

CHAPTER 10:

CONDITIONAL EXPECTATION II:

ABSTRACT DEFINITION AND EXAMPLES.

Goals: Formal definition of conditional expectation

- particular cases helping to develop an intuition.

Setup: (Ω, \mathcal{F}, P) probability space, $L^1 = \{X: \Omega \rightarrow \mathbb{R} \mid E(|X|) < \infty\}$.

$\mathcal{G} \subset \mathcal{F}$ sub σ -algebra.

 \mathcal{G} represents some information about an element $\omega \in \Omega$.

- $\mathcal{G} = \sigma(\{\Omega_1, \dots, \Omega_n\})$ where $\Omega = \Omega_1 \cup \dots \cup \Omega_n$ partition.

\hookrightarrow information = the element Ω_i where ω is.

- $\mathcal{G} = \sigma(Y)$ where Y n.v.

\hookrightarrow information = value of $Y(\omega)$ is given.

- $\mathcal{G} = \sigma(Y_1, \dots, Y_k)$ where Y_i are n.v.s.

\hookrightarrow information = values of $Y_i(\omega)$ for all i .

- $\mathcal{G} = \{B \in \mathcal{F}\}$ general σ -algebra.

\hookrightarrow information = we know $1_B(\omega)$ for every $B \in \mathcal{G}$.

If X r.v., $X \in L^1$. ($= \{Z: \Omega \rightarrow \mathbb{R} \text{ s.t. } \int |Z| dP < \infty\}$)

• "Best guess" about X without any information: $E(X)$.

• Best guess of X knowing some information \mathcal{G} ?

1 THEORETICAL BACKGROUND.

Thm: Let $X \in L^1$. Let $\mathcal{G} \subset \mathcal{F}$ be a σ -algebra.

There exists a random variable $X' \in L^1$ s.t.

(i) X' is \mathcal{G} -measurable.

(ii) $\forall A \in \mathcal{G} \quad E(X 1_A) = E(X' 1_A)$

Furthermore, if X'' is another r.v. satisfying (i) and (ii), then $X' = X''$ a.s.

Rk: (i) + (ii) $\Rightarrow X' \in L^1$

(choose $A = \{X' \geq 0\}$ and $A = \{X' \leq 0\}$ in (ii))

Proof. [Existence].

Case 1 $X \geq 0$.

Let Q be the measure on (Ω, \mathcal{G}) defined

by

$$\forall A \in \mathcal{G} \quad Q(A) = E(X 1_A)$$

Since $X \in L^1$ $Q(\Omega) = E(X) < \infty$, Q is a finite meas.

Let $\tilde{P} = P|_{\mathcal{G}}$. For every $A \in \mathcal{G}$

$$\tilde{P}(A) = 0 \Rightarrow P(A) = 0 \Rightarrow E(X 1_A) = 0 \Rightarrow Q(A) = 0.$$

By Radon-Nikodym Theorem (applied to $(E, \mathcal{E}) = (\Omega, \mathcal{G})$, $\mu = \tilde{P}$, $\nu = Q$), there exists $X' \geq 0, \mathcal{G}$ -measurable.

$$\text{s.t. } \forall A \in \mathcal{G} \quad Q(A) = \int_A X' d\tilde{P} \quad \left(= \int_A X' dP \right).$$

$$\text{i.e. } \forall A \in \mathcal{G} \quad E(X 1_A) = E(X' 1_A).$$

Taking $A = \Omega$ yields $E(X') = E(X) < \infty$.

Case 2: $X \in L^1$ general.

$$X = X_+ - X_- \quad \text{where } X_+ \geq 0 \text{ and } X_- \geq 0$$

Take $X' = X'_+ - X'_-$ where X'_+, X'_- are \mathcal{G} -meas.

and satisfy $\forall A \in \mathcal{G}$

$$E(X'_\pm 1_A) = E(X_\pm 1_A)$$

[Uniqueness].

Let X', X'' satisfying (i), (ii).

because $\{X' > X''\} = \bigcup_{a \in \mathbb{Q}} \{X' > a\} \cap \{a > X''\}$

Let $A = \{X' > X''\} \stackrel{(i)}{\in} \mathcal{G}$. By (ii), we have

$$E(X' 1_A) = E(X'' 1_A),$$

ie

$$E(\underbrace{(X' - X'') 1_{(X' - X'') > 0}}_{\geq 0}) = 0.$$

This implies $(X' - X'') 1_{X' - X'' > 0} = 0$ a.s.

ie $X' - X'' \leq 0$ a.s.

Equivalently, considering $A = \{X' < X''\}$, we

show that $X' - X'' \geq 0$ a.s. ■

Notation: For $A \in \mathcal{F}$, we write

$$P(A | \mathcal{G}) = E(1_A | \mathcal{G}).$$

"conditional probability of A"

• For Y a r.v. with values in a measured space (E, \mathcal{E}) , we write

$$E(X | Y) := E(X | \sigma(Y)).$$

Proposition: (Equivalent formulations of P2).

Let $X \in L'$, $\mathcal{G} \subset \mathcal{F}$ σ -algebra. Let $X' \in L'$, \mathcal{G} measurable.

Let $\mathcal{E} \subset \mathcal{F}$ be a π -system such that $\sigma(\mathcal{E}) = \mathcal{G}$.

The following are equivalent

$$[P2-0] \quad \forall A \in \mathcal{E} \quad E(X 1_A) = E(X' 1_A)$$

$$[P2-1] \quad \forall A \in \mathcal{G} \quad E(X 1_A) = E(X' 1_A)$$

$$[P2-2] \quad \forall Z \in \mathcal{G}\text{-meas. bounded} \quad E(XZ) = E(X'Z)$$

Proof: $0 \Rightarrow 1$ Dynkin Lemma.

$1 \Rightarrow 2$ Without loss of generality, we can assume

$Z \geq 0$ (otherwise consider $Z + c$, where c large est).

Let $Z_n \uparrow Z$ where Z_n simple.

By linearity (P2-1) implies that

$$E(X Z_n) = E(X' Z_n),$$

and the result follows from dominated convergence.

$z \rightarrow 0$ choose $z = 1_A$.

3 σ -ALGEBRA GENERATED BY A PARTITION

Assume $\Omega = \bigsqcup_{i \in I} \Omega_i$ (disjoint union) where I finite or countable.

$$\begin{aligned} \text{Let } \mathcal{G} &= \sigma(\{\Omega_i, i \in I\}) \\ &= \left\{ \left\{ \bigcup_{i \in J} \Omega_i \right\}, J \subset I \right\}. \end{aligned}$$

Prop. Let $X \in L'$. We have

$$E(X | \mathcal{G}) = \sum_{i \in I} E(X | \Omega_i) 1_{\Omega_i} \quad \text{a.s.}$$

(For almost all $\omega \in \Omega_i$, $E(X | \mathcal{G})(\omega) = E(X | \Omega_i)$.
 (By convention, we set $E(X | \Omega_i) 1_{\Omega_i} = 0$...))

Proof. Since $E(X | \mathcal{G})$ \mathcal{G} -measurable; we have

$$E(X | \mathcal{G}) = \sum_{i \in I} \lambda_i 1_{\Omega_i} \quad \text{a.s.} \quad \begin{array}{l} \text{(exercise)} \\ (\lambda_i \in \mathbb{R}) \end{array}$$

To identify λ_i , we use (P₂). For every $i \in I$

$$\begin{aligned} \lambda_i P(\Omega_i) &= E(E(X | \mathcal{G}) 1_{\Omega_i}) \\ &\stackrel{\text{(P}_2\text{)}}{=} E(X 1_{\Omega_i}) \end{aligned}$$

Example: $\Omega = [0, 1]$ $\mathcal{F} = \mathcal{B}([0, 1])$ $P = \text{Leb}_{[0, 1]}$

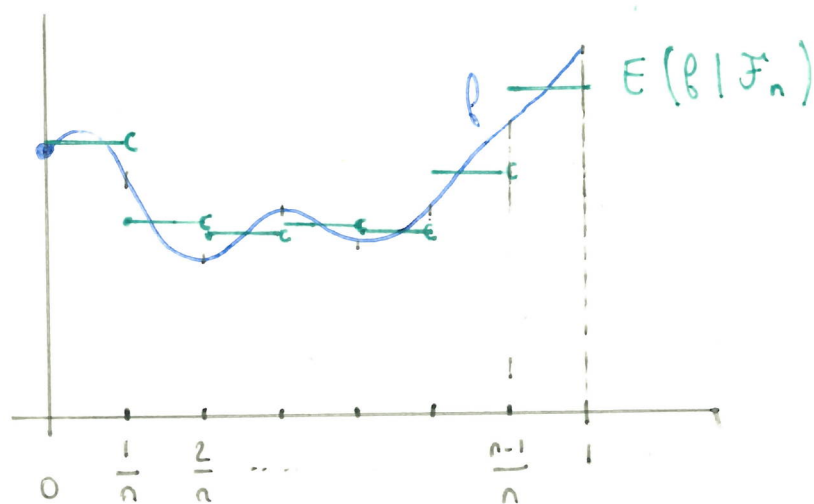
$f: [0, 1] \rightarrow \mathbb{R}$ continuous.

$$\Omega = \underbrace{[0, \frac{1}{n}[}_{I_1} \cup \underbrace{[\frac{1}{n}, \frac{2}{n}[}_{I_2} \cup \dots \cup \underbrace{[\frac{n-2}{n}, \frac{n-1}{n}[}_{I_{n-1}} \cup \underbrace{[\frac{n-1}{n}, 1]}_{I_n}$$

$$\mathcal{F}_n = \sigma(\{I_1, \dots, I_n\})$$

$$E(f | \mathcal{F}_n) = \sum_{i=1}^n \alpha_i \mathbb{1}_{I_i}$$

where $\alpha_i = E(f | I_i) = \frac{1}{h} \int_{\frac{i-1}{n}}^{\frac{i}{n}} f(x) dx$.



"On each interval I_i we replace f by its expectation on I_i "

4 DISCRETE R.V.'S

Prop. Let $X \in L^1$, Y n.v. in a measured space (E, \mathcal{E}) .

Assume that there exists $D \subset E$ finite or countable s.t. $Y \in D$ a.s. Then

$$E(X|Y) = \sum_{y \in D} E(X|Y=y) 1_{Y=y}.$$

(with the convention $E(X|Y=y) 1_{Y=y} = 0$ if $P(Y=y) = 0$)

Rk: We recover the formula in Chapter 9.

Proof: By applying the proposition of Section 3 to the partition

$$\Omega = \{Y \notin D\} \cup \bigcup_{y \in D} \{Y=y\},$$

we get

$$E(X|Y) = \sum_{y \in D} E(X|Y=y) 1_{Y=y}. \quad \blacksquare$$

5 CONDITIONAL DENSITIES

Def. (density). Let $f: \mathbb{R}^d \rightarrow [0, \infty]$. A random variable X in \mathbb{R}^d has density f if

$$\forall A \subset \mathbb{R}^d \text{ meas. } P(X \in A) = \int_A f(x) dx.$$

Rk. X has a density iff $\nu_x \ll \text{Leb}_{\mathbb{R}^d}$, and in this case its density is $f = \frac{d\text{Leb}}{d\nu_x}$.

(Radon-Nikodym derivative).

- If X has density f , we have for every $\Psi: \mathbb{R}^d \rightarrow \mathbb{R}$ meas. ≥ 0 or s.t. $E(|\Psi(X)|) < \infty$.

$$E(\Psi(X)) = \int_{\mathbb{R}^d} \Psi(x) f(x) dx.$$

- If a vector $(X, Y) \in \mathbb{R}^k \times \mathbb{R}^p$ has density f , then X has density f_x , given by

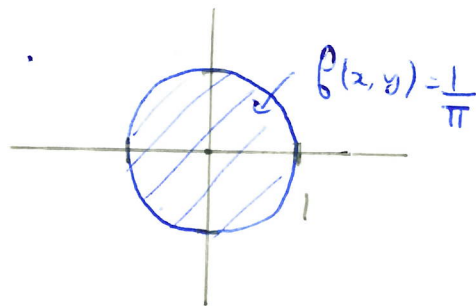
$$\forall x \in \mathbb{R}^k \quad f_x(x) = \int_{\mathbb{R}^p} f(x, y) dy$$

and Y has density f_y , given by

$$\forall y \in \mathbb{R}^p \quad f_y(y) = \int_{\mathbb{R}^k} f(x, y) dx.$$

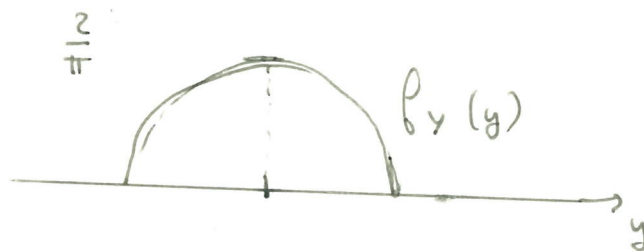
Example. Uniform point in a circle.

$$\text{Let } f(x, y) = \frac{1}{\pi} \mathbb{1}_{x^2 + y^2 \leq 1}$$



Let $(X, Y) \in \mathbb{R}^2$ with density f . Density of Y :

$$f_Y(y) = \frac{1}{\pi} \int_{-1}^1 \mathbb{1}_{x^2 + y^2 \leq 1} dx = \frac{2}{\pi} \sqrt{1 - y^2}$$



Prop. Let $k, l \geq 1$, X random variable in \mathbb{R}^k ,
 Y random variable in \mathbb{R}^l . Assume that (X, Y)
has a density $f: \mathbb{R}^k \times \mathbb{R}^l \rightarrow [0, \infty]$
Let $\Psi: \mathbb{R}^k \rightarrow \mathbb{R}$ s.t. $\Psi(X) \in L^1$. Then

$$E(\Psi(X) | Y) = \varphi(Y), \text{ where}$$

$$\varphi(y) = \int_{\mathbb{R}^k} \Psi(x) \cdot \frac{f(x, y)}{f_Y(y)} dy.$$

Convention: $\varphi(y) = 0$ if $f_Y(y) = 0$.

Rk: This is the continuous analog of: if X takes value in D and Y in D' (at most countable).

$$E(\Psi(X) | Y) = \varphi(Y) \text{ a.s.}$$

$$\text{where } \varphi(y) = \sum_x \Psi(x) \underbrace{P(X=x | Y=y)}_{= \frac{P(X=x, Y=y)}{P(Y=y)}}.$$

• $\frac{P(x, y)}{f_Y(y)}$ is the density of X "conditionally on $Y=y$ ",

sometimes denoted $f_{X|Y}(x|y)$.

Proof. $\varphi(Y)$ is Y -meas. and for every bounded meas. $g: \mathbb{R}^p \rightarrow \mathbb{R}$, we have

$$\begin{aligned} E(\varphi(Y) g(Y)) &= \int_{\mathbb{R}^p} \varphi(y) g(y) f_Y(y) dy \\ &\stackrel{\text{Fub.}}{=} \int_{\mathbb{R}^{k+p}} \Psi(x) \frac{P(x, y)}{f_Y(y)} g(y) f_Y(y) dx dy \\ &= E(\Psi(X) g(Y)) \quad \square \end{aligned}$$

GEOMETRIC INTERPRETATION OF $E(X)$ IN L^2

$$L^2 = \{X: \Omega \rightarrow \mathbb{R} \text{ measurable } E(X^2) < \infty\}$$

$$H = L^2 / \sim \quad (X \sim Y \text{ if } X=Y \text{ a.s.}).$$

If $X \in L^2$, write $\tilde{X} \in H$ for its equivalence class.

Given $\tilde{X}, \tilde{Y} \in H$, we can define

$$\langle \tilde{X}, \tilde{Y} \rangle = E(XY).$$

$(H, \langle \cdot, \cdot \rangle)$ Hilbert space (admitted).

Geometric interpretation of $E(X)$ and $\text{Var}(X)$.

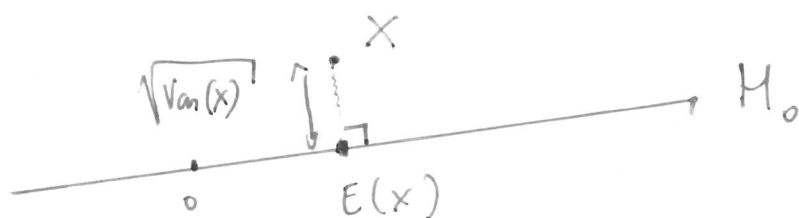
Let $H_0 = \{\tilde{\lambda}, \lambda \in \mathbb{R}\}$ constant r.v.s.

Let $X \in L^2$. For every $\lambda \in \mathbb{R}$, we have

$$E((X - E(X)) \cdot \lambda) = 0.$$

Hence $\forall \tilde{\lambda} \in H_0$

$$\langle \tilde{\lambda}, \tilde{X} - E(\tilde{X}) \rangle = 0$$



$E(X)$ is the orthogonal projection of X on the closed subspace H_0 . In particular

$$E((X-\lambda)^2) \text{ is minimized for } \lambda = E(X).$$

GEOMETRIC INTERPRETATION OF $E(X|\mathcal{G})$.

Let $\mathcal{G} \subset \mathcal{F}$ σ -algebra. Write

$$H_{\mathcal{G}} = \{X: \Omega \rightarrow \mathbb{R} \text{ } \mathcal{G}\text{-meas. } E(X^2) < \infty\} / \sim$$

One can check that $H_{\mathcal{G}}$ is a closed subspace of H .

Prop. Let $X \in L^2$. Among all functions $Z \in L^2$, \mathcal{G} -meas.,

$$E((X-Z)^2) \text{ is minimized for } Z = E(X|\mathcal{G}).$$

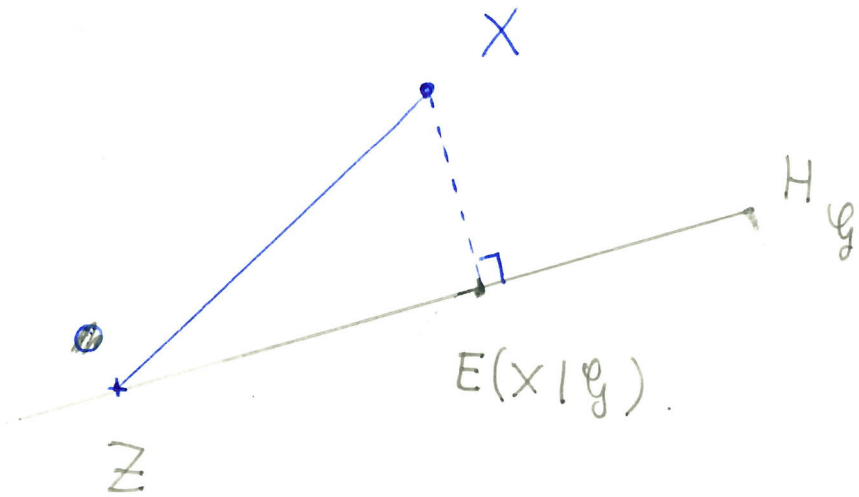
Proof. Let $\tilde{X}' \in H_{\mathcal{G}}$ be the orthogonal projection of \tilde{X} on $H_{\mathcal{G}}$. We have

$$\begin{cases} \tilde{X}' \in H_{\mathcal{G}} \text{ and} \\ \forall \tilde{Z} \in H_{\mathcal{G}} \quad \langle \tilde{X} - \tilde{X}', \tilde{Z} \rangle = 0 \end{cases}$$

This implies $\begin{cases} X' \text{ is } \mathcal{G}\text{-measurable} \\ \forall Z \text{ } \mathcal{G}\text{-measurable bounded } E(XZ) = E(X'Z). \end{cases}$

Hence $X' = E(X|\mathcal{G})$ a.s. ■

Rk: This gives a geometrical interpretation of $E(X|Y)$ when $X \in L^2$: it is the orthogonal projection of X on $H_{\mathcal{G}}$.



(P2) is the orthogonality condition $(X - E(X|Y)) \perp H_{\mathcal{G}}$.

7 NON NEGATIVE R.V.

Def. Let X be r.v. with values in $[0, \infty]$ a.s. Let $\mathcal{G} \subset \mathcal{F}$ be a σ -algebra. The conditional expectation $E(X|\mathcal{G})$ is the r.v. in $[0, \infty]$ satisfying

(P1) $E(X|\mathcal{G})$ is \mathcal{G} -measurable

(P2) For every $A \in \mathcal{G}$ $E(X 1_A) = E(E(X|\mathcal{G}) 1_A)$.

Rk: $E(X|\mathcal{G})$ is well def. up to a.s. equality:

[Existence] Let $X_n = X 1_{X \leq n}$ for $n \geq 1$, and define

$$X_n' = E(X_n | \mathcal{G}). \text{ We have}$$

$$0 \leq X_n' \leq X_{n+1}' \text{ a.s.}$$

(if $U \leq V$ $U, V \in L'$ then $E(U|\mathcal{G}) \leq E(V|\mathcal{G})$ a.s.:
consider $A = \{V > U\}$ and use $E(U 1_A) \leq E(V 1_A)$.)

Set $X' = \lim_{n \rightarrow \infty} X_n'$. X' satisfies P1 as

a a.s. lim of \mathcal{G} -measurable functions. Furthermore,

by monotone cv, for every $A \in \mathcal{G}$

$$E(X' 1_A) = \lim_{n \rightarrow \infty} E(X_n' 1_A) = \lim_{n \rightarrow \infty} E(X_n 1_A) = E(X 1_A)$$

[Uniqueness] Let X', X'' satisfying P_1 and P_2

Let $0 < a < b$ and $A = \{X' \leq a < b \leq X''\}$

$$b P(A) \leq E(1_A X'') = E(1_A X') \leq a P(A)$$

ie. $(b-a) P(A) \leq 0$, which gives $P(A) = 0$

By taking the union over $a, b \in \mathbb{Q}$, we get

$$P(X' < X'') = 0$$

Rk: (P_2) is equivalent to

$$\forall Z \geq 0 \text{ } \mathcal{G}\text{-measurable } E(ZX) = E(Z E(X|\mathcal{G}))$$

(exercise)