

Rigorous math course with physics motivations. Parts with physics non-examinable and will be clearly marked. \otimes Plan of course:

- Topic 0: Preliminaries (first 3 classes, 4th class overview)
- Topic 1: Nodal sets of Laplace eigenfns. (~2 classes)
- Topic 2: Geometric properties of rough fns. (some probability) (3 classes)
- Topic 3: Multifractality & Energy Conservation results. (4 classes)

Advanced topics: Anomalous dissipation, ~~Varying viscos~~ Turbulence in 2D, ...
3D energy

\otimes What is Turbulence? Simply random or universal & structured? \leftarrow Ref: Frisch Turbulence

0.1 Incompressible Fluids: Let us fix $(x,t) \in \mathbb{T}^3 \times \mathbb{R}$, $u: \mathbb{T}^3 \times \mathbb{R} \rightarrow \mathbb{R}^3$, $p: \mathbb{T}^3 \times \mathbb{R} \rightarrow \mathbb{R}$
 $v=0$ (Euler) (N-S) $\left\{ \begin{array}{l} \partial_t u + (u \cdot \nabla)u + \nabla p = \nu \Delta u, \quad \nu \geq 0 \\ \operatorname{div} u = 0 \end{array} \right.$ | Summation notation: $\nabla = \partial_i$
 $(u \cdot \nabla)u = u_i \partial_i u_j = \partial_i (u_i u_j) = \operatorname{div}(u \otimes u)$

\Rightarrow p can be recovered from u : $\operatorname{div} \operatorname{div}(u \otimes u) + \Delta p = 0$
 Momentum is conserved.
 Energy identity: $\partial_t \frac{\|u\|_2^2}{2} + (u \cdot \nabla) \frac{\|u\|_2^2}{2} + \operatorname{div}(pu) = \nu \Delta \frac{\|u\|_2^2}{2} - \nu |\nabla u|^2$
 (Let $u \in C^1_{t,x}$)
 $\Rightarrow \frac{d}{dt} \frac{\|u\|_2^2}{2} = -\nu \int_{\mathbb{T}^3} |\nabla u|^2 \Rightarrow \|u\|_2^2(T) = \|u\|_2^2(0) - \int_0^T \int_{\mathbb{T}^3} 2\nu |\nabla u|^2$

$\nu=0 \Rightarrow$ Energy is conserved.

Γ PHYSICS: Anomalous dissipation (0th Law of Turbulence)

We observe $\liminf_{\nu \rightarrow 0} \nu \int_0^T \int_{\mathbb{T}^3} |\nabla u|^2 \neq 0$. How do we describe the limiting soln. of the Euler eqns? By above it cannot be a C^1 soln.

\hookrightarrow

Weak derivatives & Weak Solns.

Defn.: We say $g \in L^1(\Omega)$ is the weak derivative of $f \in L^1(\Omega)$ if $\forall \varphi \in C_c^\infty(\Omega)$
 $\int f \partial_i \varphi = -\int g \varphi$.

Defn.: $u \in L^2(\mathbb{T}^3 \times \mathbb{R})$ is a weak soln. of Euler/N-S if $\forall \varphi \in C_c^\infty(\mathbb{T}^3 \times \mathbb{R})$ we have
 $-\iint u \partial_t \varphi + u \otimes u \cdot \nabla \varphi + p \nabla \varphi = \nu \iint u \Delta \varphi, \quad \iint u \cdot \nabla \varphi = 0$

Eg: (Shear flows): $u(t, x_1, x_2, x_3) = \tilde{u}(x_1, x_2) \vec{e}_3$ for any $\tilde{u} \in L^2(\mathbb{T}^2)$ is a weak soln. of Euler.
 $p \equiv 0$

The weak solns. as defined need not satisfy the energy identity!

Thm (Paradox of Scheffer): $\exists (u,p)$ weak soln of (Euler) which is compactly supported in spacetime.

Γ No anomalous dissipation in 2D: Taking curl of N-S gives $\left\{ \begin{array}{l} \partial_t \omega + u \cdot \nabla \omega = \nu \Delta \omega \\ u = \mathcal{K} * \omega \end{array} \right.$

~~incompressible~~ $\Rightarrow \frac{d}{dt} \|\omega\|_{L^2}^2 = -\nu \int |\nabla \omega|^2 \leq 0$
 $\Rightarrow \|\omega\|_{L^2} \sim \|\omega\|_{H^1} \leq C$ indep of $\nu \Rightarrow \nu \|\nabla \omega\|_{L^2}^2 \rightarrow 0$.

∇ Doesn't work in 3D due to "vortex stretching" $\omega \cdot \nabla u$

$\Omega = \mathbb{R}^n$ or \mathbb{T}^n .

0.2. Function Spaces: How do we measure regularity of fns. with less than 1 derivative.

Defn.: (Hölder spaces) For $0 < \alpha < 1$, we define $C^\alpha(\Omega)$ to be the set of all fns $f: \Omega \rightarrow \mathbb{R}$ st.

$$[f]_\alpha := \sup_{x \neq y \in \Omega} \frac{|f(x) - f(y)|}{|x - y|^\alpha} < +\infty. \text{ With the norm } \|f\|_\alpha := \|f\|_{C^0} + [f]_\alpha \text{ it}$$

is a Banach space.

Eg: $C^\alpha(\Omega)$ is NOT the closure of $C^\infty(\Omega)$ under the $\|\cdot\|_\alpha$ norm.

Defn.: (Sobolev spaces) For $p=2$, we define $H^s = W^{s,2}$ to be fns. $f: \Omega \rightarrow \mathbb{R}$ st.

$$\|f\|_{H^s}^2 := \int (1 + |\xi|^2)^s |\hat{f}(\xi)|^2 d\xi < +\infty. \text{ This is a Hilbert space: the inner product } \langle f, g \rangle_{H^s} = \int \hat{f} \bar{\hat{g}} d\xi + \int |\xi|^{2s} \hat{f}(\xi) \bar{\hat{g}}(-\xi) d\xi \text{ gives an equivalent norm.}$$

$p \neq 2$ is more complicated, can be done by:

- Littlewood-Paley Theory (c.f. Alhinaré - Gerard)
- Gagliardo Seminorm
- Wavelets

Defn: For $0 < \alpha < 1, p \geq 1$, $\|f\|_{\alpha,p} := \left(\iint \frac{|f(x) - f(y)|^p}{|x - y|^{d\alpha p}} dx dy \right)^{1/p}$

$W^{\alpha,p} = \{f \in L^1 : \|f\|_{\alpha,p} < +\infty\}$.

PHYSICS: Experiments/numerics measure $\langle |u(x+\ell) - u(x)|^p \rangle \stackrel{\text{ergodic hypothesis}}{=} \|u(x+\ell) - u(x)\|_p^p$
 "ensemble average"

Kolmogorov K41 theory:

$\langle |\delta u(\ell)|^p \rangle \sim C |\ell|^{3p/5}$, $z_p = \frac{p}{5}$. Moreover, for $p=3$,

$\langle |\delta u(\ell)|^3 \rangle \sim c_\varepsilon |\ell|$

Rank: A rigorous version of such laws have been established. We'll look at this towards the end of the course.

The above motivates us to consider spaces so that $\|\delta u(\ell)\|_p \leq C |\ell|^{\alpha_p}$. We get

Defn.: (Besov spaces) $[f]_{B_{p,q}^\alpha} := \left(\int_0^\infty \left(\sup_{|x| \leq h} \|f(x) - f(\frac{x+\ell}{2})\|_p \right)^q \frac{dh}{h} \right)^{1/q}$.

Eg.: $B_{\infty,\infty}^\alpha = C^\alpha$, $B_{p,p}^\alpha = W^{\alpha,p}$.

Thm (Sobolev/Besov embedding): Let $0 \leq \alpha < \beta < 1$, $1 \leq p < q \leq \infty$, If: $\frac{1}{p} - \frac{\beta}{d} = \frac{1}{q} - \frac{\alpha}{d}$

$\Rightarrow B_{p,r}^\beta \subseteq B_{q,r}^\alpha$

Rank: K41 theory suggests turbulent solns $u \in B_{3,\infty}^{1/3}$.

Rank: We only care about the local picture, so we assume Ω is opt or replace B_α with $B_{loc,\beta}$

Thm (Interpolation): $1 \leq p_0, q_0, p_1, q_1 \leq \infty$, $0 \leq \alpha, \beta < 1$, $f \in B_{p_0,q_0}^\alpha \cap B_{p_1,q_1}^\beta$.

\Rightarrow for $0 < \theta < 1$, $\frac{1}{p} = \frac{\theta}{p_0} + \frac{1-\theta}{p_1}$, $\frac{1}{q} = \frac{\theta}{q_0} + \frac{1-\theta}{q_1}$, $\gamma = \theta\alpha + (1-\theta)\beta$, $f \in B_{p,q}^\gamma$.

Defn. (Structure function exponents): Given a function $f: \Omega \rightarrow \mathbb{R}$, we define its p -order structure fn. exponent $z_p(u) := p \cdot \sup \{ \beta : u \in W^{p,\beta} \}$.

Defn. (Besov domain): The Besov domain of a fn. $f = \{ (p,s) : f \in W^{s,p} \}$.

Interpolation \Rightarrow Besov domain (f) is convex

$(q,s) \in B(f) \Rightarrow (t, d(t-q)+s) \in B(f)$ $t \in (0,q)$

$(q,s) \in B(f) \Rightarrow (t,s) \in B(f)$ $t \in (q,1)$

$\partial B(f) \ni (q, s(q))$ $s(q)$ concave, increasing
 is given by $0 \leq s(q) \leq d$



Thm (Jaffard): Any convex fn s satisfying \otimes gives the Besov domain of a function f .