rightarrow$ path connected.

We recall

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① A sequence (z_n) with $z_n = x_n + iy_n$ converges to $z = x + iy$ if one of the following equivalent conditions hold

(i) $x_n \rightarrow x$ and $y_n \rightarrow y$ in \mathbb{R}

(ii) $|z_n - z| \rightarrow 0$ in \mathbb{R}

(iii) $\forall \epsilon > 0, \exists N, \forall m, n \geq N, |z_m - z_n| < \epsilon$

② Let $U \subset \mathbb{C}$ be an open subset

$f: U \rightarrow \mathbb{C}$ any function.

For $z_0 \in U$ and $w_0 \in \mathbb{C}$ we have

$$\lim_{\substack{z \rightarrow z_0 \\ z \in U}} f(z) = w_0 \text{ if one of the}$$

following equivalent conditions hold

(i) $\forall \epsilon > 0, \exists \delta > 0, \forall z \in U$ with $|z - z_0| < \delta$, we have $|f(z) - w_0| < \epsilon$

(ii) If $(z_n) \subset U$ is a sequence with $\lim z_n = z_0$, then $f(z_n)$ converges to w_0 .

③ $f: U \rightarrow \mathbb{C}$ is continuous on U

iff $\forall z_0 \in U, \lim_{z \rightarrow z_0} f(z) = f(z_0)$

iff $\forall (z_n) \subset U$ with $\lim z_n = z_0$, $\lim f(z_n) = f(\lim z_n) = f(z_0)$

§2 Holomorphic Functions

§2.1 Definitions, basic properties

This is a central notion for the rest of the class.

Let $\Omega \subset \mathbb{C}$ an open set

$f: \Omega \rightarrow \mathbb{C}$ a complex valued function on Ω .

Defn: f is called holomorphic at $z_0 \in \Omega$

if

$$\lim_{\substack{z \rightarrow z_0 \\ z \neq z_0}} \frac{f(z) - f(z_0)}{z - z_0} = \lim_{\substack{h \rightarrow 0 \\ h \neq 0}} \frac{f(z_0 + h) - f(z_0)}{h} \text{ exists}$$

Here $h \in \mathbb{C}$, $z_0 + h \in \Omega$, (so that the quotient is well defined)

If the limit exists, we denote it with $f'(z_0)$.

It is called the derivative of f at z_0 .

f is called holomorphic on Ω if it is holomorphic $\forall z_0 \in \Omega$.

If f is holomorphic on all of \mathbb{C} , then it is called entire.

Remark Regular or complex differentiable are other words used for holomorphic.

Example 2.1 Let $f: \mathbb{C} \rightarrow \mathbb{C}$, $f(z) = z$

Then f is entire. Since

$$\lim_{h \rightarrow 0} \frac{f(z_0+h) - f(z_0)}{h} = \lim_{h \rightarrow 0} \frac{(z_0+h) - z_0}{h} = \lim_{h \rightarrow 0} \frac{h}{h} = 1$$

Hence $f'(z) = 1 \quad \forall z \in \mathbb{C}$.

As in real variables, we have

Prop 2.2. ① Let $\mathcal{H}(\Omega) = \{ f: \Omega \rightarrow \mathbb{C} \mid f \text{ is hol. on } \Omega \}$

then $\mathcal{H}(\Omega)$ is a \mathbb{C} -vector space

More precisely

if $f, g \in \mathcal{H}(\Omega)$ then $\alpha f + \beta g \in \mathcal{H}(\Omega)$
for every $\alpha, \beta \in \mathbb{C}$.

And

$$(\alpha f + \beta g)' = \alpha f' + \beta g'$$

($0: \Omega \rightarrow \mathbb{C}$, $0(z) = 0$ is the 0 element)

② $f, g \in \mathcal{H}(\Omega) \Rightarrow fg \in \mathcal{H}(\Omega)$

$$\text{and } (fg)' = f'g + fg'$$

③ If $g(z_0) \neq 0$ then f/g is hol. at z_0 and

$$\left(\frac{f}{g} \right)' = \frac{f'g - fg'}{g^2}$$

If $g(z) \in \mathcal{H}(\Omega)$ and $g(z) \neq 0 \quad \forall z \in \Omega$
then $f/g \in \mathcal{H}(\Omega)$.