

## Solution 5

### 1. Elliptic Points

A point  $p \in M \subset \mathbb{R}^{m+1}$  on a hypersurface is called *elliptic* if the second fundamental form is (positive or negative) definite. Show that if  $M$  is compact then it has elliptic points.

#### Solution:

Since  $M$  is compact, it is closed and bounded. Hence there exists a radius  $R > 0$  such that  $M$  is contained in  $\bar{B}_R(0)$  and the boundary  $S := S_R^m(0) = \partial \bar{B}_R(0)$  touches  $M$  in (at least) one point  $p \in M$ .

As  $S$  touches  $M$  in  $p$ , it holds that  $TS_p = TM_p$ . In a neighborhood of  $p$  one can write  $M$  as a graph over  $TM_p$ : let  $f$  be such a local parametrization, so (upon a translation and an orthogonal transformation if necessary) we have

$$f(x^1, \dots, x^m) = (x^1, \dots, x^m, b(x^1, \dots, x^m))$$

with  $b(0, \dots, 0) = 0$  and  $\nabla b(0, \dots, 0) = 0$ .

As seen in class the matrix of the second fundamental form of  $f$  is given by

$$(h_{ij}) = \frac{1}{\sqrt{1 + |\nabla b|^2}} \text{Hess}(b),$$

where  $\text{Hess}(b) := (b_{ij})$  is the Hessian matrix of  $b$ . In particular it holds that  $(h_{ij}(0)) = \text{Hess}_0(b) = (b_{ij}(0))$ .

The sphere  $S$  can also be locally parametrized around  $p$  by

$$g(x^1, \dots, x^m) := (x^1, \dots, x^m, s(x^1, \dots, x^m))$$

with  $s(x) = R - \sqrt{R^2 - |x|^2}$ . Notice that  $s(0) = 0$ ,  $\nabla s = 0$  and  $\text{Hess}_0(s) = (s_{ij}(0)) = \frac{1}{R} \mathbb{1}$ .

Moreover, since  $M$  is contained the closed ball bounded by  $S$ , we have that  $b(x) \geq s(x)$ . Therefore a Taylor-expansion around 0 show that

$$b(x) = \frac{1}{2} x^T \text{Hess}_0(b) x + \mathcal{O}(|x|^3) \geq s(x) = \frac{1}{2} x^T \text{Hess}_0(s) x + \mathcal{O}(|x|^3) = \frac{1}{2R} |x|^2 + \mathcal{O}(|x|^3),$$

from which we deduce that  $y^T \text{Hess}_0(b) y \geq \frac{1}{R} |y|^2$  for any  $y \in \mathbb{R}^m$ , which shows that  $(h_{ij}(0)) = \text{Hess}_0(b)$  is positive definite and  $p$  is an elliptic point.

### 2. Mean Curvature

Let  $M \subset \mathbb{R}^3$  be a surface and  $p \in M$  a point. Fix  $0 \neq v_0 \in TM_p$ . Let  $H(p)$  be the mean curvature in  $p$  and denote by  $\kappa_p(\theta) := h_p(v, v)$  the normal curvature in direction  $v$ , where  $v \in TM_p$ ,  $|v| = 1$ , forms an angle  $\theta$  with  $v_0$ .

Prove that

$$H(p) = \frac{1}{\pi} \int_0^\pi \kappa_p(\theta) d\theta.$$

#### Solution:

Let  $(e_1, e_2)$  be an orthonormal basis of  $TM_p$  consisting of principal curvature directions, i.e.  $L_p e_i = \kappa_i e_i$ , for  $i = 1, 2$ .

If  $v_0 = \lambda(\cos \theta_0 \cdot e_1 + \sin \theta_0 \cdot e_2)$  for some  $\lambda > 0$ , then the vector  $v$  at an angle  $\theta$  with  $v_0$  is given by

$$v(\theta) = \cos(\theta_0 + \theta) \cdot e_1 + \sin(\theta_0 + \theta) \cdot e_2.$$

Then we can compute the normal curvature as follows:

$$\begin{aligned} \kappa_p(\theta) &= h_p(v(\theta), v(\theta)) = g_p(v(\theta), L_p(v(\theta))) \\ &= \langle \cos(\theta_0 + \theta) \cdot e_1 + \sin(\theta_0 + \theta) \cdot e_2, \kappa_1 \cos(\theta_0 + \theta) \cdot e_1 + \kappa_2 \sin(\theta_0 + \theta) \cdot e_2 \rangle \\ &= \kappa_1 \cos^2(\theta_0 + \theta) + \kappa_2 \sin^2(\theta_0 + \theta) \end{aligned}$$

from which we obtain

$$\begin{aligned} \int_0^\pi k_p(\theta) d\theta &= \kappa_1 \cdot \int_0^\pi \cos^2(\theta_0 + \theta) d\theta + \kappa_2 \cdot \int_0^\pi \sin^2(\theta_0 + \theta) d\theta \\ &= \kappa_1 \cdot \frac{\pi}{2} + \kappa_2 \cdot \frac{\pi}{2} = \frac{1}{2} (\kappa_1 + \kappa_2) \cdot \pi = H(p) \cdot \pi, \end{aligned}$$

so  $H(p) = \frac{1}{\pi} \int_0^\pi k_p(\theta) d\theta$ .

### 3. Local Isometries

Let  $f, \tilde{f}: \mathbb{R}_{\geq 0} \times \mathbb{R} \rightarrow \mathbb{R}^3$  be two immersions, given by

$$\begin{aligned} f(x, y) &:= (x \sin y, x \cos y, \log x), \\ \tilde{f}(x, y) &:= (x \sin y, x \cos y, y). \end{aligned}$$

- Show that  $f$  and  $\tilde{f}$  have the same Gauss curvature (as functions of  $(x, y)$ ).
- Are  $f$  and  $\tilde{f}$  (locally) isometric?

Hint: Consider the level sets of the Gauss curvature and the curves orthogonal to these.

### Solution:

a) We begin by computing the partial derivatives of  $f$  and the Gauss map:

$$\begin{aligned} f_x(x, y) &= (\sin y, \cos y, \frac{1}{x}), & f_y(x, y) &= (x \cos y, -x \sin y, 0), \\ f_{xx}(x, y) &= (0, 0, -\frac{1}{x^2}), & f_{yy}(x, y) &= (-x \sin y, -x \cos y, 0), \\ f_{xy}(x, y) &= f_{yx}(x, y) = (\cos y, -\sin y, 0), \\ \nu &= \frac{f_x \times f_y}{|f_x \times f_y|} = \frac{1}{\sqrt{1+x^2}} (\sin y, \cos y, -x). \end{aligned}$$

Thus

$$(g_{ij}) = (\langle f_i, f_j \rangle) = \begin{pmatrix} 1 + \frac{1}{x^2} & 0 \\ 0 & x^2 \end{pmatrix},$$

$$(h_{ij}) = (\langle f_{ij}, \nu \rangle) = \frac{1}{\sqrt{1+x^2}} \begin{pmatrix} \frac{1}{x} & 0 \\ 0 & -x \end{pmatrix}$$

and therefore

$$K(x, y) = \frac{\det(h_{ij})}{\det(g_{ij})} = \frac{-\frac{1}{1+x^2}}{1+x^2} = -\frac{1}{(1+x^2)^2}.$$

Analogously for  $\tilde{f}$  we have

$$\begin{aligned} \tilde{f}_x(x, y) &= (\sin y, \cos y, 0), & \tilde{f}_y(x, y) &= (x \cos y, -x \sin y, 1), \\ \tilde{f}_{xx}(x, y) &= (0, 0, 0), & \tilde{f}_{yy}(x, y) &= (-x \sin y, -x \cos y, 0), \\ \tilde{f}_{xy}(x, y) &= \tilde{f}_{yx}(x, y) = (\cos y, -\sin y, 0), \\ \tilde{\nu} &= \frac{\tilde{f}_x \times \tilde{f}_y}{|\tilde{f}_x \times \tilde{f}_y|} = \frac{1}{\sqrt{1+x^2}} (\cos y, -\sin y, -x), \end{aligned}$$

and

$$(\tilde{g}_{ij}) = (\langle \tilde{f}_i, \tilde{f}_j \rangle) = \begin{pmatrix} 1 & 0 \\ 0 & 1+x^2 \end{pmatrix},$$

$$(\tilde{h}_{ij}) = (\langle \tilde{f}_{ij}, \tilde{\nu} \rangle) = \frac{1}{\sqrt{1+x^2}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

from which

$$\tilde{K}(x, y) = \frac{\det(\tilde{h}_{ij})}{\det(\tilde{g}_{ij})} = \frac{-\frac{1}{1+x^2}}{1+x^2} = -\frac{1}{(1+x^2)^2},$$

so  $K(x, y) = \tilde{K}(x, y)$ .

b) We claim that  $f$  and  $\tilde{f}$  are not locally isometric. Let  $(x_0, y_0) \in \mathbb{R}_{\geq 0} \times \mathbb{R}$ . Suppose there exist a neighborhood  $U \subset \mathbb{R}_{\geq 0} \times \mathbb{R}$  of  $(x_0, y_0)$  and an isometry  $\varphi: (U, g) \rightarrow (\varphi(U), \tilde{g})$ . We write  $\varphi(x, y) = (\tilde{x}(x, y), \tilde{y}(x, y))$ . As the Gauss curvature is intrinsic we have  $K(x, y) = \tilde{K}(\varphi(x, y)) = \tilde{K}(\tilde{x}, \tilde{y})$ , that is

$$-\frac{1}{(1+x^2)^2} = -\frac{1}{(1+\tilde{x}^2)^2},$$

and hence  $\tilde{x}(x, y) = x$ , which implies that  $\varphi(x, y) = (x, \tilde{y}(x, y))$ .

Notice that the Gauss curvature is constant on curves with constant  $x$ -coordinate. Now consider a curve  $\gamma(t) = (u(t), y_0)$  with  $u(0) = x_0$ , parametrized by arc length (with respect to  $g$ ). The curve  $\gamma$  runs perpendicularly to curves with constant Gauss curvature (with respect to  $g$ ). Its image  $\tilde{\gamma} := \varphi \circ \gamma$  must also be parametrized by arc length and run perpendicularly to curves with constant Gauss curvature (with respect to  $\tilde{g}$ ). Hence  $\tilde{\gamma}(t) = (u(t), \tilde{y}_0)$ , where  $\tilde{y}_0 := \tilde{y}(x_0, y_0)$ , and  $|\dot{\tilde{\gamma}}(t)|_{\tilde{g}} = |\dot{u}(t)| = 1$ , so  $u(t) = x_0 \pm t$ . Therefore we obtain

$$|\dot{\gamma}(t)|_g = \sqrt{1 + \frac{1}{u^2(t)}} \neq 1,$$

a contradiction to the fact that  $\gamma$  is parametrized by arc length with respect to  $g$ .

*Alternative solution:*

Now notice that since  $\varphi$  is an isometry it holds that the matrix of the first fundamental form of  $\tilde{f}$  in  $\varphi(x, y) = (x, \tilde{y})$  with respect to the basis  $(\tilde{e}_1, \tilde{e}_2) := (d\varphi_{(x,y)}(e_1), d\varphi_{(x,y)}(e_2))$  of  $T\tilde{U}_{x,\tilde{y}}$  ( $\tilde{U} := \varphi(U)$ ) coincides with  $(g_{ij}(x, y))$  and is therefore given by

$$\left(\tilde{g}_{ij}(x, \tilde{y})\right)_{(\tilde{e}_1, \tilde{e}_2)} = \begin{pmatrix} 1 + \frac{1}{x^2} & 0 \\ 0 & x^2 \end{pmatrix}.$$

On the other hand the matrix of the first fundamental form of  $f$  with respect to the standard basis is given by  $(\tilde{g}_{ij}(x, \tilde{y}))_{(e_1, e_2)} = (\tilde{g}_{ij}(x, \tilde{y}))$  and was computed in a).

The matrix of change of basis from  $(e_1, e_2)$  to  $(\tilde{e}_1, \tilde{e}_2)$  is given exactly by

$$M := d\varphi_{(x,y)} = \begin{pmatrix} 1 & 0 \\ a & b \end{pmatrix}$$

for some  $a, b$ . Thus it must hold that

$$\left(\tilde{g}_{ij}(x, \tilde{y})\right)_{(\tilde{e}_1, \tilde{e}_2)} = M^T \cdot \left(\tilde{g}_{ij}(x, \tilde{y})\right)_{(e_1, e_2)} \cdot M,$$

which is equivalent to

$$\begin{cases} 1 + a^2(1 + x^2) = 1 + \frac{1}{x^2}, \\ ab(1 + x^2) = 0, \\ b^2(1 + x^2) = x^2. \end{cases}$$

But the above system has no solutions for  $x \in \mathbb{R}_{\geq 0}$ . Contradiction arises.